



# Style and Content, Texture Synthesis

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16-726, Spring 2023

# Collection Style Transfer



Photograph ©Alexei Efros



Monet



Van Gogh



Cezanne



Ukiyo-e

# Style and Content Separation

**A**

Classification

<b>A</b>	<b>B</b>	<b>C</b>	<b>D</b>	<b>E</b>
<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>
A	B	C	D	E
<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>
<b>A</b>	<b>B</b>	<b>C</b>	<b>D</b>	<b>E</b>
B	C	A	E	D

Domain Adaptation

**B**

Extrapolation

<b>A</b>	<b>B</b>	<b>C</b>	<b>D</b>	<b>E</b>
<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>
A	B	C	D	E
<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>
<b>A</b>	<b>B</b>	<b>C</b>	<b>D</b>	<b>E</b>
?	?	C	D	E

Paired Image-to-Image Translation

**C**

Translation

<b>A</b>	<b>B</b>	<b>C</b>	<b>D</b>	<b>E</b>	?	?	?
<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>			
A	B	C	D	E			
<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>			
<b>A</b>	<b>B</b>	<b>C</b>	<b>D</b>	<b>E</b>	?	?	?
?	—	—	—	?	F	G	H

Unpaired Image-to-Image Translation

Training
Generalization

Separating Style and Content  
[Tenenbaum and Freeman 1996]

$$y_k^{sc} = \sum_{i=1}^I \sum_{j=1}^J w_{ijk} a_i^s b_j^c.$$

# Style and Content

## Adversarial loss

$$\mathbb{E}_x \log(1 - D_Y(G(x))) + \mathbb{E}_y \log D_Y(y)$$



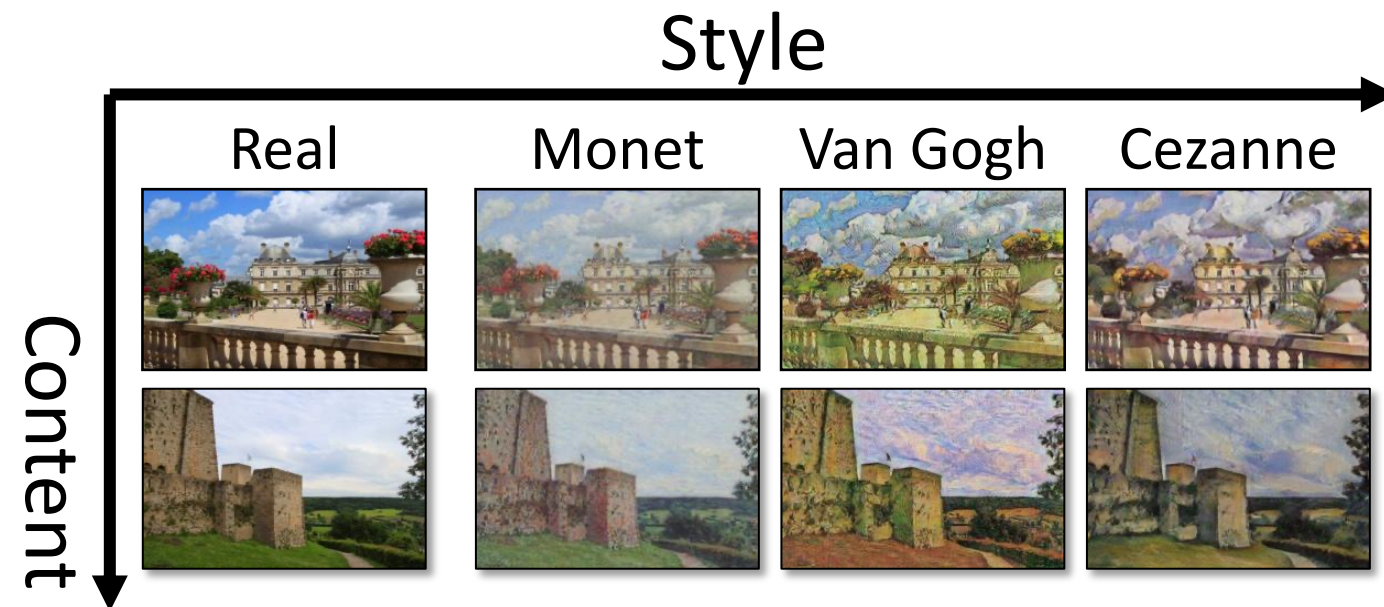
$p(x) \rightarrow p(y)$  change **style**

## Cycle-consistency loss

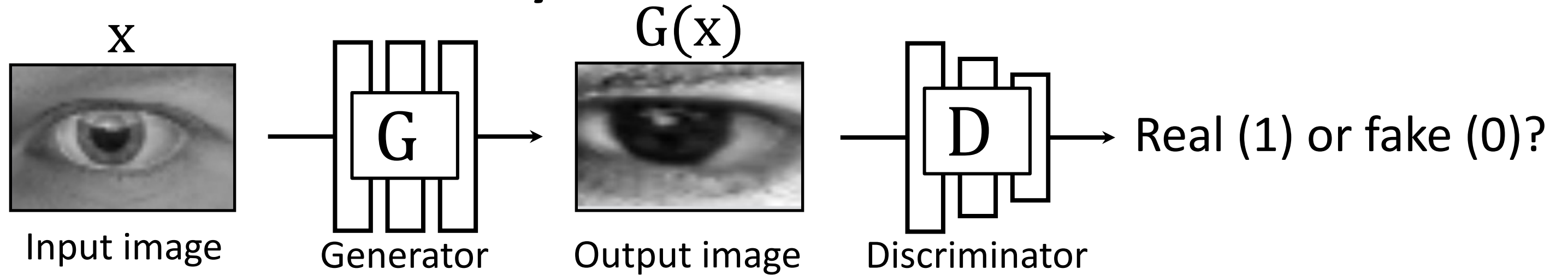
$$\mathbb{E}_x ||F(G(x)) - x||_1$$



Bidirectional: preserve **content**



# Style and Content

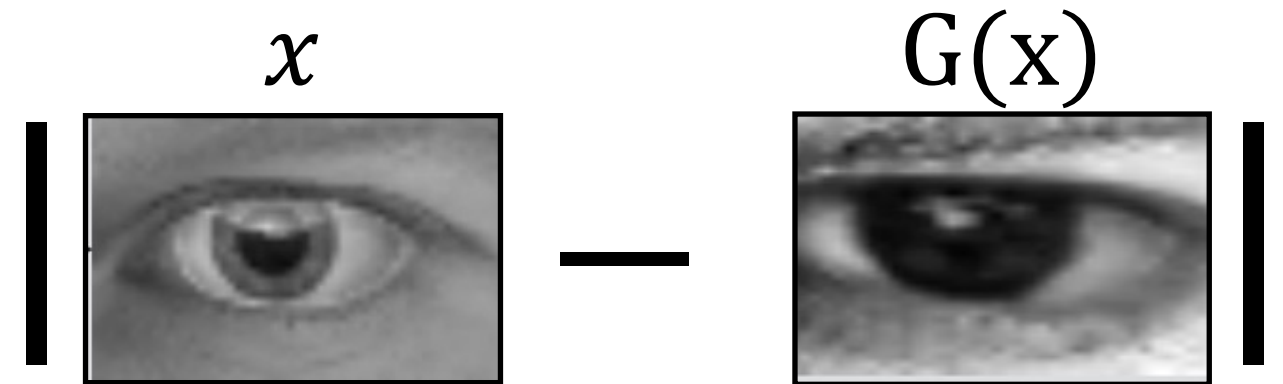


## Adversarial loss (change style)

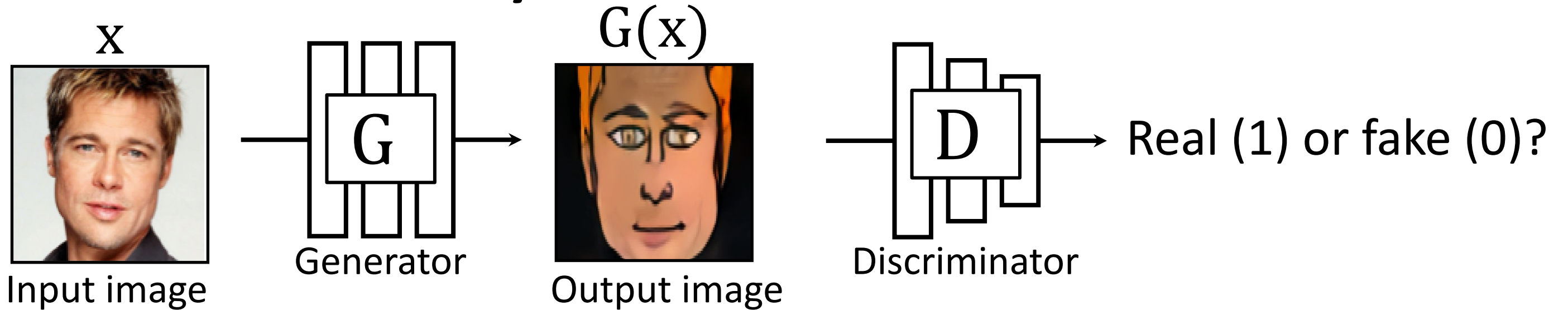
$$\mathbb{E}_x \log(1 - D_Y(G(x))) + \mathbb{E}_y \log D_Y(y)$$

## L1 loss (preserve content in pixel space)

$$\mathbb{E}_x ||G(x) - x||_1$$



# Style and Content

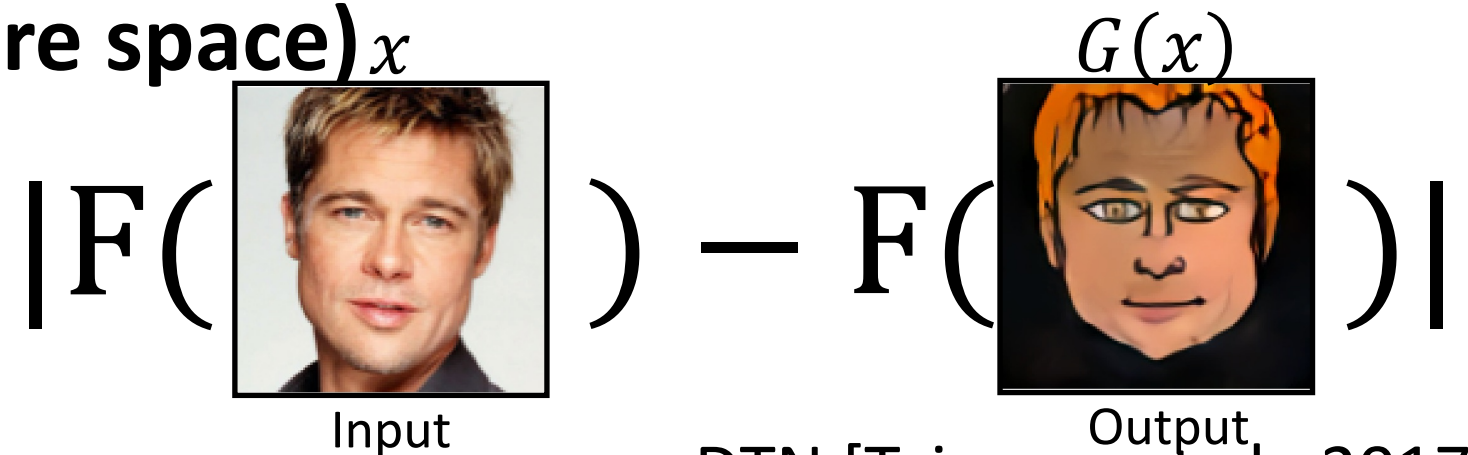


## Adversarial loss (change style)

$$\mathbb{E}_x \log(1 - D_Y(G(x))) + \mathbb{E}_y \log D_Y(y)$$

## Feature loss (Preserve content in feature space) <sub>$x$</sub>

$$\mathbb{E}_x ||F(G(x)) - F(x)||$$



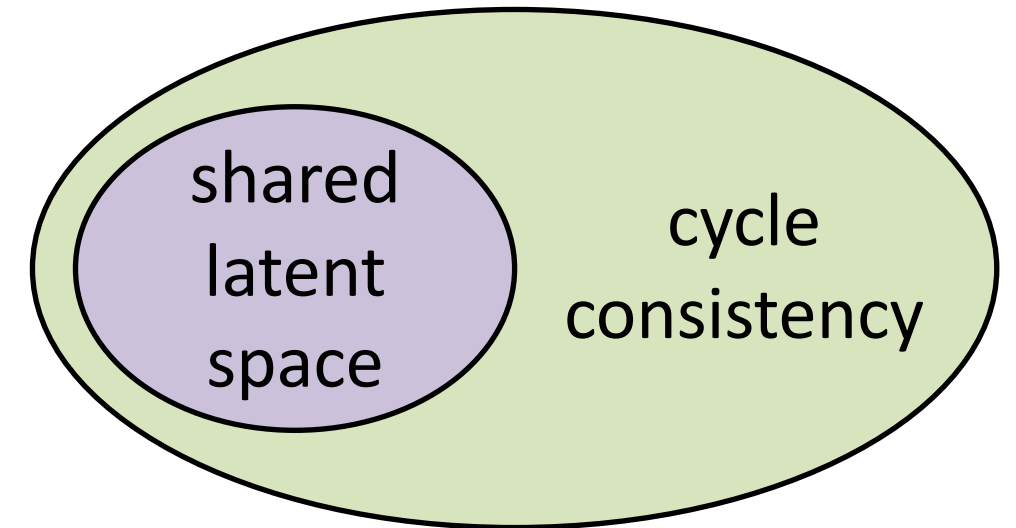
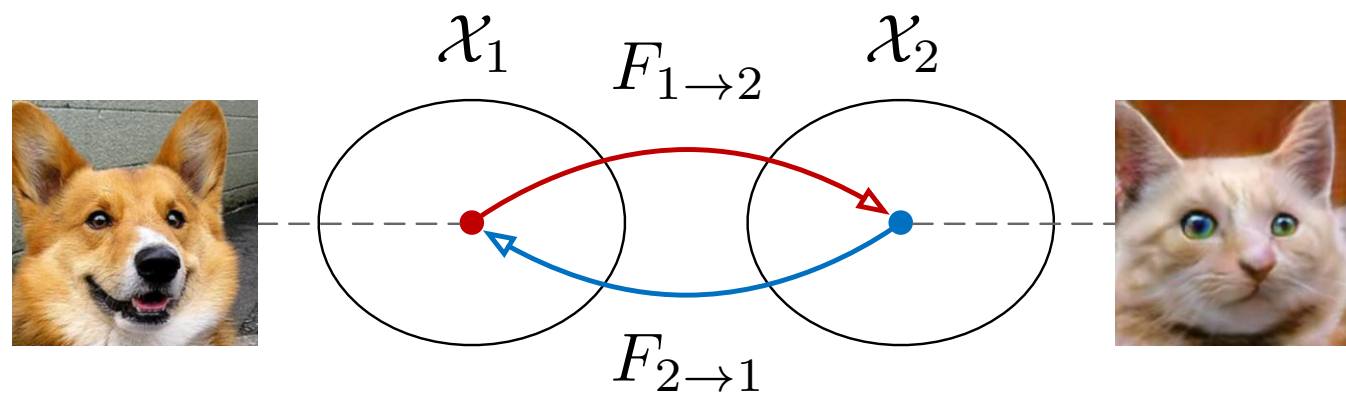
DTN [Taigman et al., 2017]

# Style and Content

- Style: domain-specific features  
(horse vs. zebra)
- Content: features shared across two domains

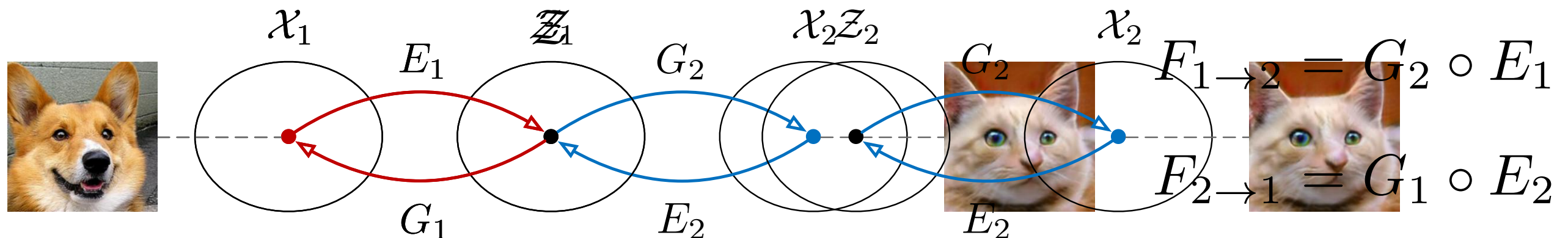
# CycleGAN and UNIT

- CycleGAN (cycle consistency)



- UNIT (shared latent space) [Liu et al. 2017]

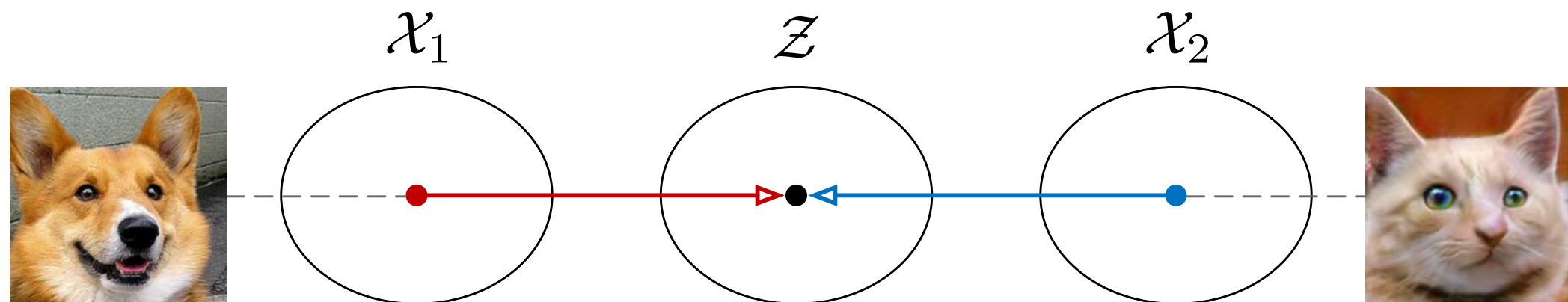
shared latent space  $\Rightarrow$  cycle consistency





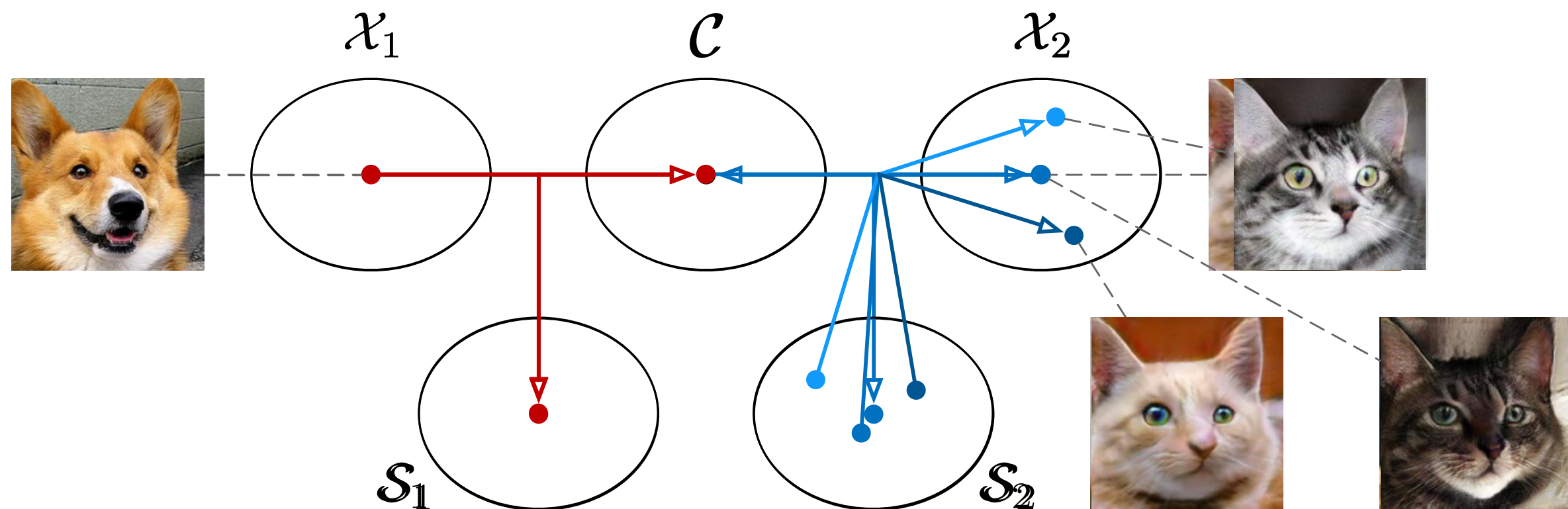
# Disentangling the Latent Space

- UNIT
  - A single **shared, domain-invariant** latent space  $\mathcal{Z}$



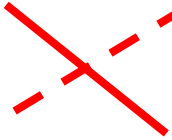
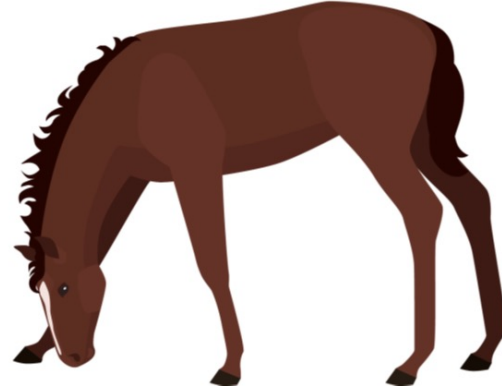
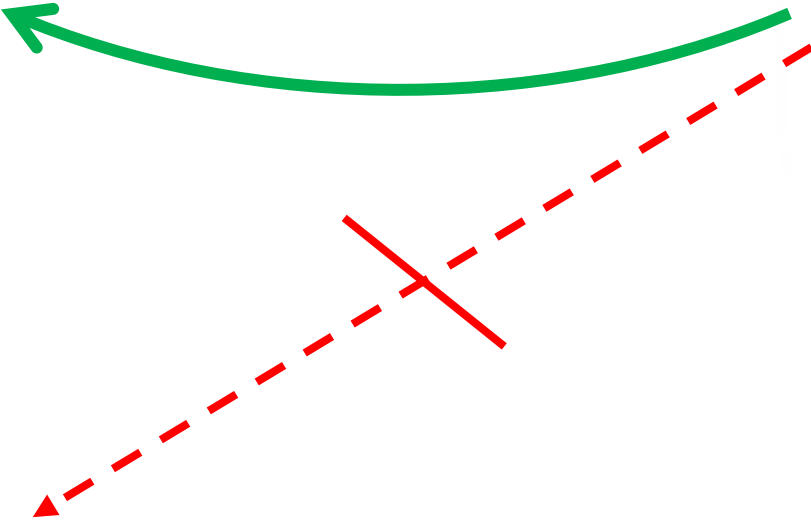
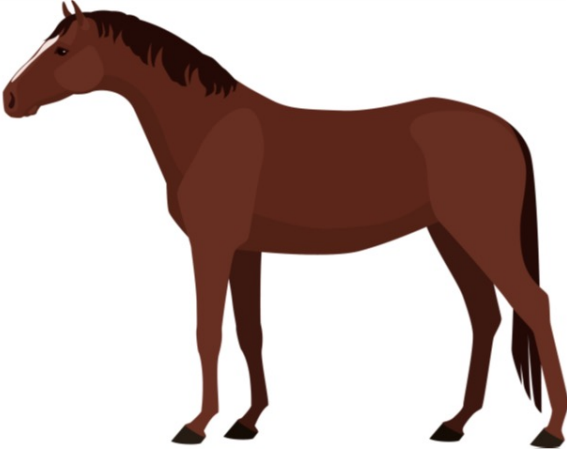
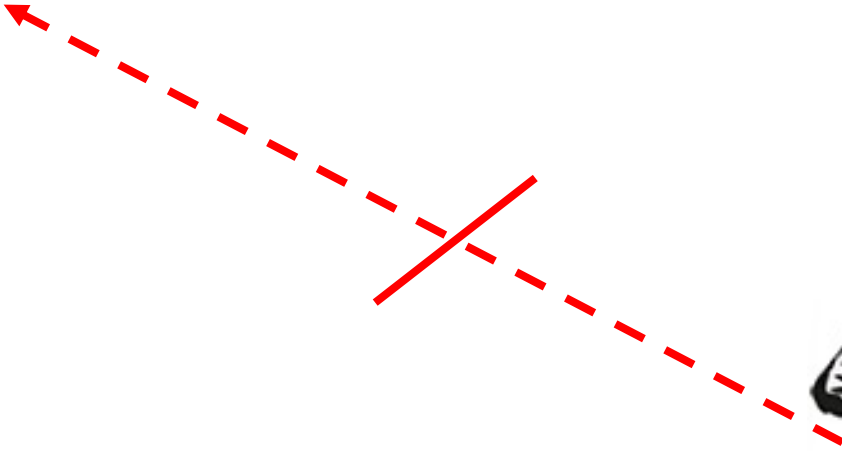
# Disentangling the Latent Space

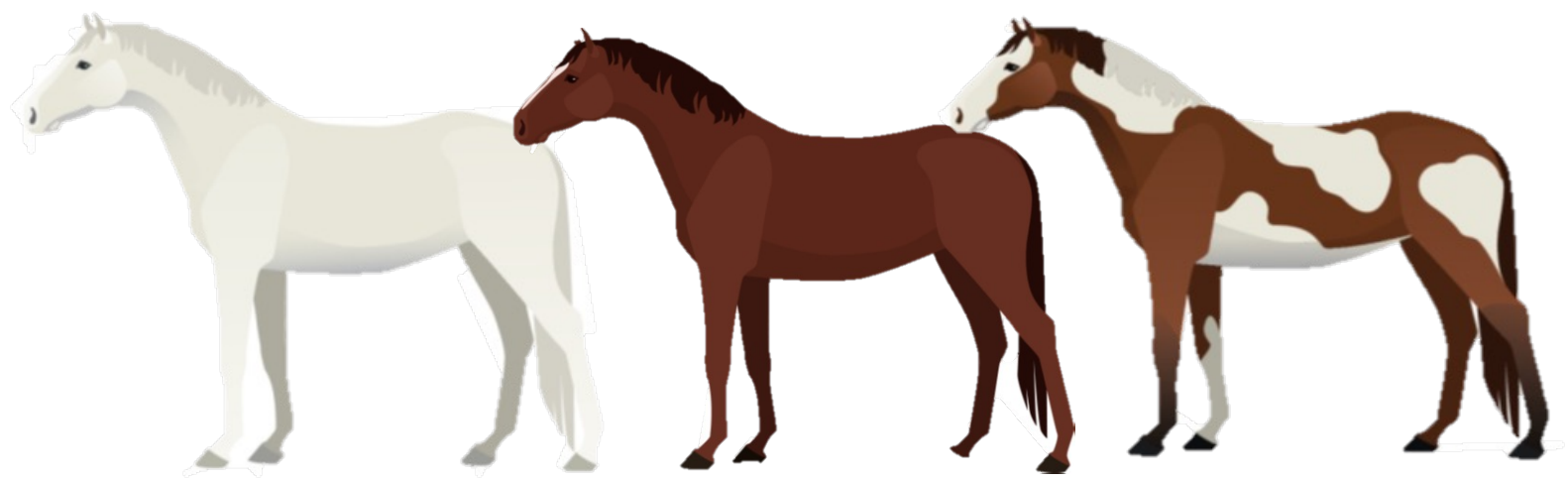
- Multimodal UNIT (MUNIT)
  - A **content** space  $\mathcal{C}$  that is **shared, domain-invariant**
  - Two **style** spaces  $\mathcal{S}_1, \mathcal{S}_2$  that are **unshared, domain-specific**



# Style and Content

- Style: variations within the same domain  
(different colors, textures, etc.)
- Content: features shared across two domains

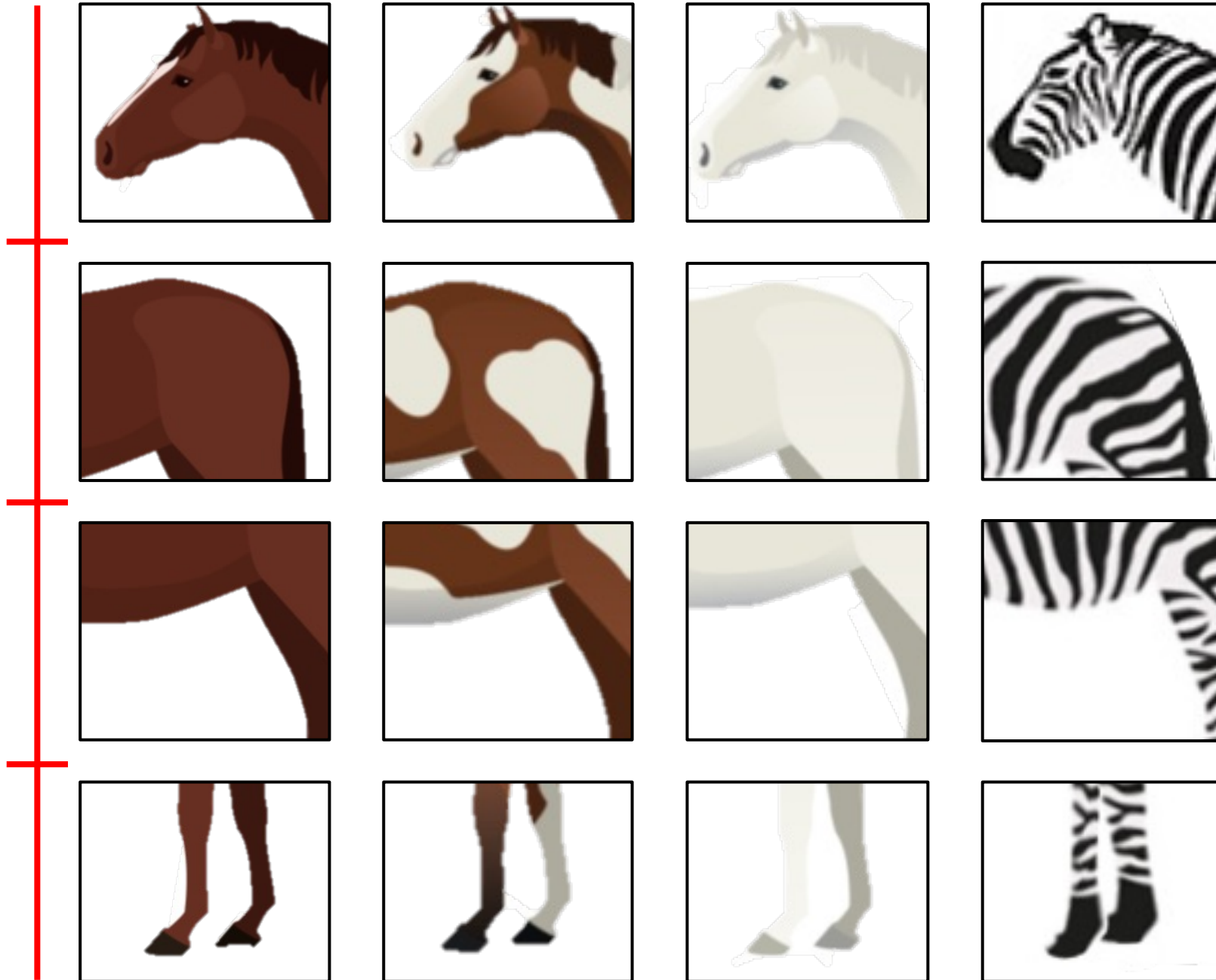




Style

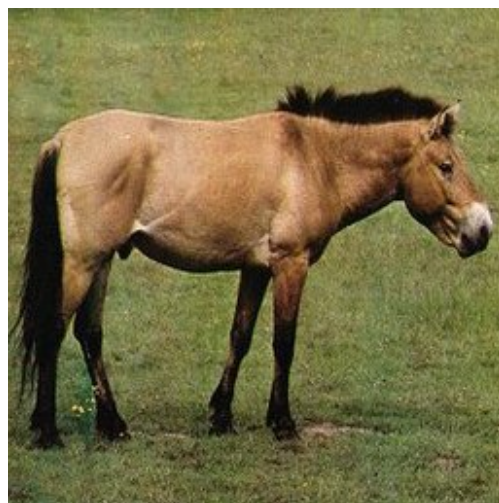


Content

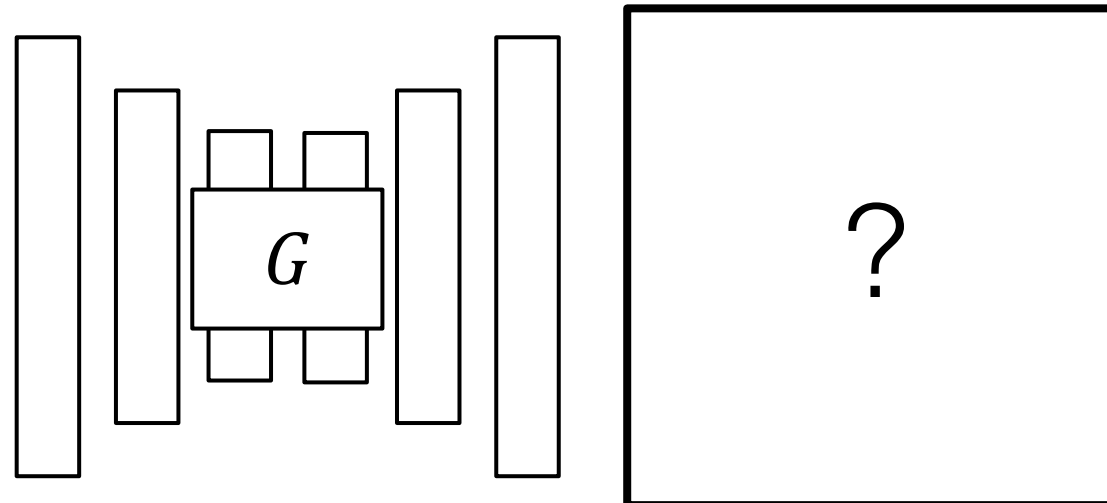


# What makes for a good output?

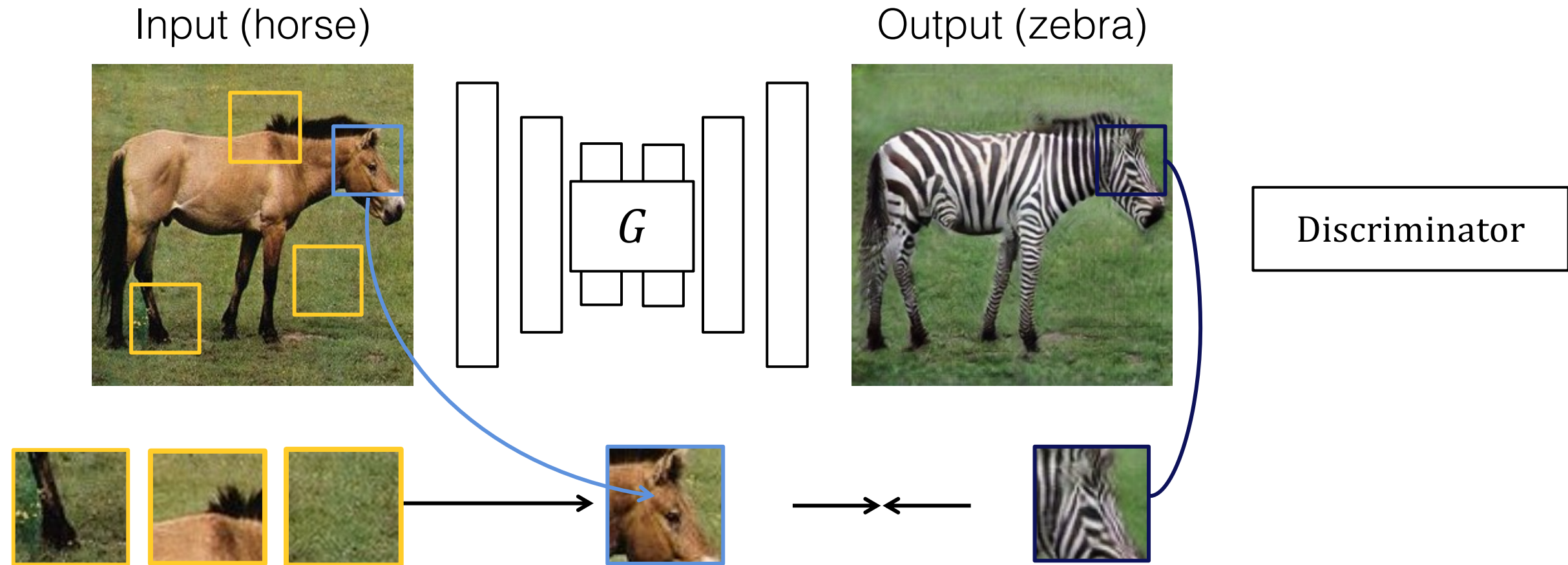
Input (horse)



Output (zebra)

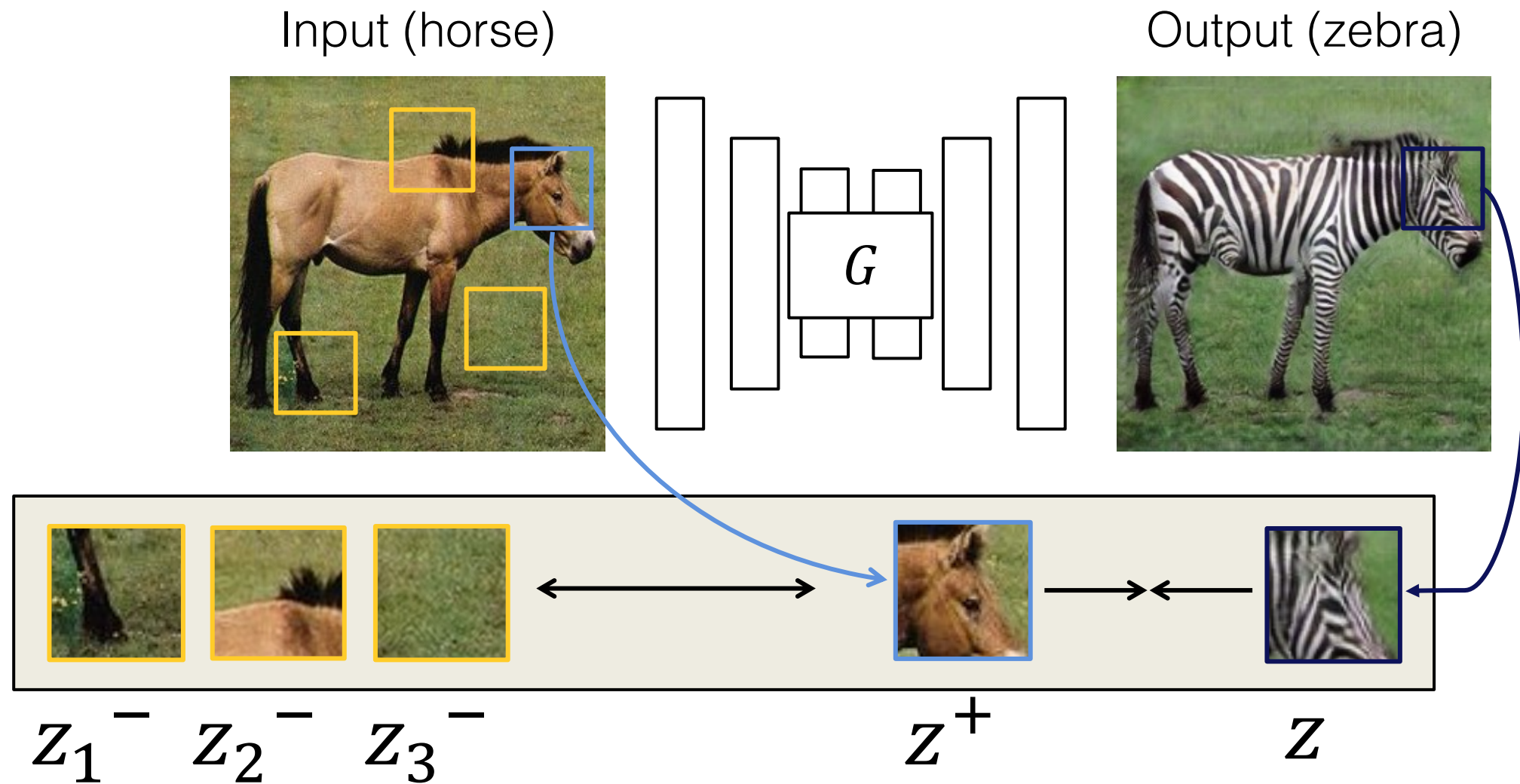


# Retaining input content



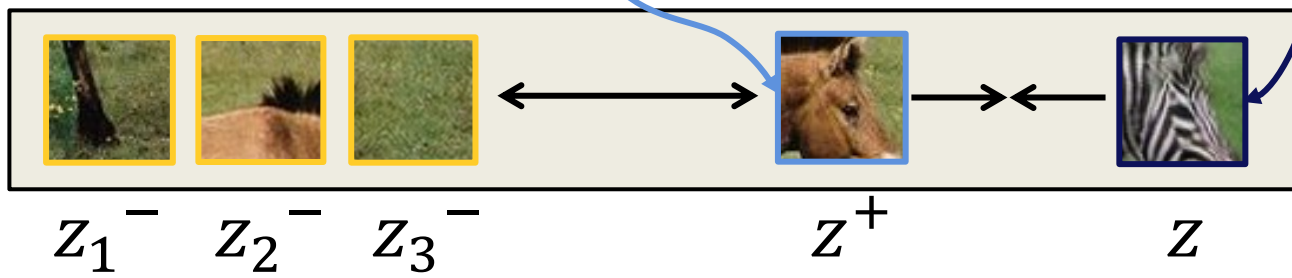
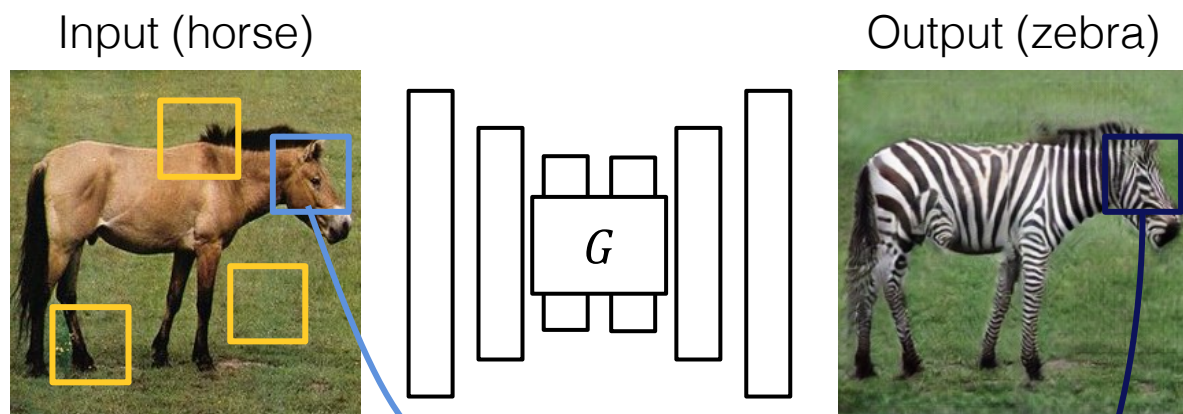


# Retaining input content



Corresponding patches should have high similarity

# Patch-based Contrastive Loss



softmax

$$\begin{pmatrix} \uparrow z \cdot z^+ / \tau \\ \downarrow z \cdot z_1^- / \tau \\ \downarrow z \cdot z_2^- / \tau \\ \vdots \\ \downarrow z \cdot z_N^- / \tau \end{pmatrix}$$

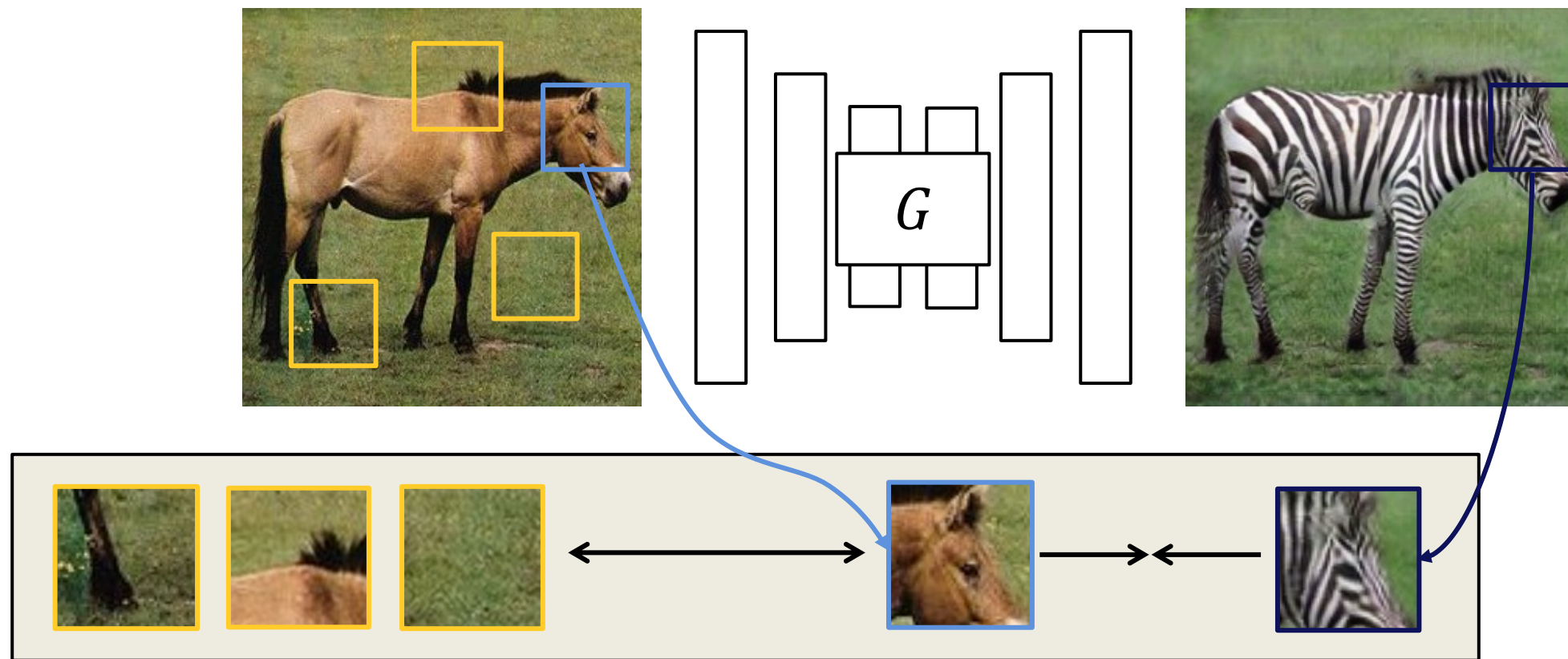


1
0
0
⋮
0

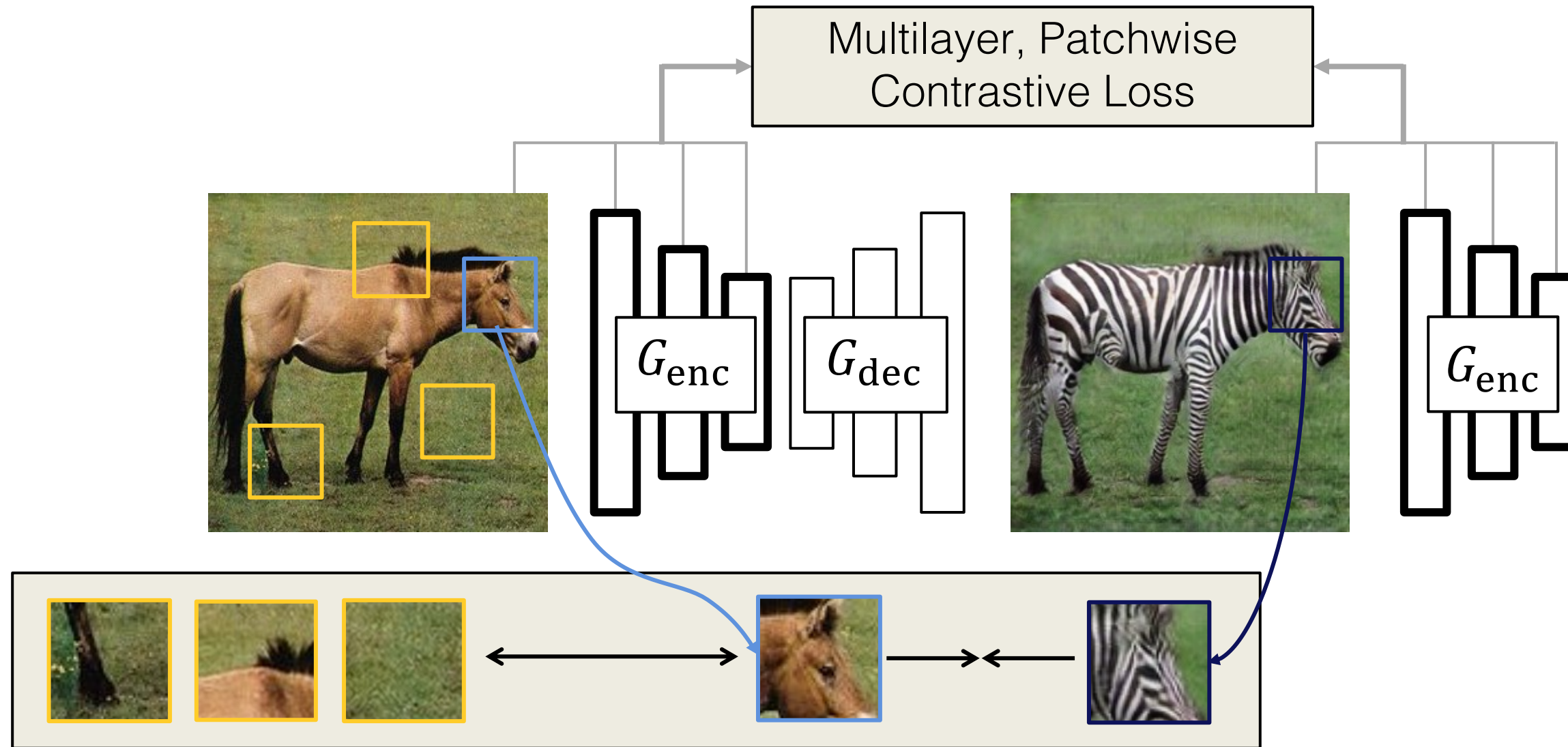
softmax (cosine similarities  $/\tau$ )  
 $\tau=0.07$

- InfoNCE loss (Gutmann et al., AISTATS18 , van den Oord et al., 2018) used in MoCo and SimCLR
- To produce positive pairs:
  - Handcrafted data augmentation (MoCo, SimCLR, etc.)
  - Input and synthesized image (ours)

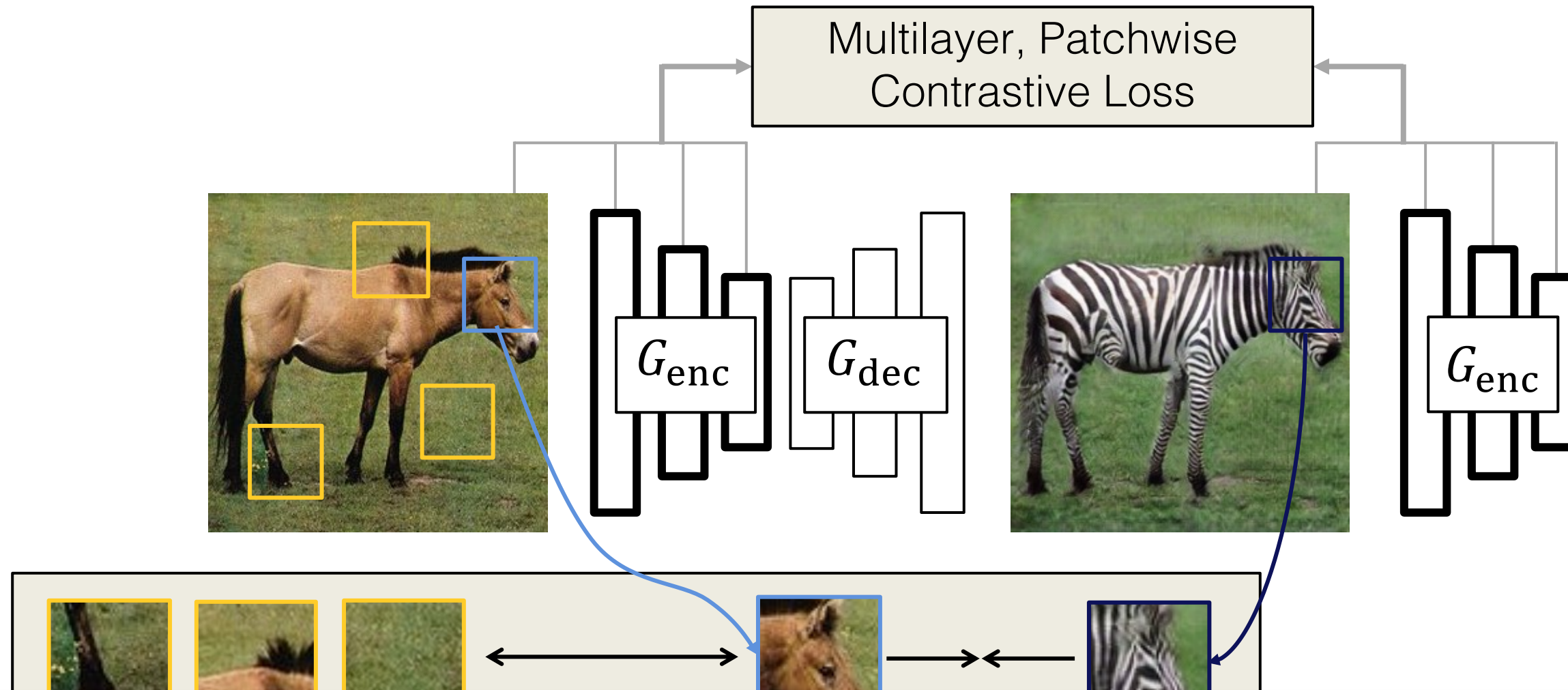
# Patchwise contrastive loss



# Patchwise contrastive loss

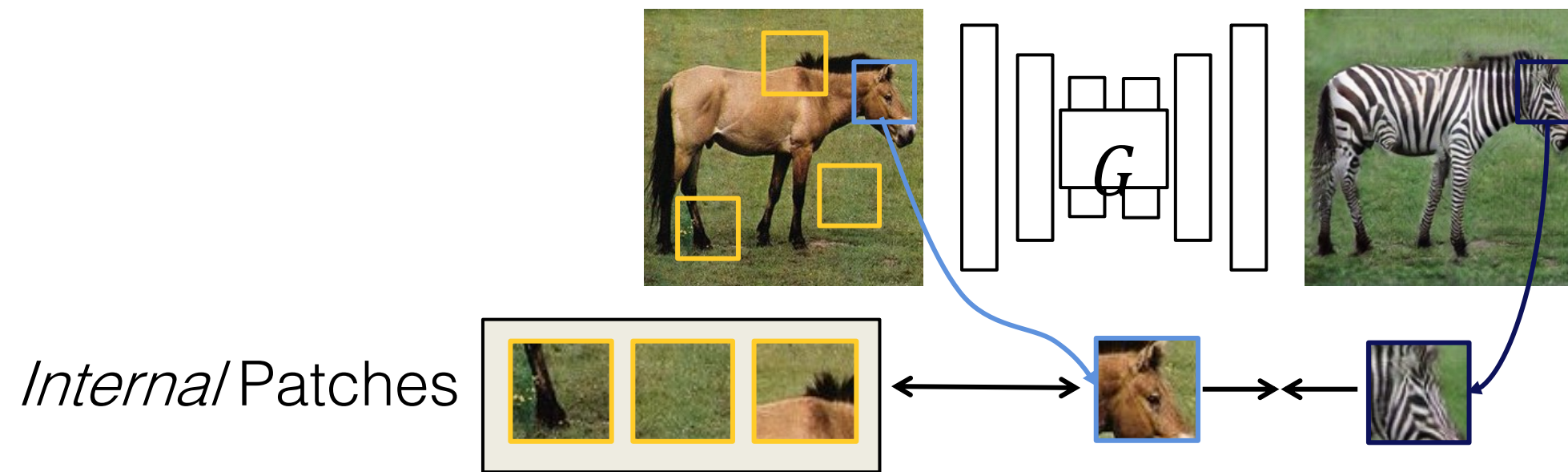


# Patchwise contrastive loss

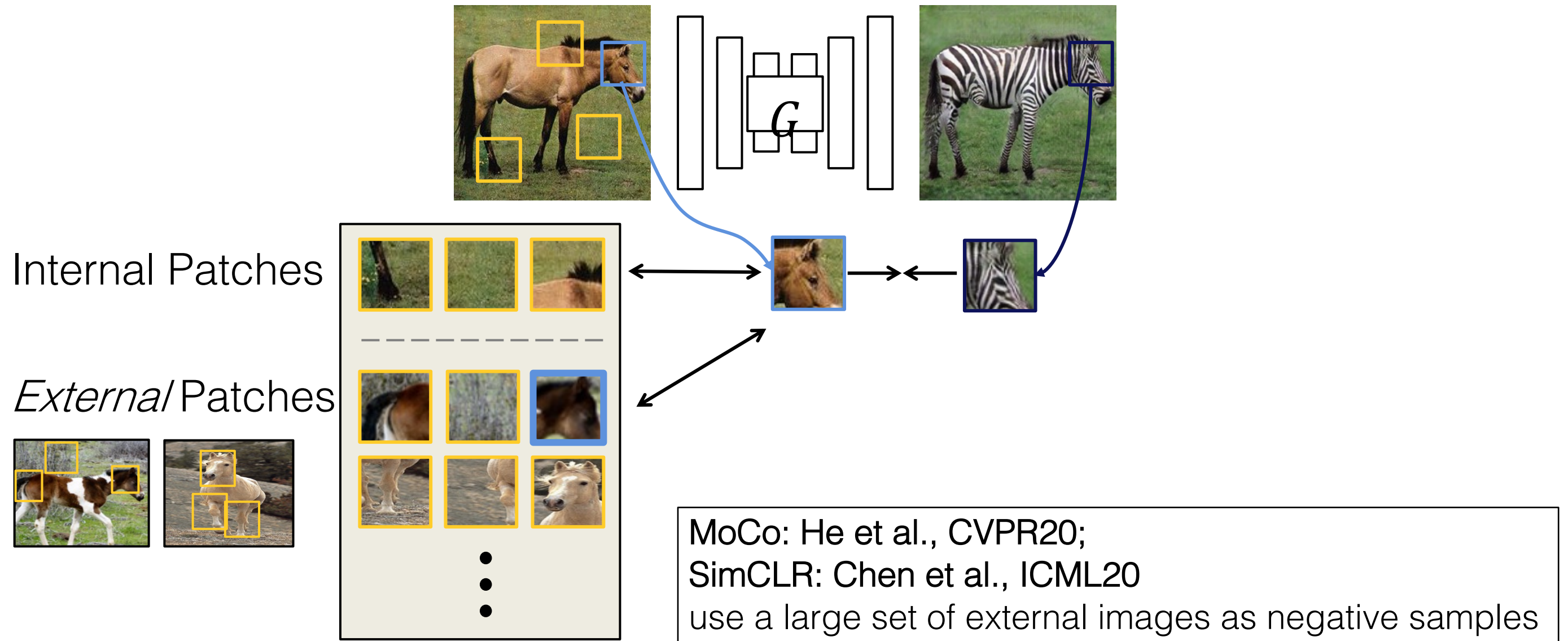


- + No fixed similarity metric (e.g., L1 or perceptual loss)
- + One-sided (no inverse mapping needed)

# Internal vs External Patches



# Internal vs External Patches



External patches make things worse

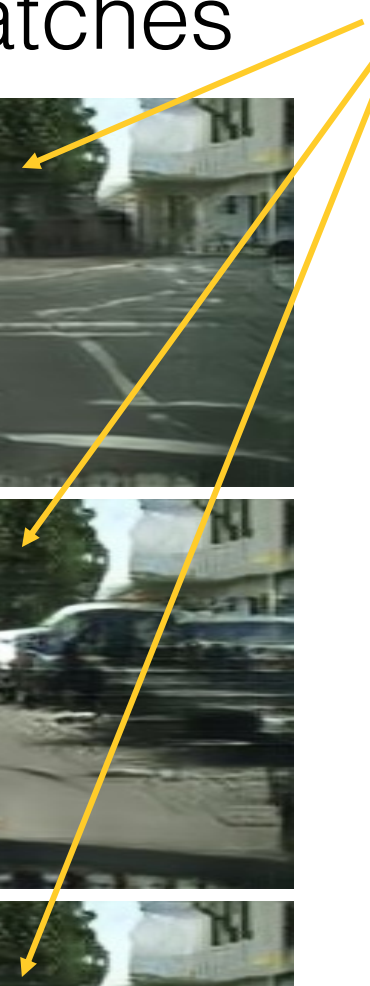
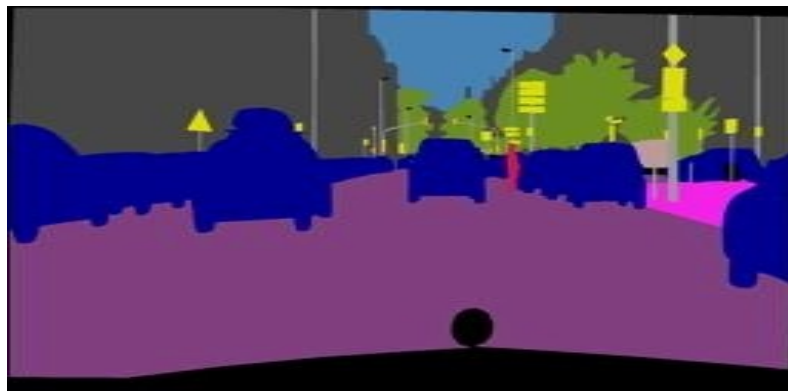
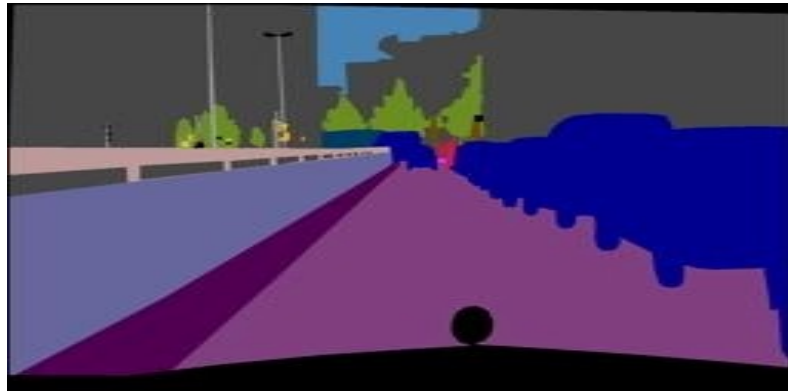
# Internal vs External Patches

input

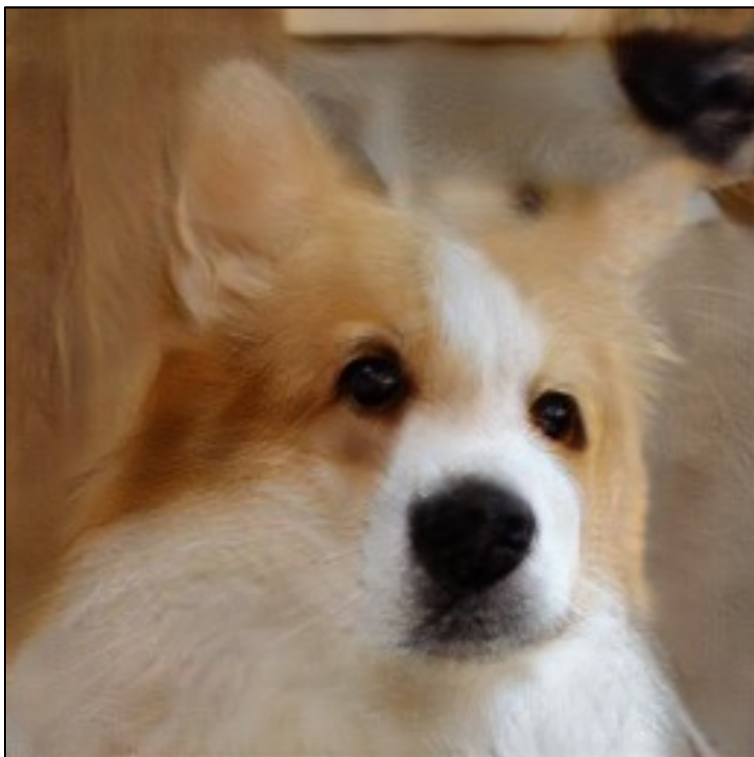
internal patches

external patches

**Mode  
Collapse!**







Cat



Yosemite Summer



Apple



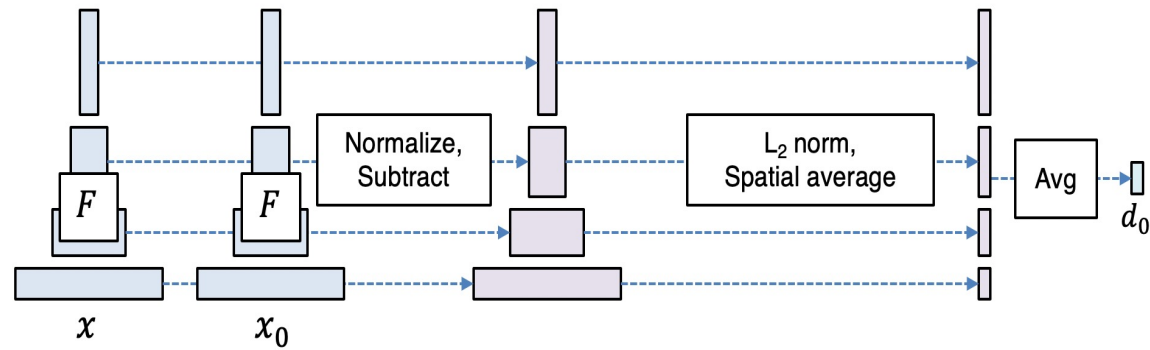
Paris



GTA

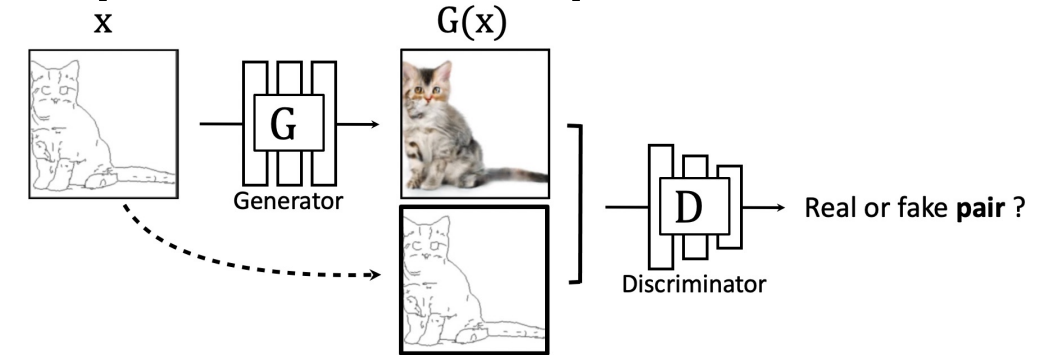
# Summary

# Perceptual/Feature Loss



How well do "perceptual losses" describe perception?

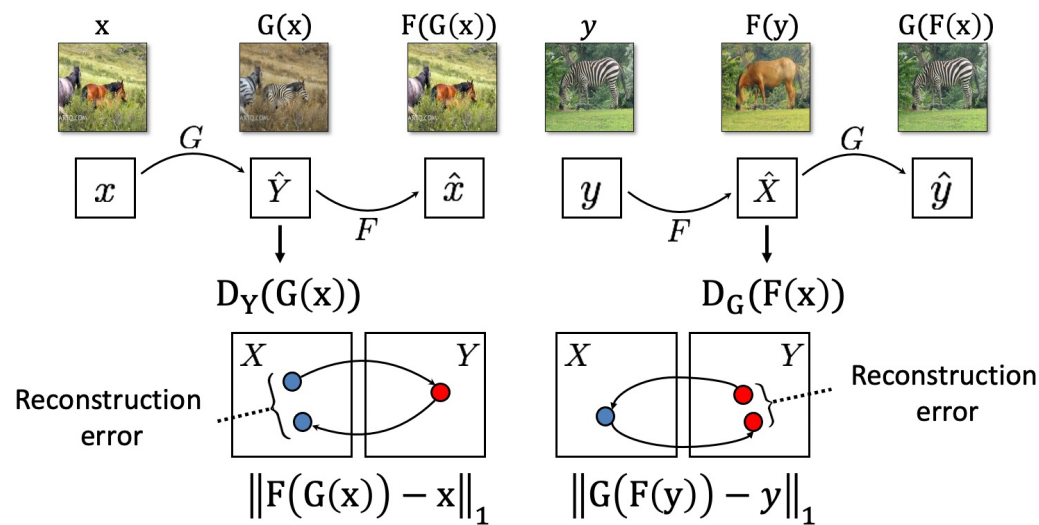
# (Conditional) GAN Loss



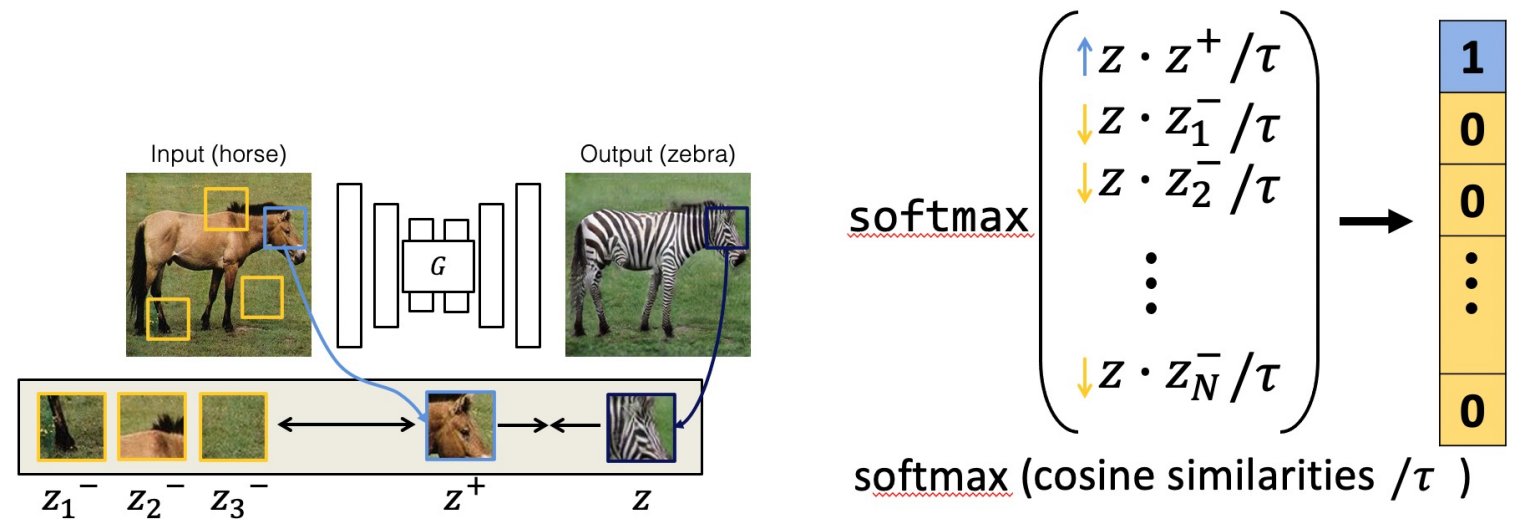
Learning objective

$$\min_G \max_D \mathbb{E}_x [\log(1 - D(x, G(x)))] + \mathbb{E}_{x,y} [\log D(x, y)]$$

# Cycle-Consistency Loss



# Patch-wise Contrastive Loss



Other loss functions: Style Loss [Gatys et al.], Contextual Loss [Mechrez et al.], Domain-specific Loss (e.g., face), 3D-aware Loss (for geometric data)



# Style and Content, Texture Synthesis

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# Texture

- Texture depicts spatially repeating patterns
- Many natural phenomena are textures



radishes



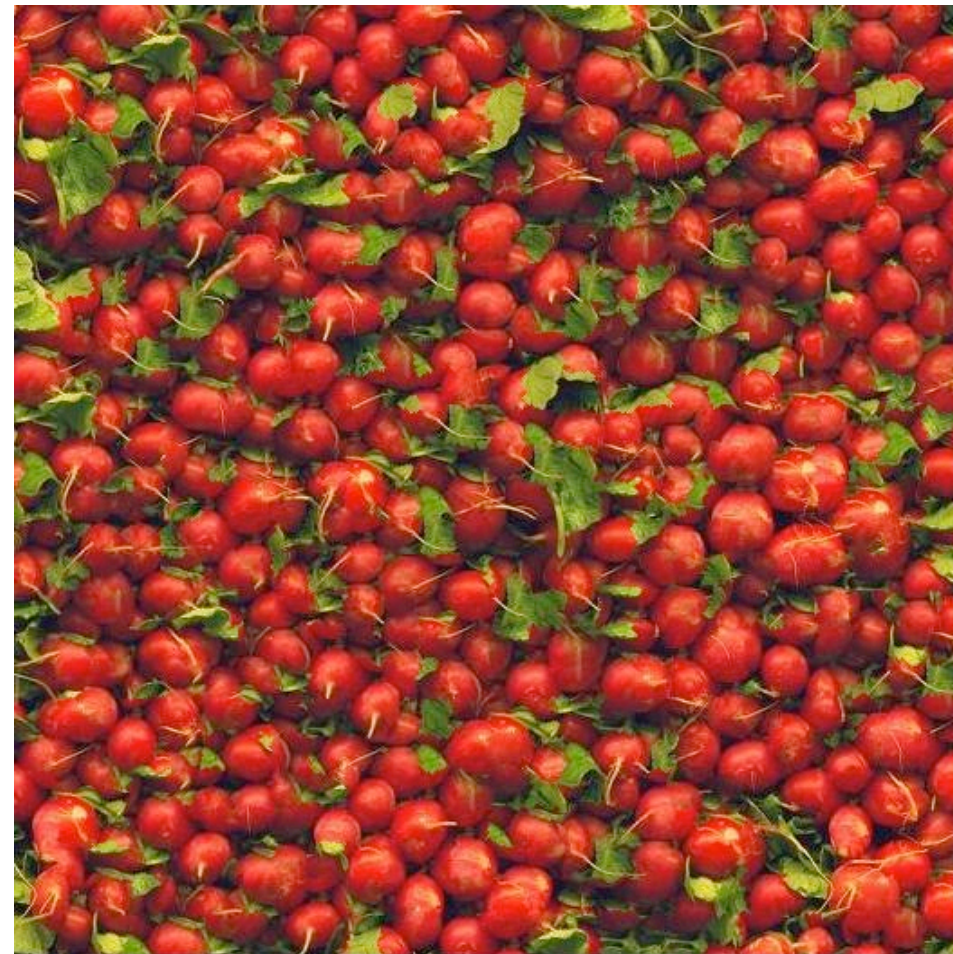
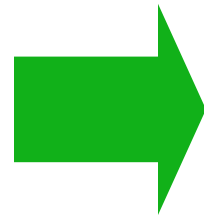
rocks



yogurt

# Texture Synthesis

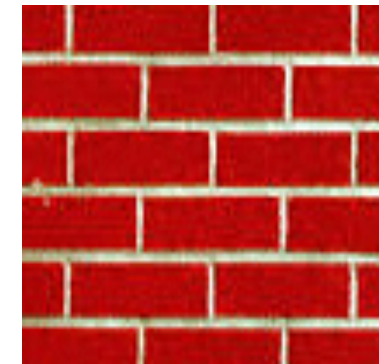
- Goal: create new samples of a given texture
- Applications: virtual environments, inpainting, texturing surfaces



# Non-parametric Texture Synthesis

# The Challenge

- Need to model the whole spectrum: from repeated to stochastic texture



**repeated**



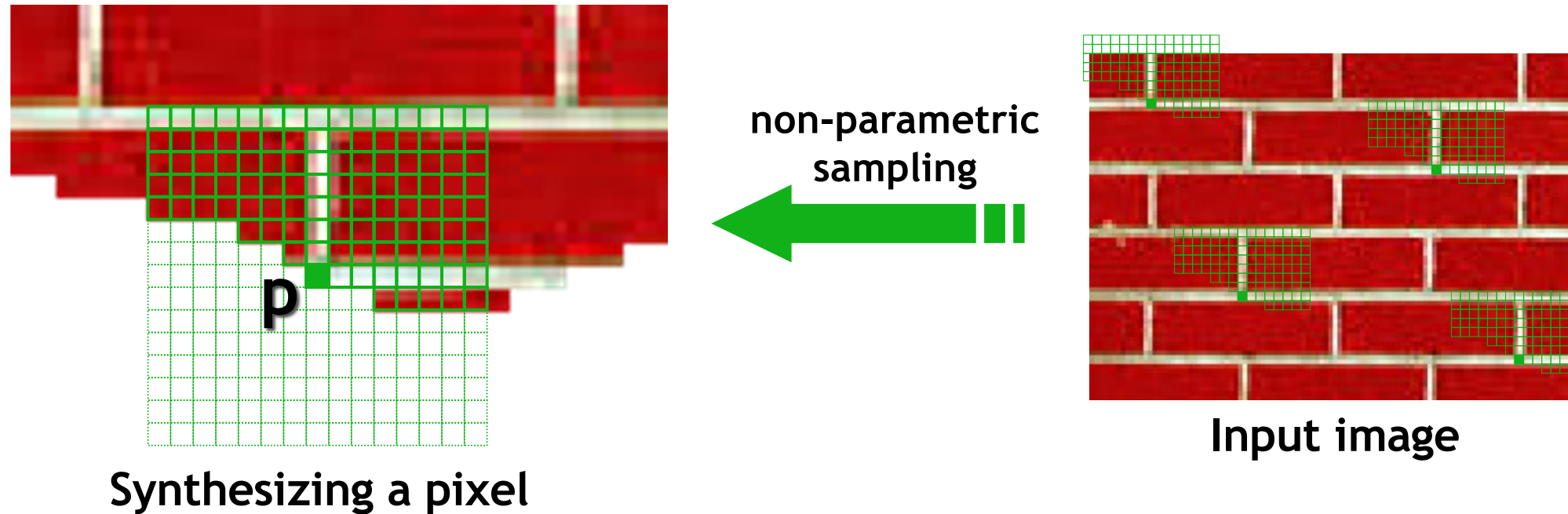
**stochastic**



**Both?**



# Efros & Leung Algorithm



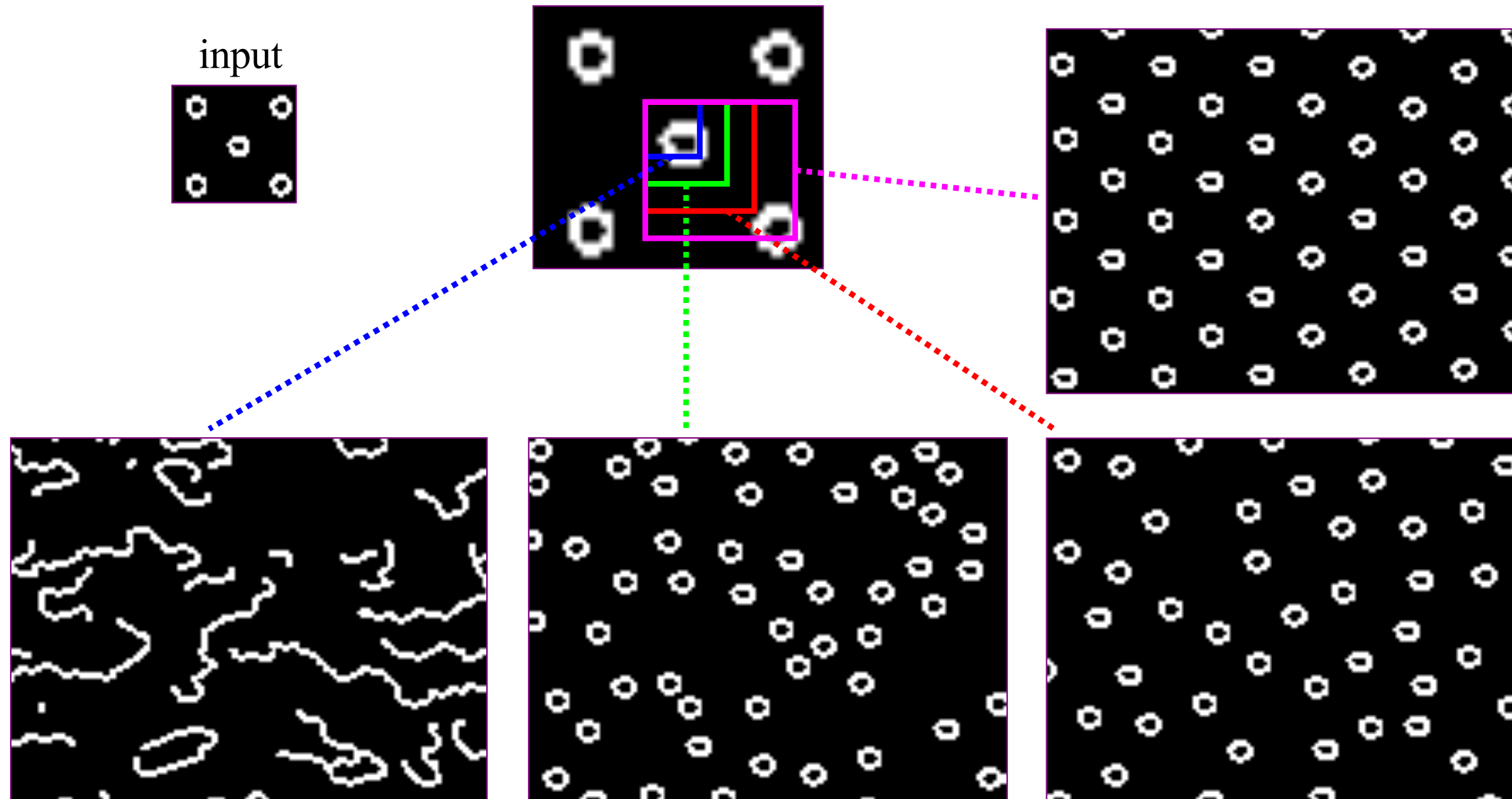
- Assuming Markov property, compute  $P(\mathbf{p} | N(\mathbf{p}))$ 
  - Building explicit probability tables infeasible
  - Instead, we *search the input image* for all similar neighbourhoods — that's our pdf for  $\mathbf{p}$
  - To sample from this pdf, just pick one match at random

PixelCNN

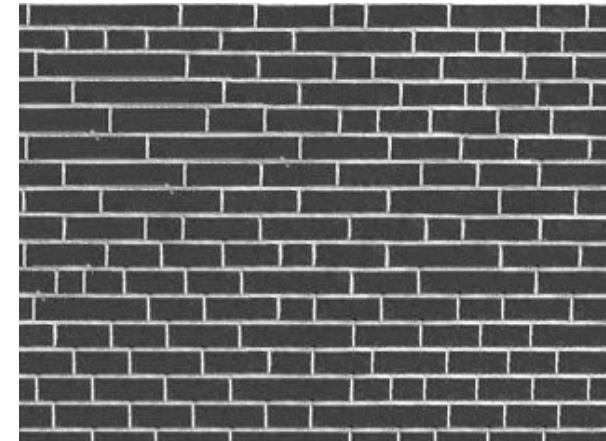
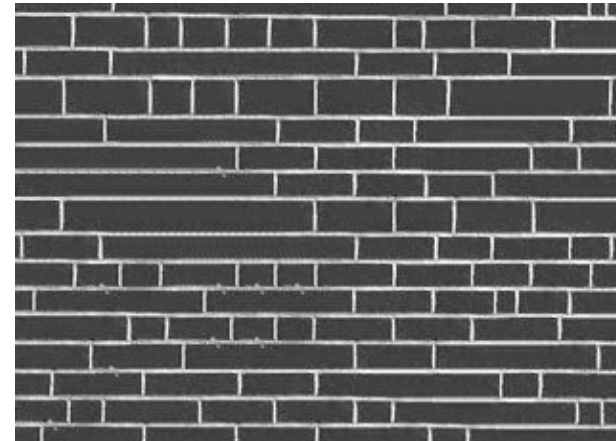
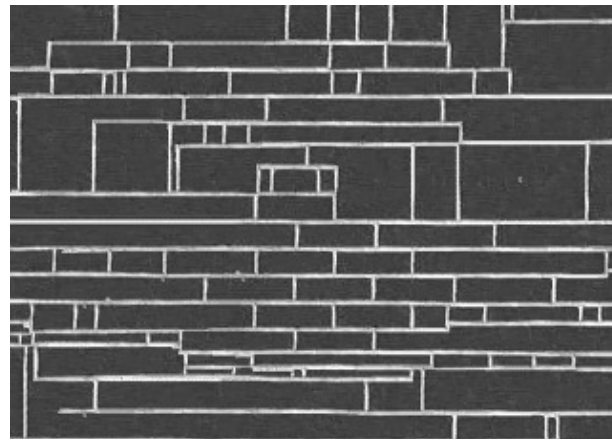
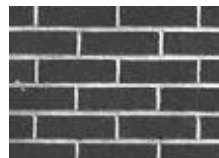
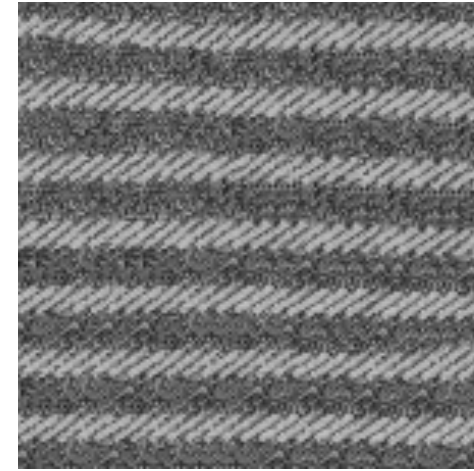
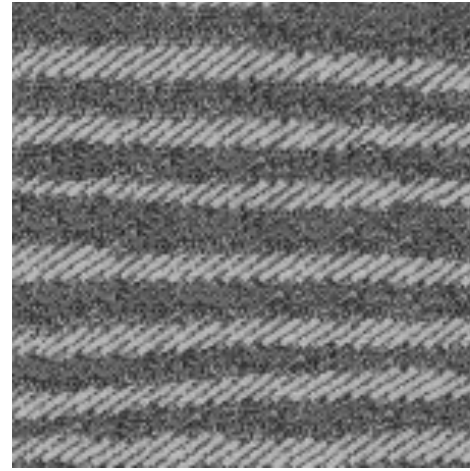
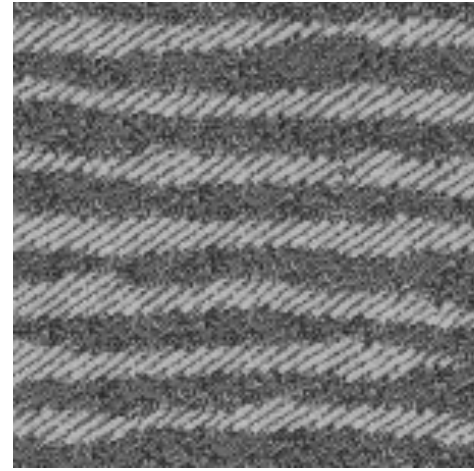
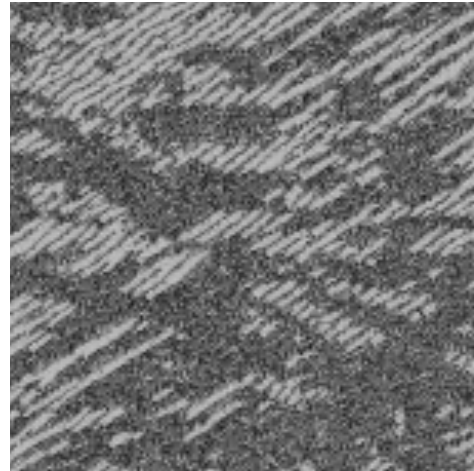
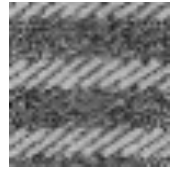
# Some Details

- Growing is in “onion skin” order
  - Within each “layer”, pixels with most neighbors are synthesized first
  - If no close match can be found, the pixel is not synthesized until the end
- Using *Gaussian-weighted SSD* is very important
  - to make sure the new pixel agrees with its closest neighbors
  - Approximates reduction to a smaller neighborhood window if data is too sparse

# Neighborhood Window



# Varying Window Size

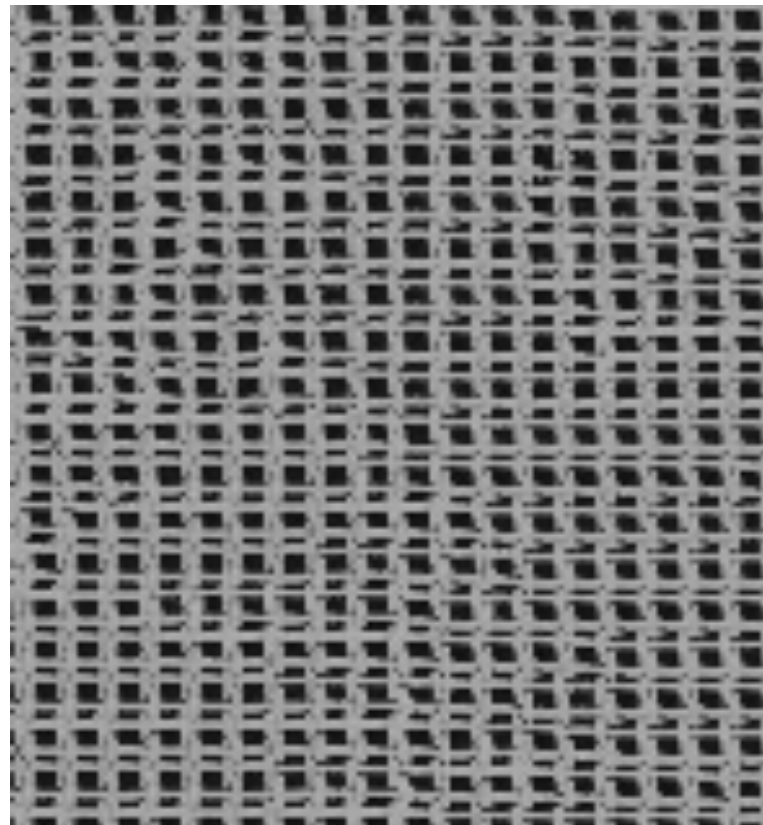
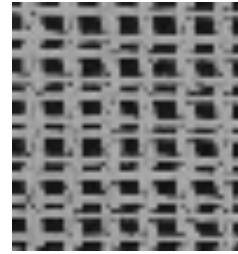


Increasing window size

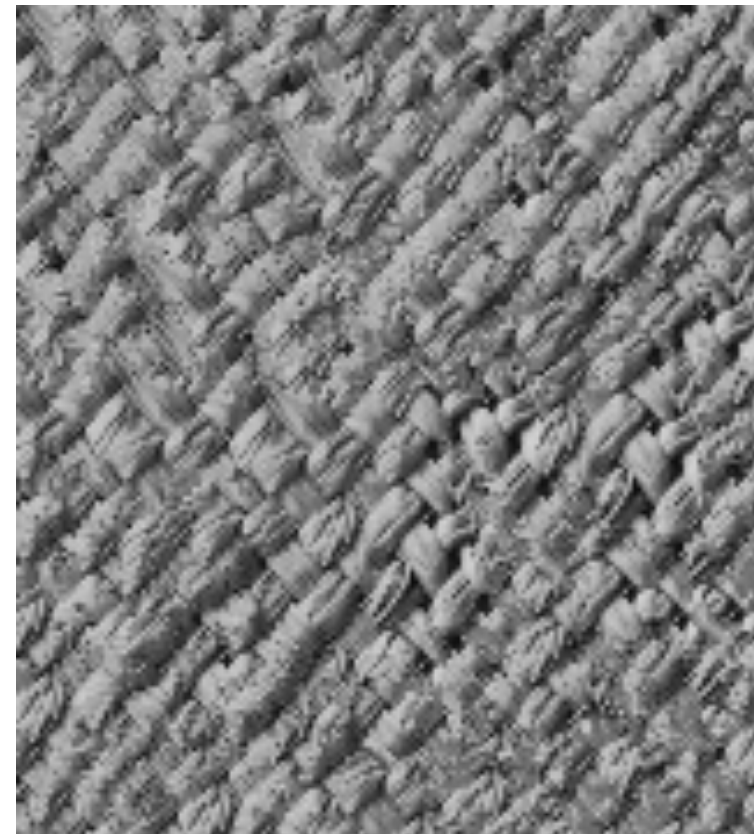
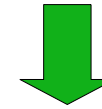


# Synthesis Results

french canvas



rafia weave

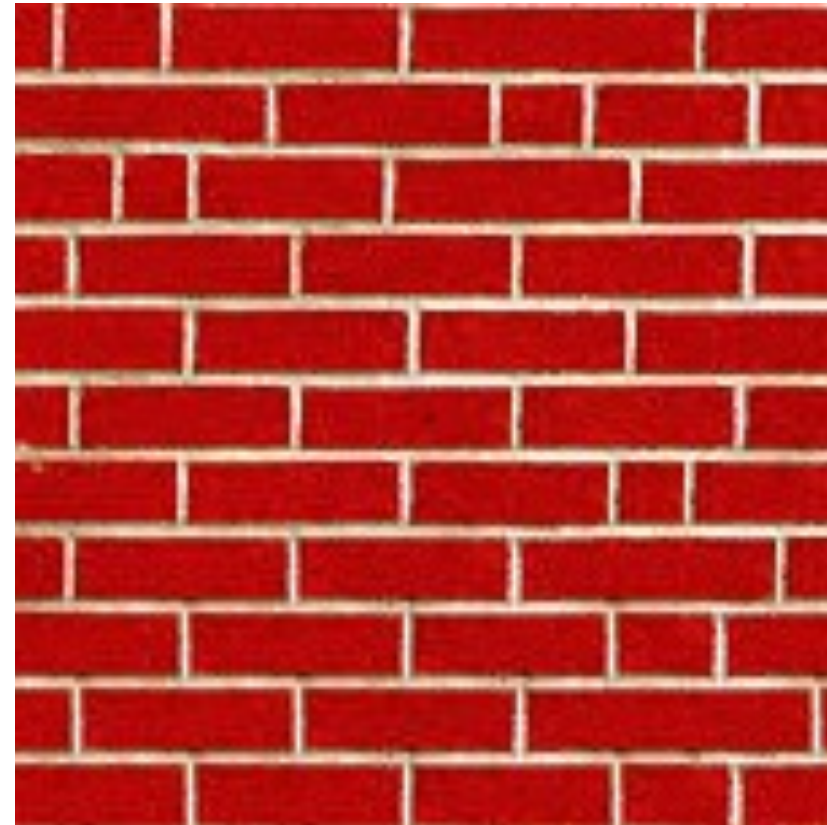
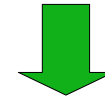
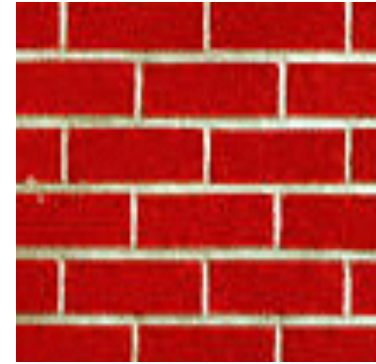


# More Results

white bread

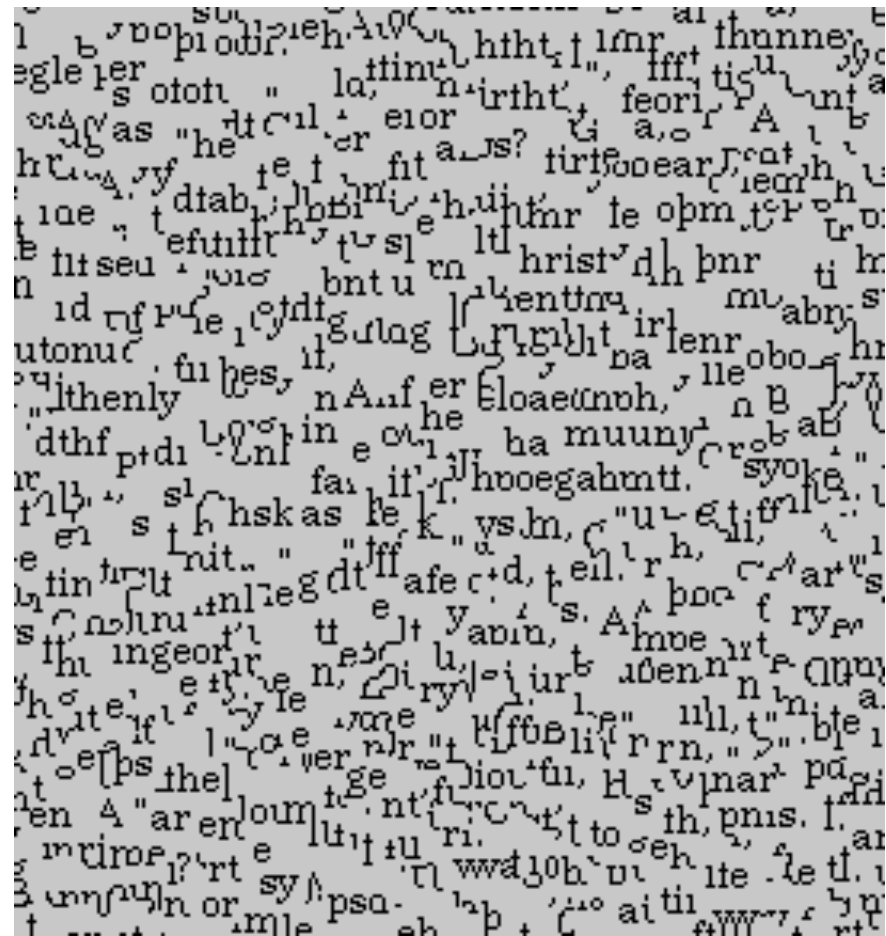


brick wall



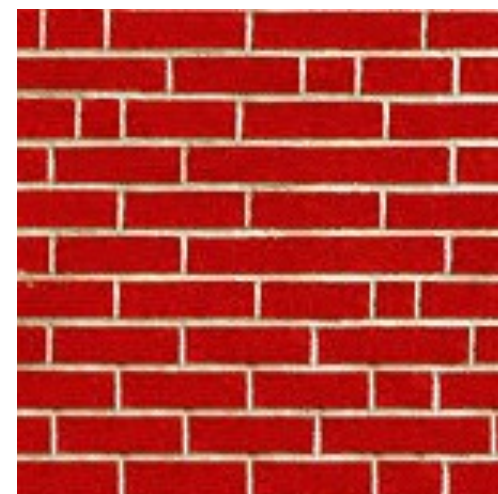
# Homage to Shannon

...ing in the unsensadon  
r Dick Gephardt was fai  
rful riff on the looming  
nly asked, "What's your  
tions?" A heartfelt sigh  
story about the emergen  
es against Clinton. "Boy  
g people about continuin  
ardt began, patiently obs  
s, that the legal system k  
g with this latest tanger



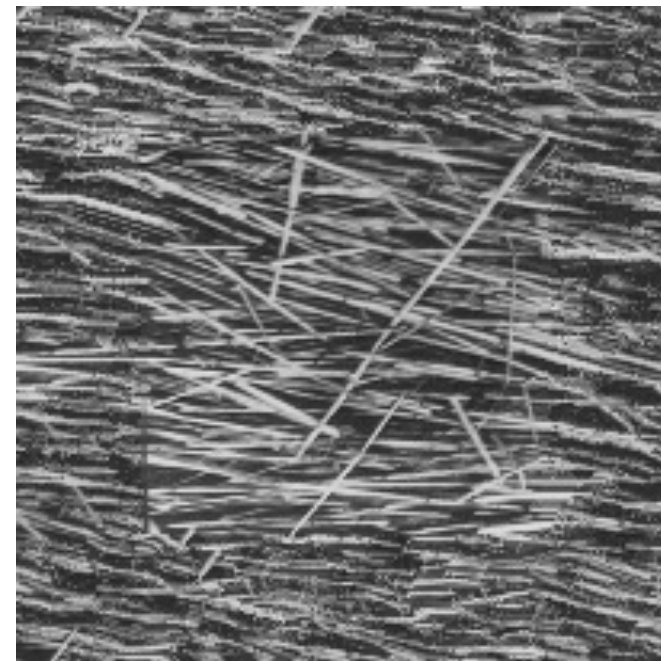
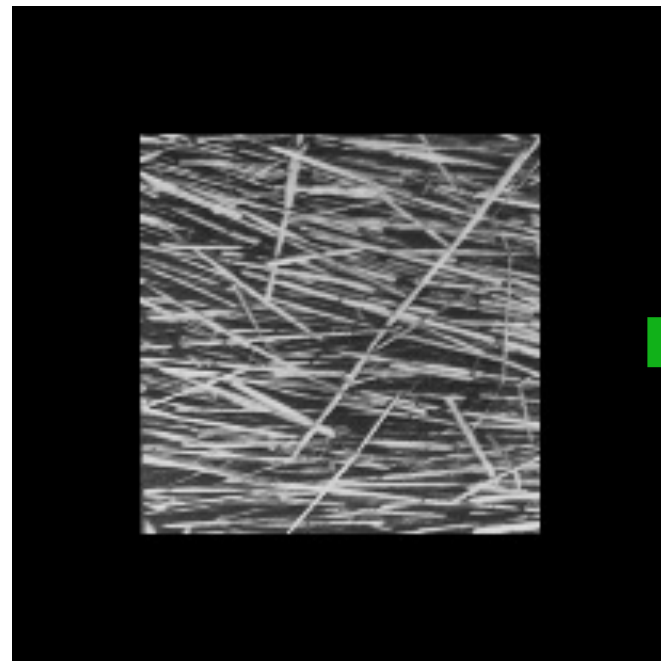
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the ry onst wartfe lck Gephtoomimeationl sigab  
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tiensteneltorydt telemephinsverdt was agemer  
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# Hole Filling





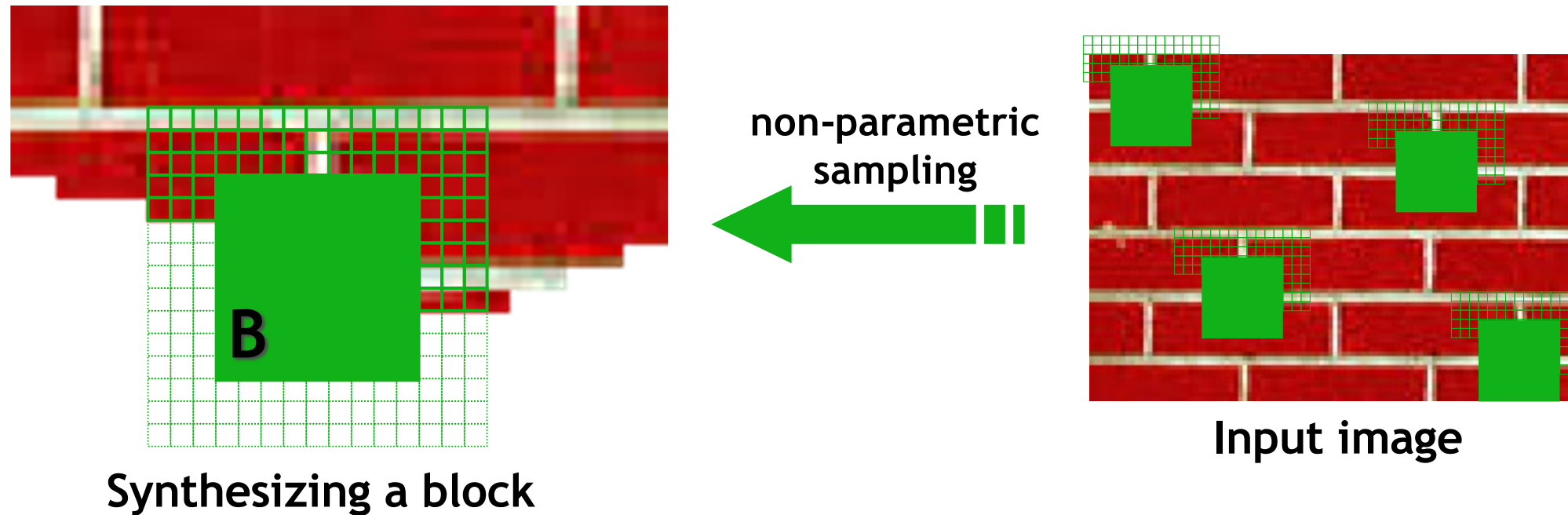
# Extrapolation



# Summary

- The Efros & Leung algorithm
  - + Very simple
  - + Surprisingly good results
  - + Synthesis is easier than analysis!
  - ...but very slow

# Image Quilting [Efros & Freeman]

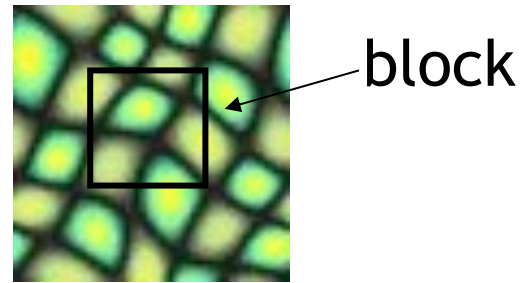


- Observation: neighbor pixels are highly correlated

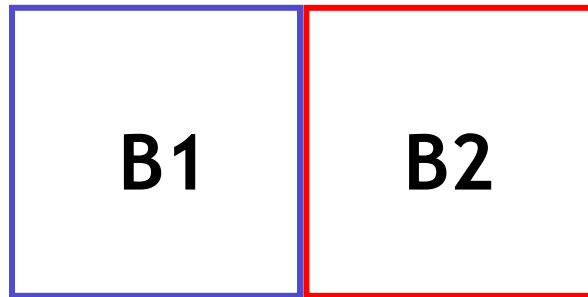
**Idea: unit of synthesis = block**

- Exactly the same but now we want  $P(\mathbf{B} | N(\mathbf{B}))$
- Much faster: synthesize all pixels in a block at once
- Not the same as multi-scale!

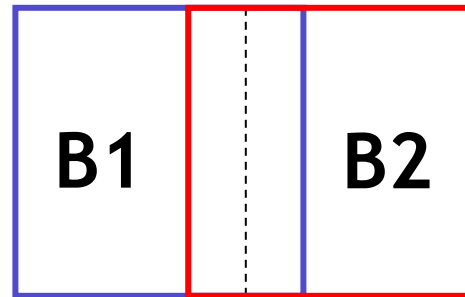
VQ-VAE2



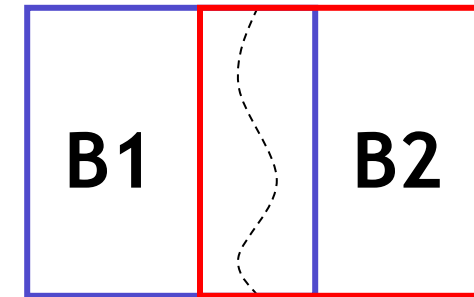
Input texture



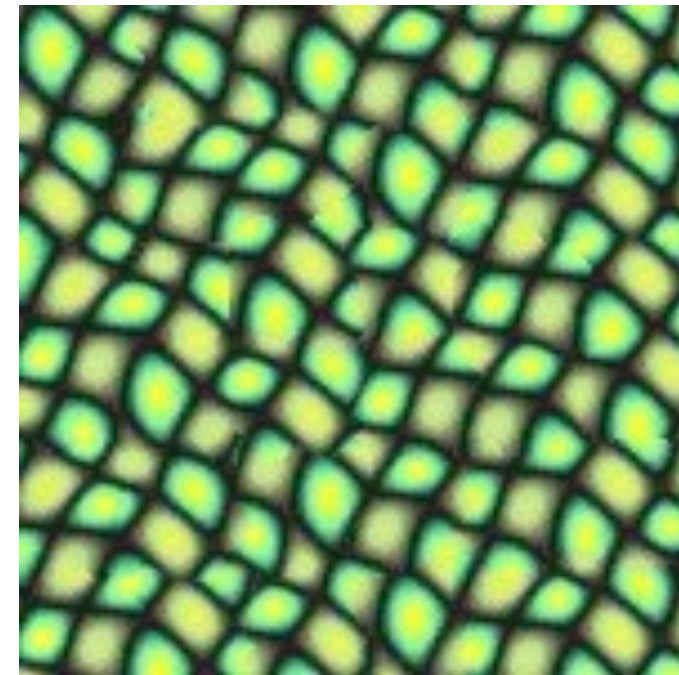
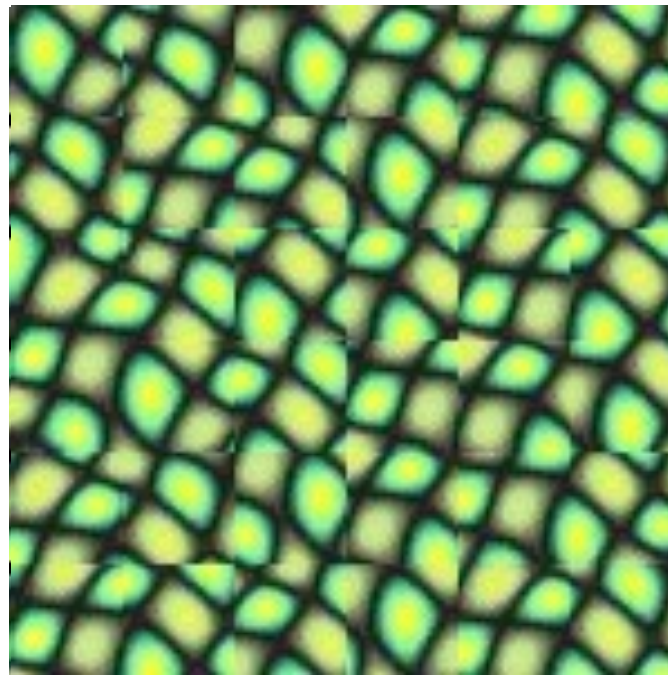
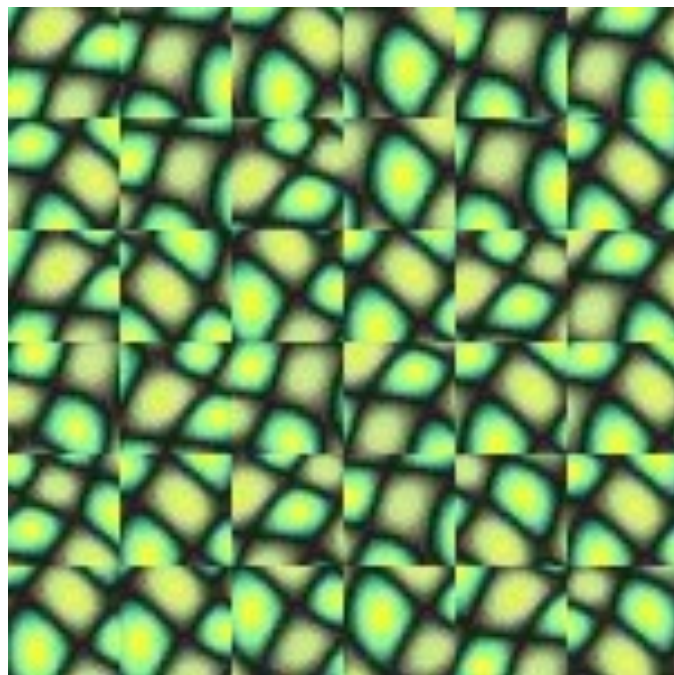
Random placement of blocks



Neighboring blocks constrained by overlap

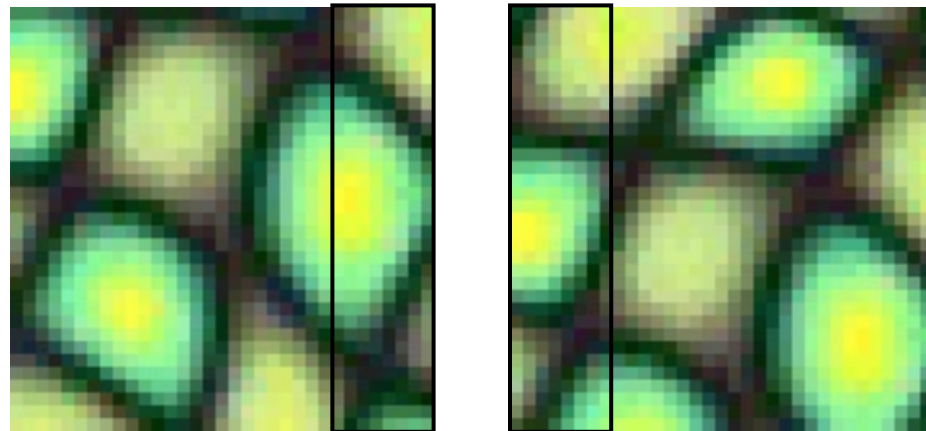


Minimal error boundary cut

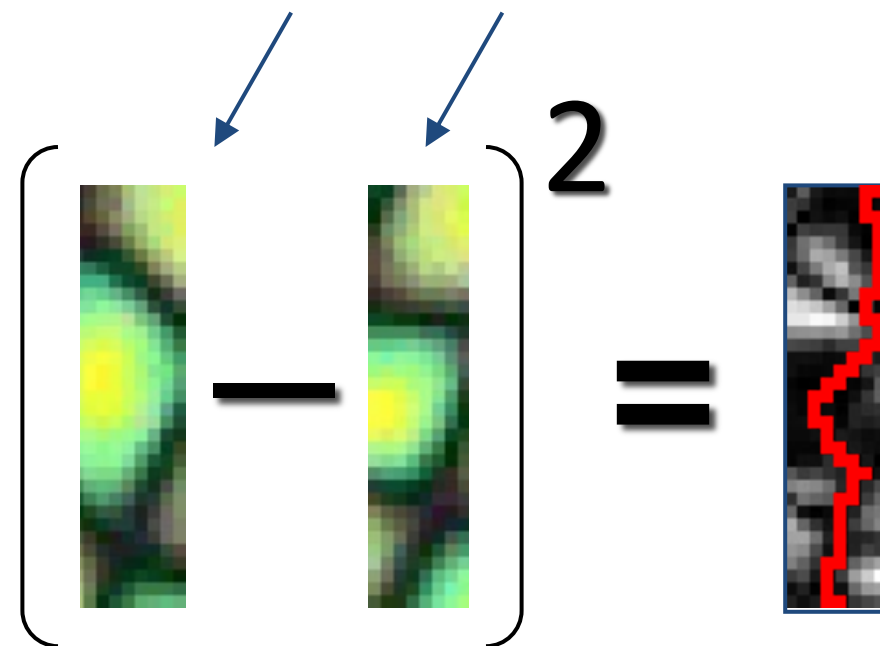
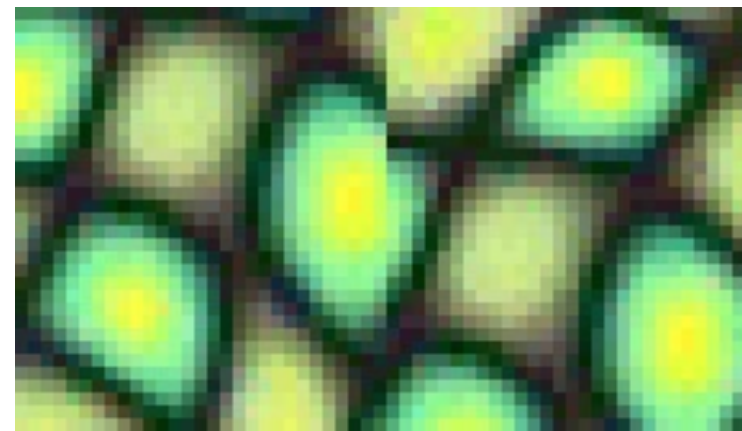


# Minimal error boundary

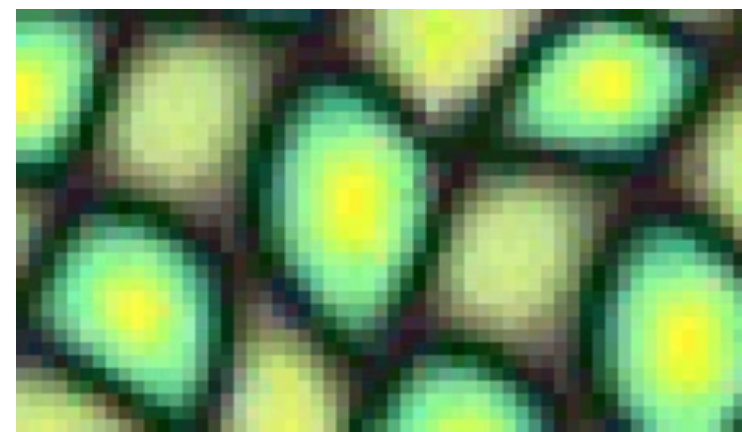
overlapping blocks



vertical boundary



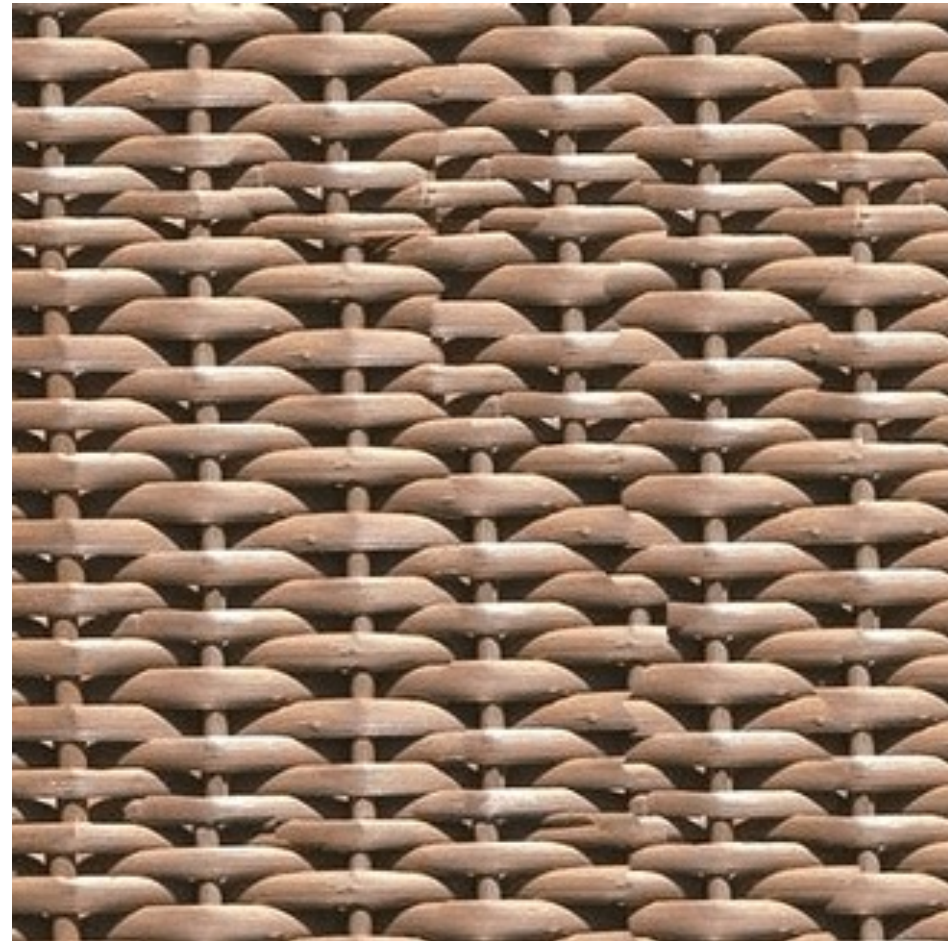
overlap error

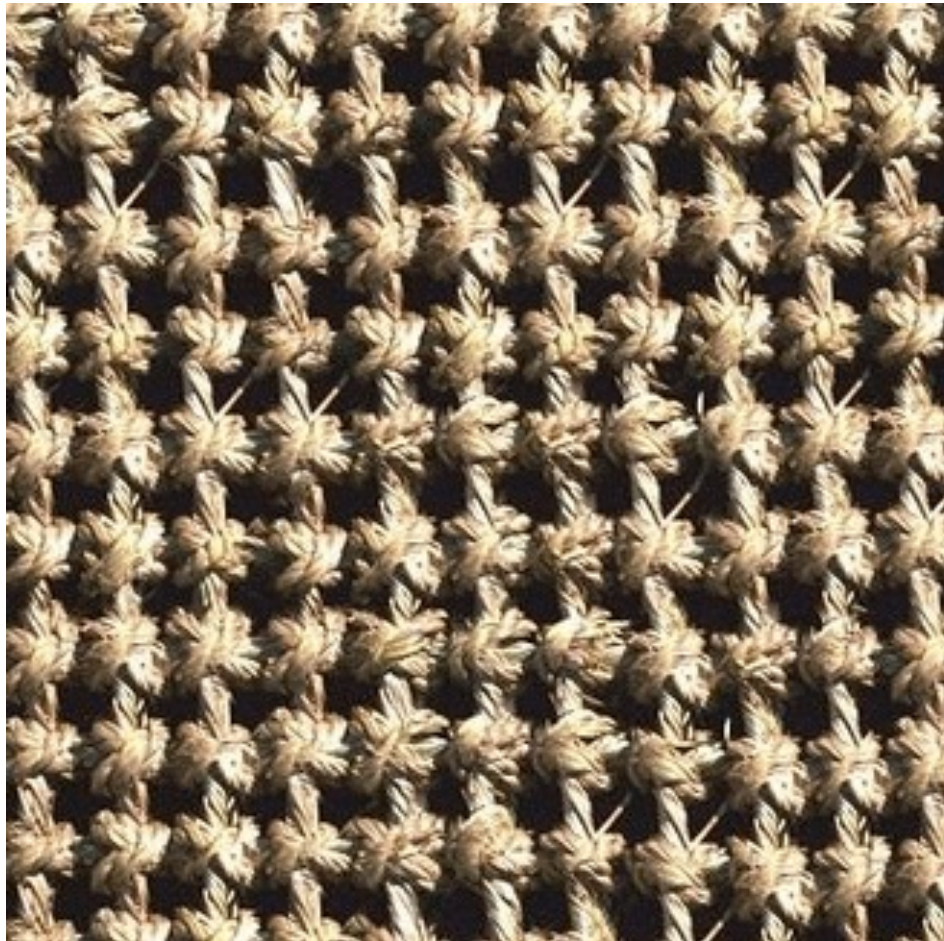


min. error boundary

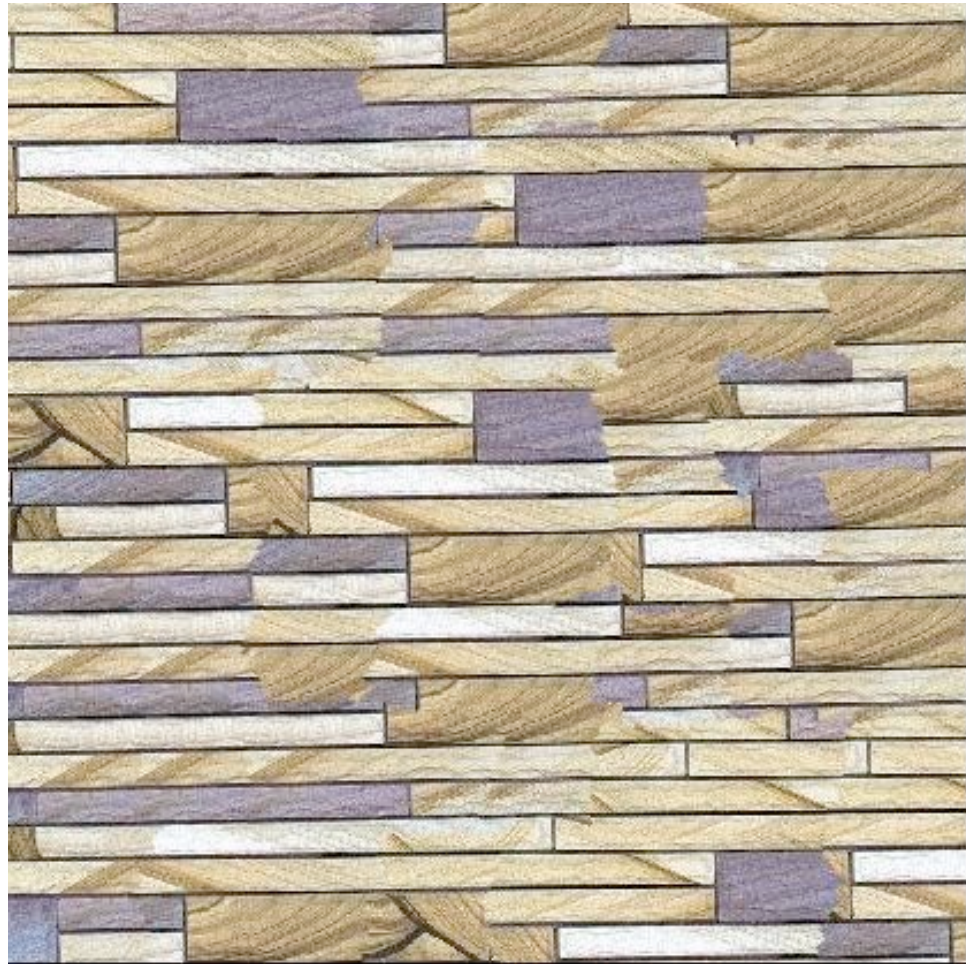
# Our Philosophy

- The “Corrupt Professor’s Algorithm”:
  - Plagiarize as much of the source image as you can
  - Then try to cover up the evidence
- Rationale:
  - Texture blocks are by definition correct samples of texture so problem only connecting them together



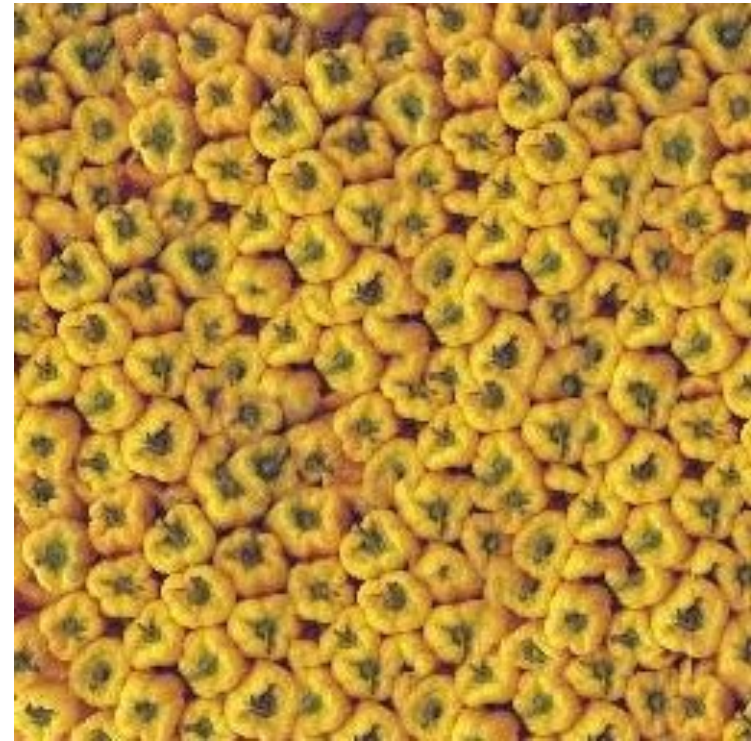
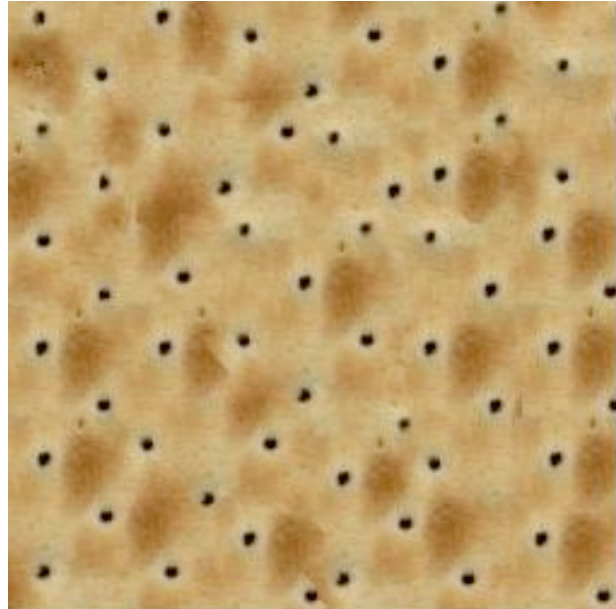
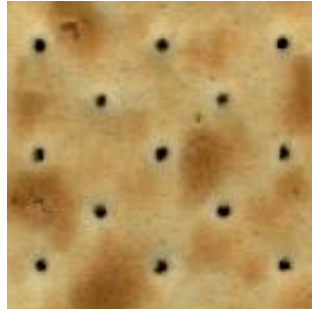








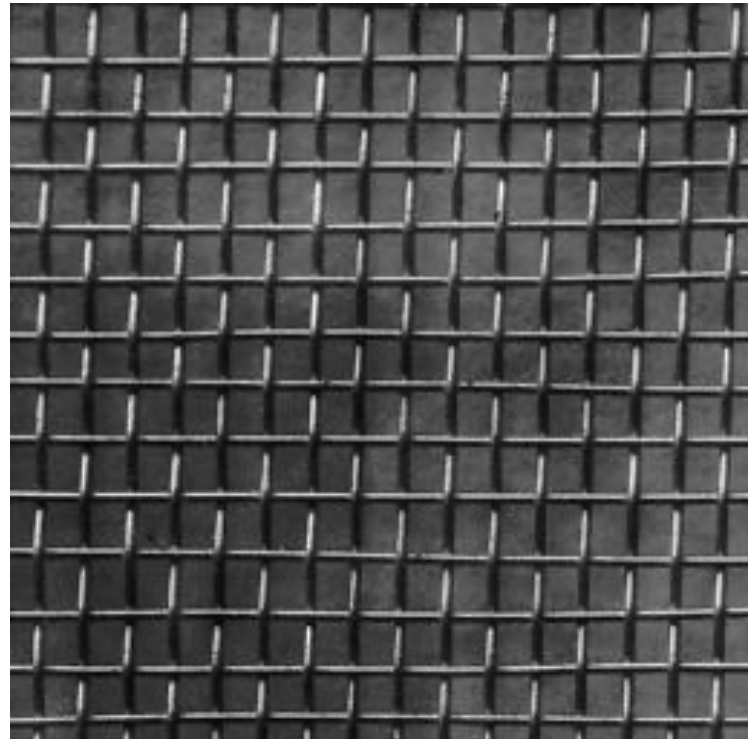




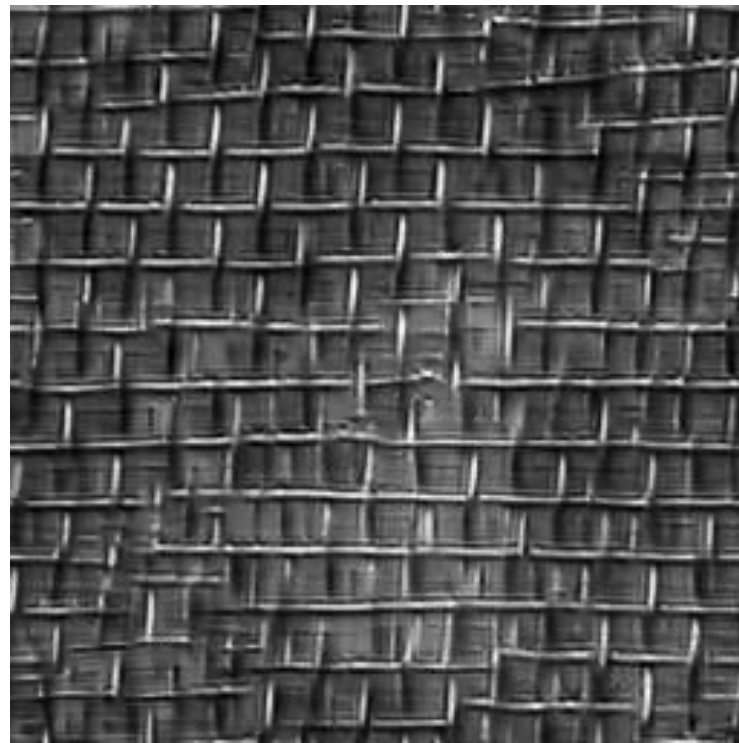


# Failures (Chernobyl Harvest)

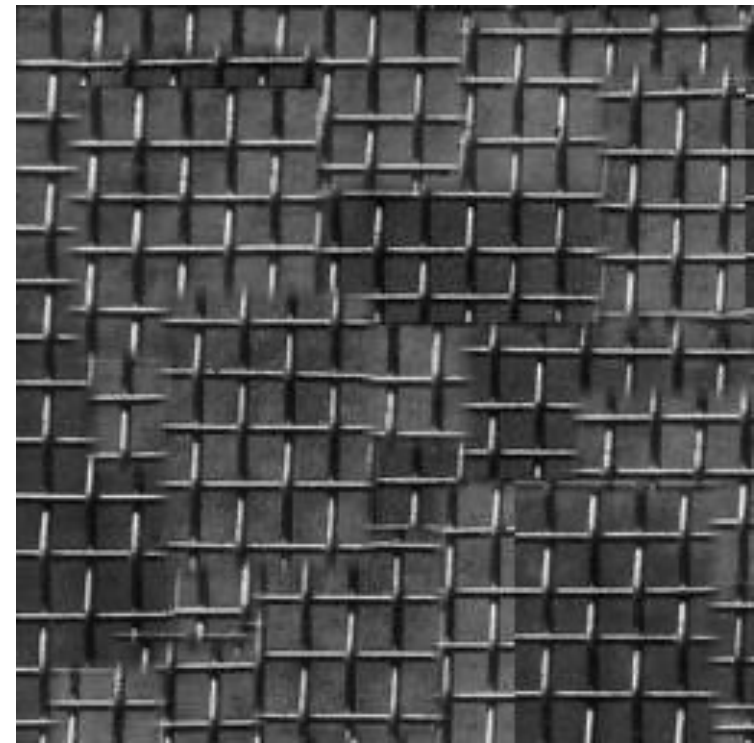




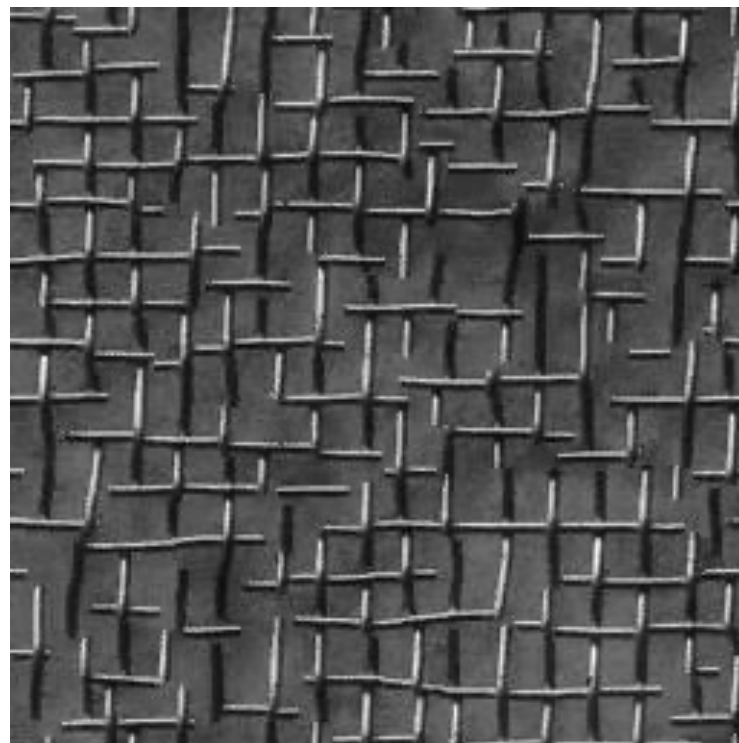
**input image**



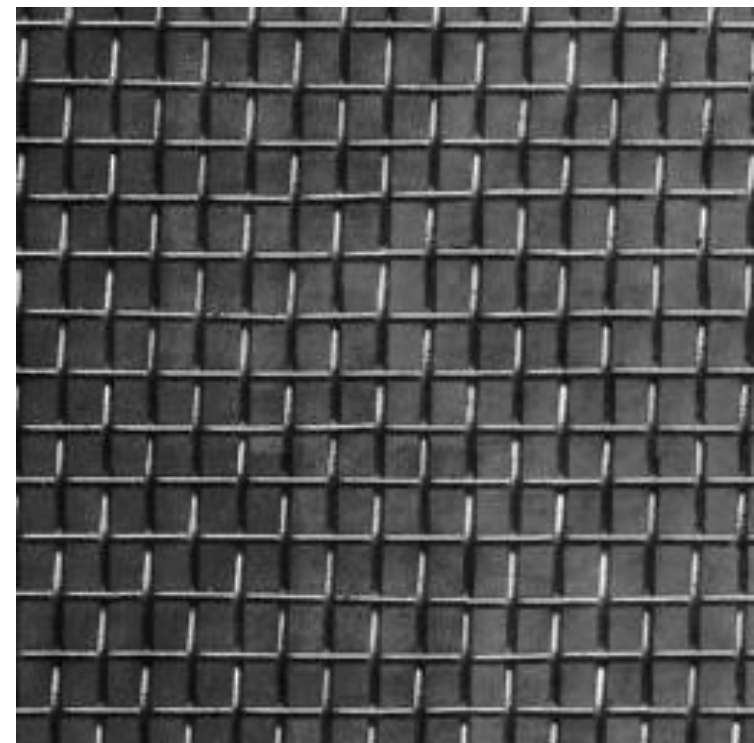
**Portilla & Simoncelli**



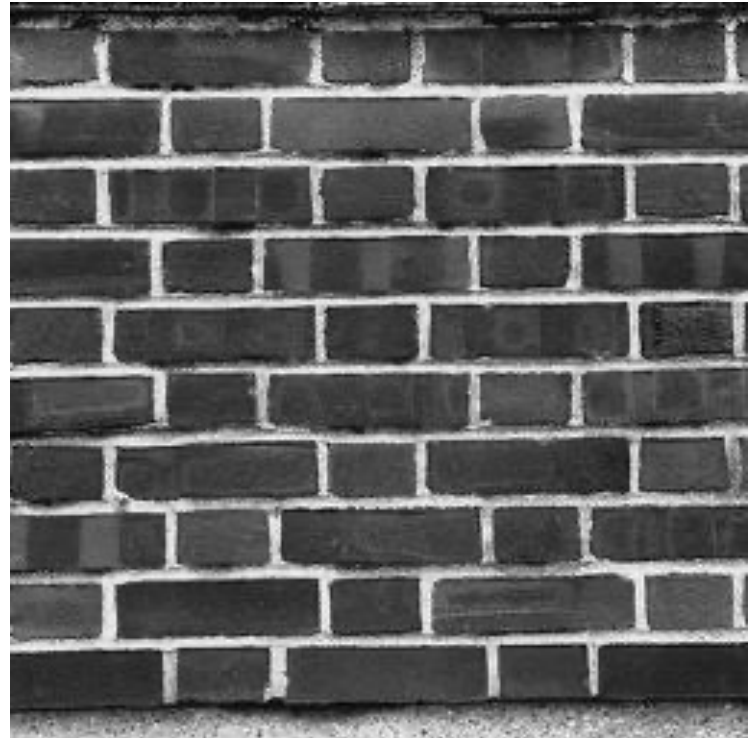
**Xu, Guo & Shum**



**Wei & Levoy**



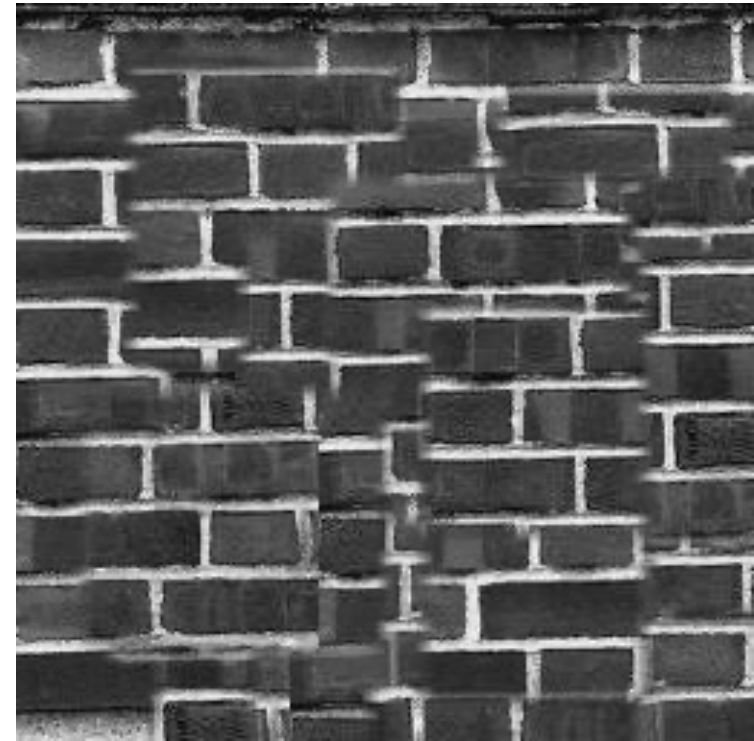
**Efros and Freeman**



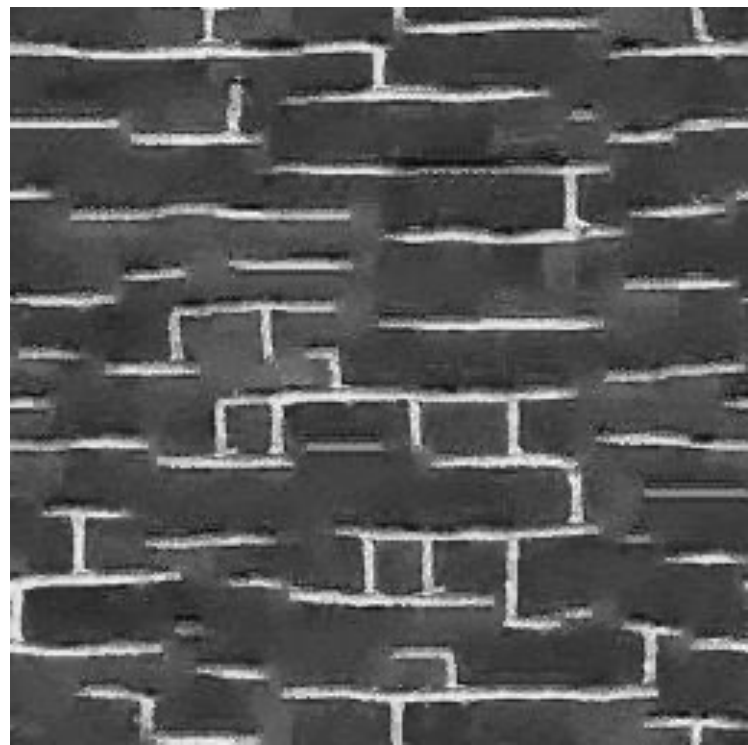
**input image**



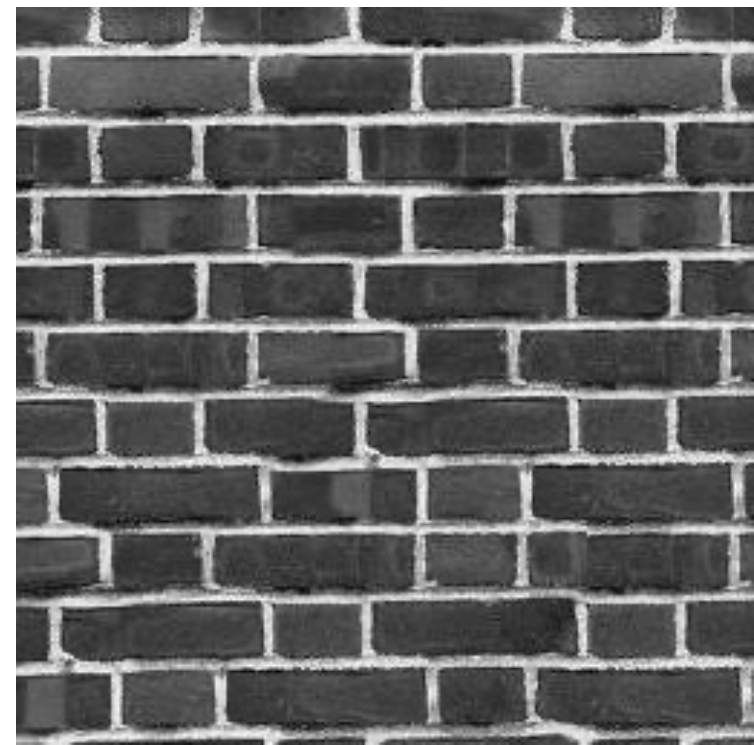
**Portilla & Simoncelli**



**Xu, Guo & Shum**



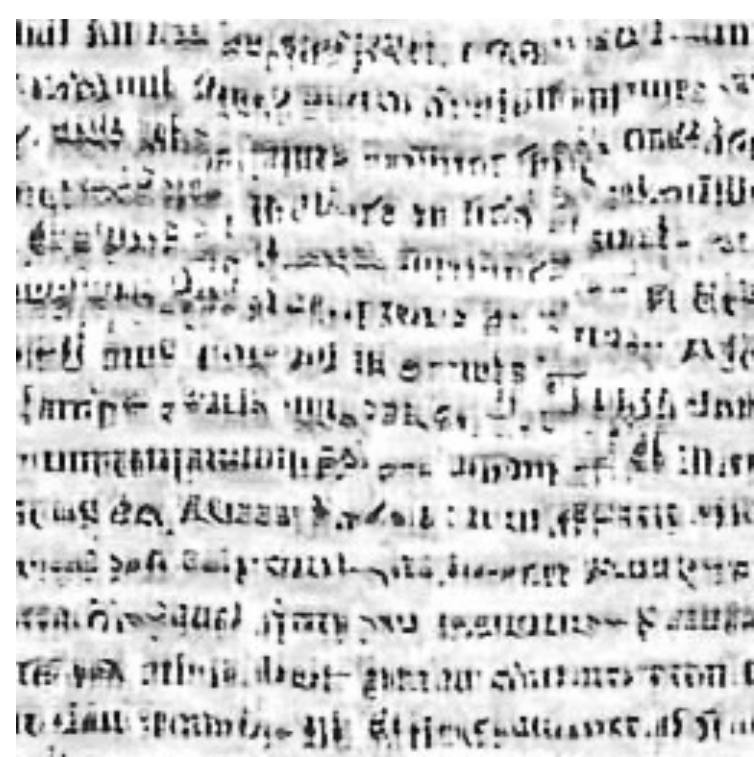
**Wei & Levoy**



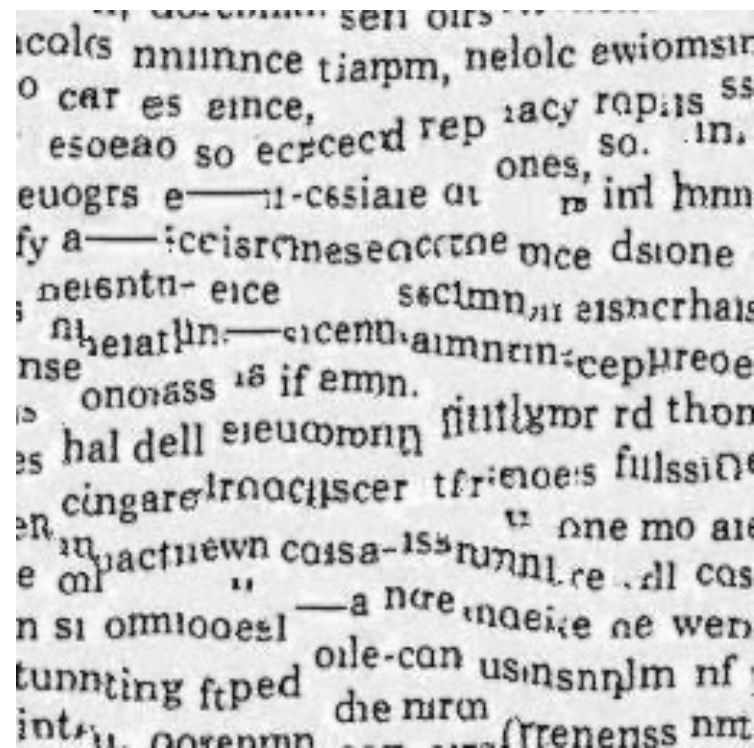
**Efros and Freeman**

... of a visual cortical neuron—the in  
... describing the response of that neuro  
... as a function of position—is perhap  
... functional description of that neuron.  
... seek a single conceptual and mathem  
... describe the wealth of simple-cell recep  
... and neurophysiologically<sup>1-3</sup> and inferred  
... especially if such a framework has the  
... it helps us to understand the functio  
... leeper way. Whereas no generic mo  
... ussians (DOG), difference of offset C  
... rivative of a Gaussian, higher derivati  
... function, and so on—can be expect  
... simple-cell receptive field, we noneth

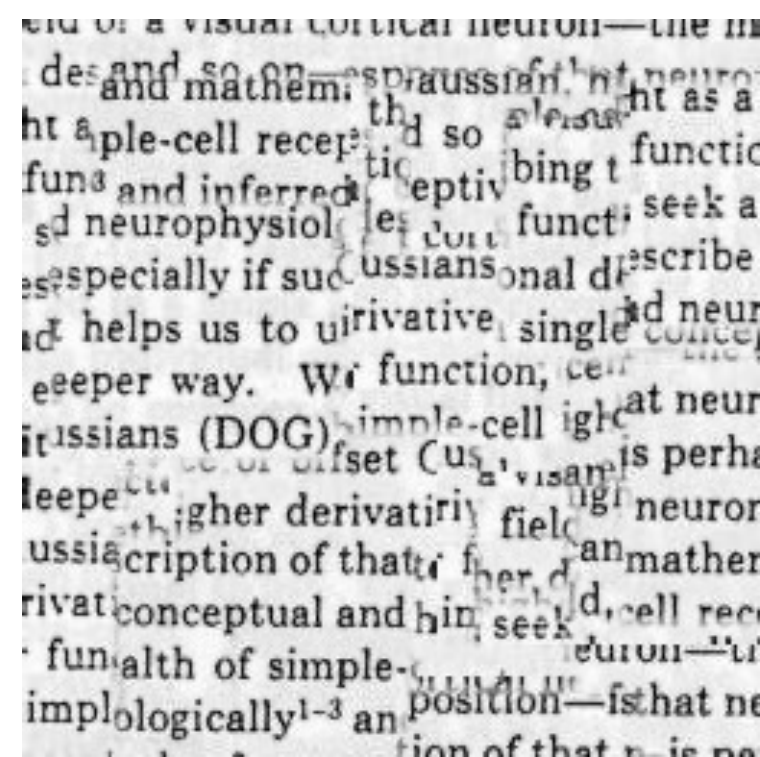
**input image**



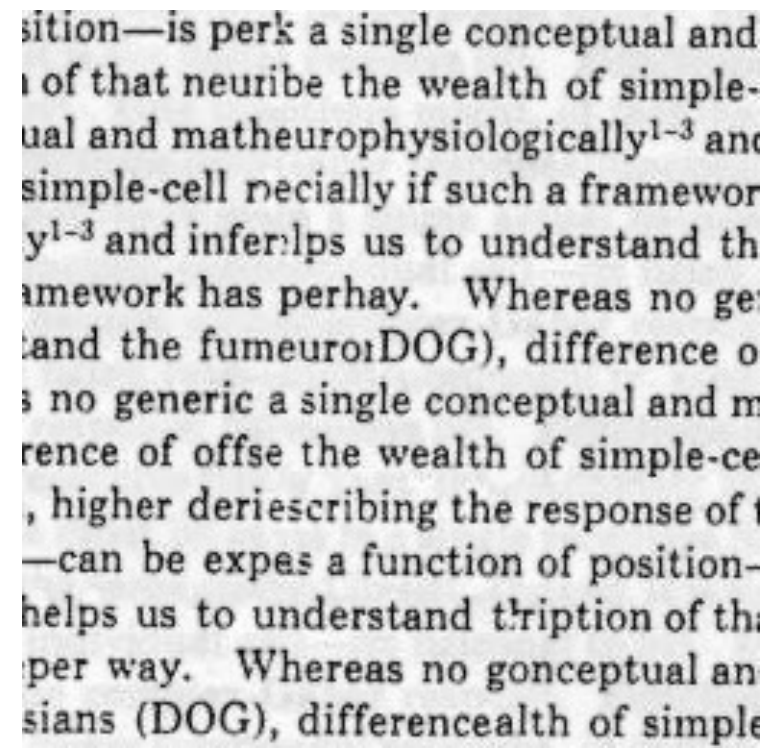
**Portilla & Simoncelli**



**Wei & Levoy**



**Xu, Guo & Shum**

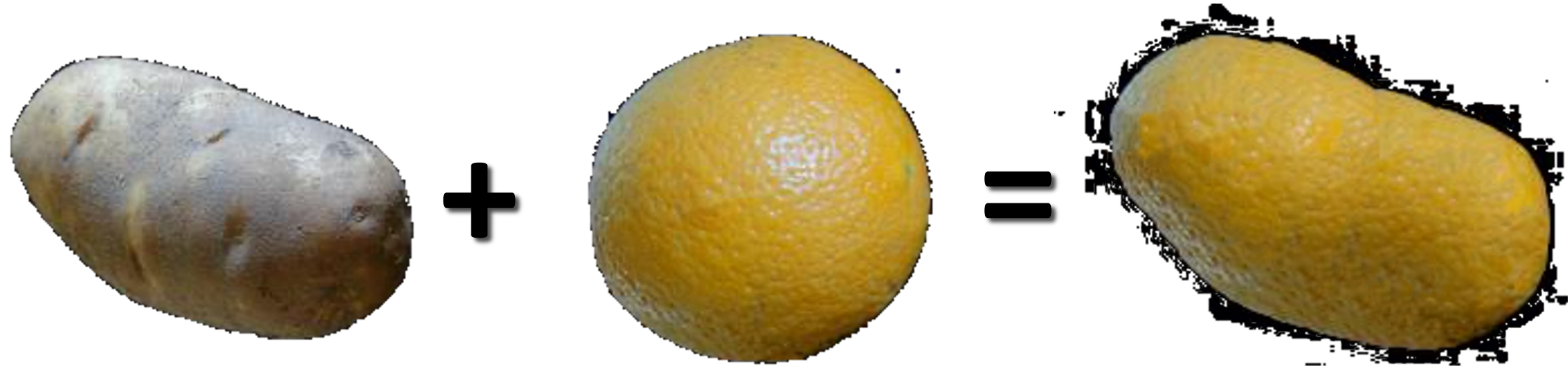


**Efros and Freeman**



# Application: Texture Transfer

- Try to explain one object with bits and pieces of another object:

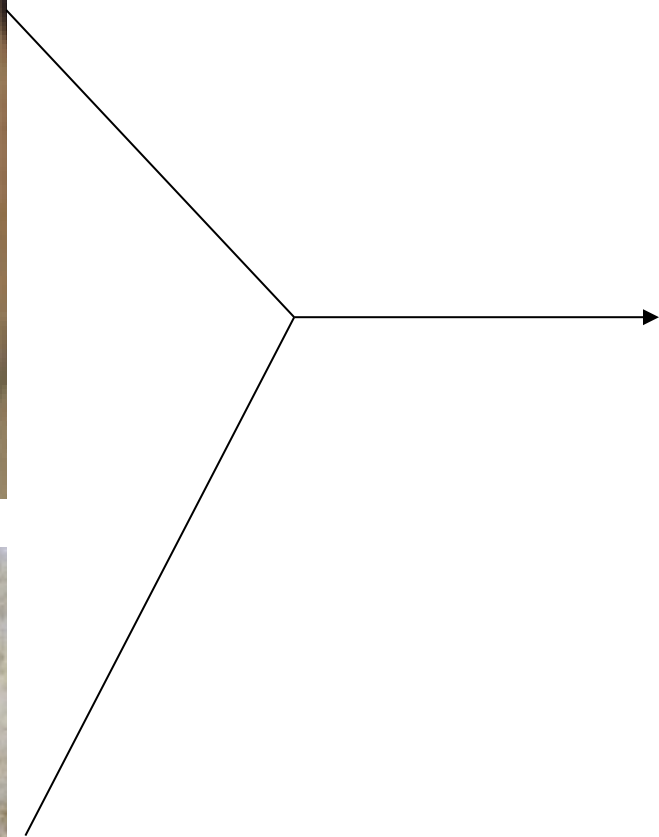


# Texture Transfer

Constraint



Texture sample



# Texture Transfer

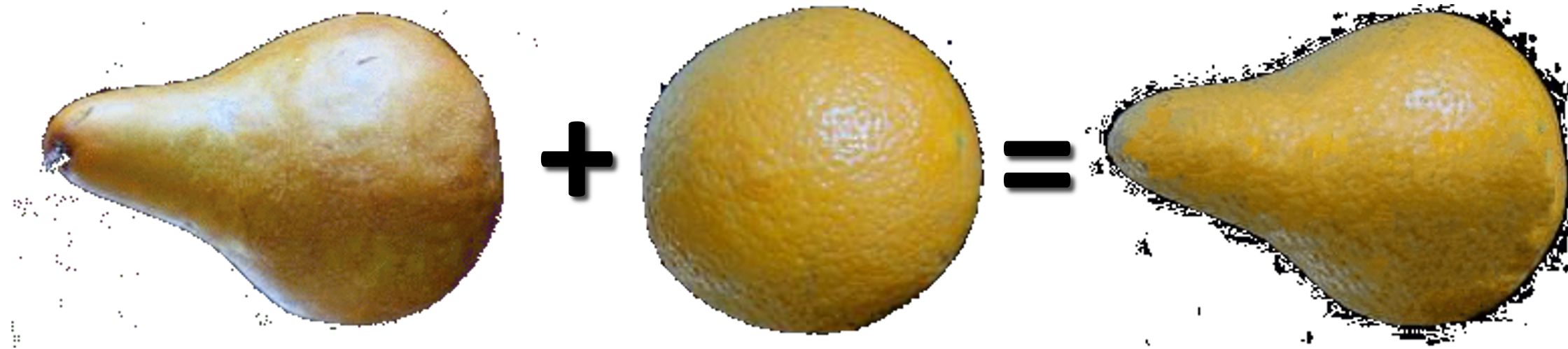
- Take the texture from one image and “paint” it onto another object



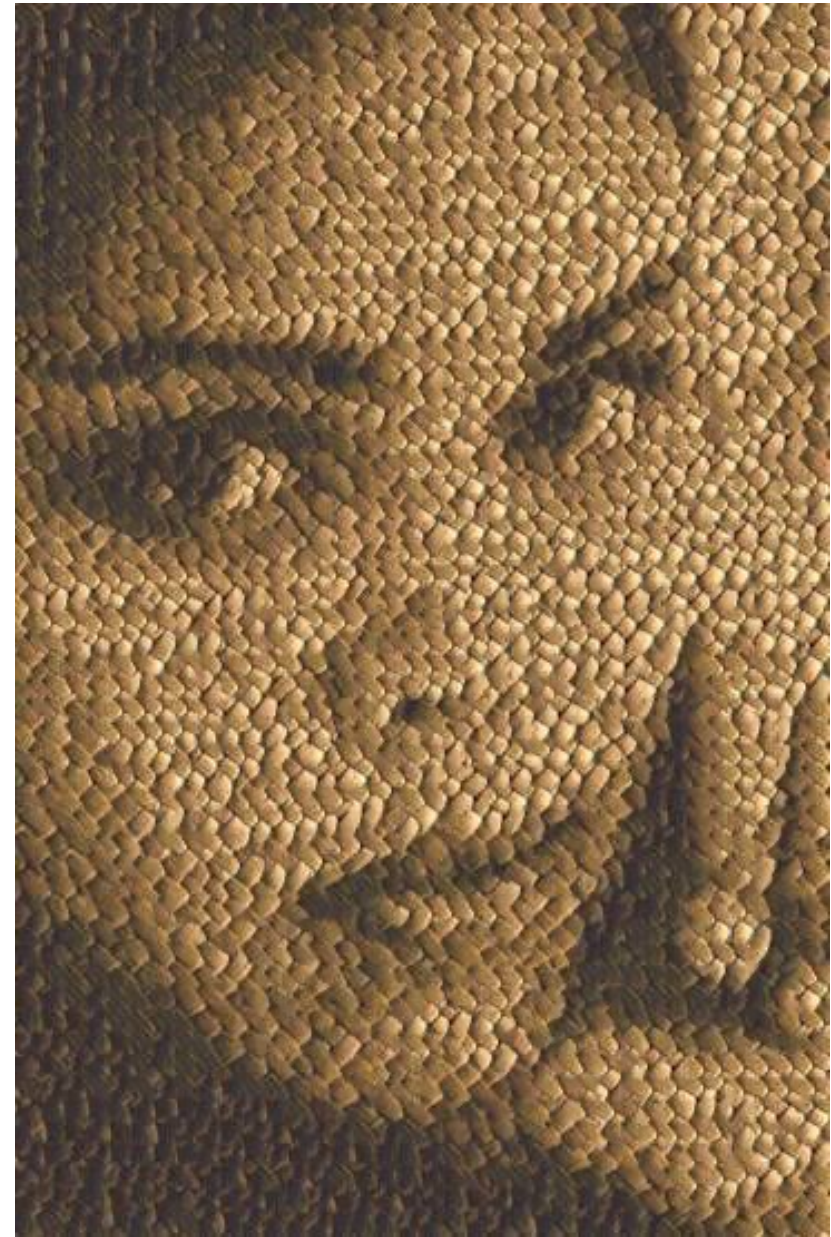
Same as texture synthesis, except an additional constraint:

1. Consistency of texture
2. Similarity to the image being “explained”

# Texture Transfer



# Texture Transfer



# Image Analogies

Aaron Hertzmann<sup>1,2</sup>

Chuck Jacobs<sup>2</sup>

Nuria Oliver<sup>2</sup>

Brian Curless<sup>3</sup>

David Salesin<sup>2,3</sup>

<sup>1</sup>**New York University**

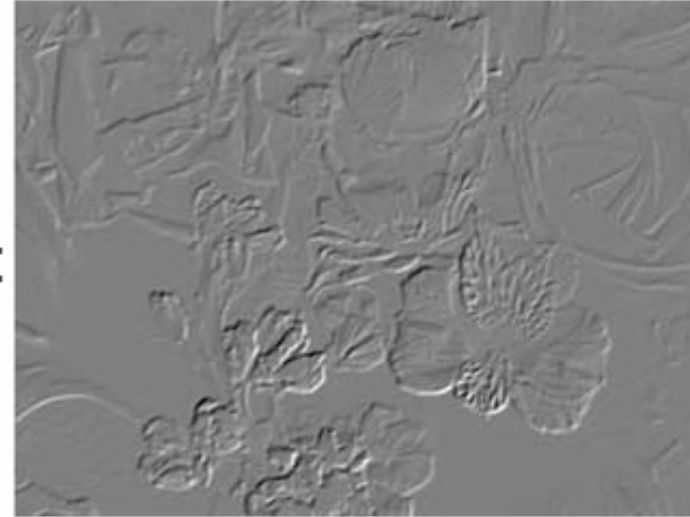
<sup>2</sup>**Microsoft Research**

<sup>3</sup>**University of Washington**

# Edge Filter



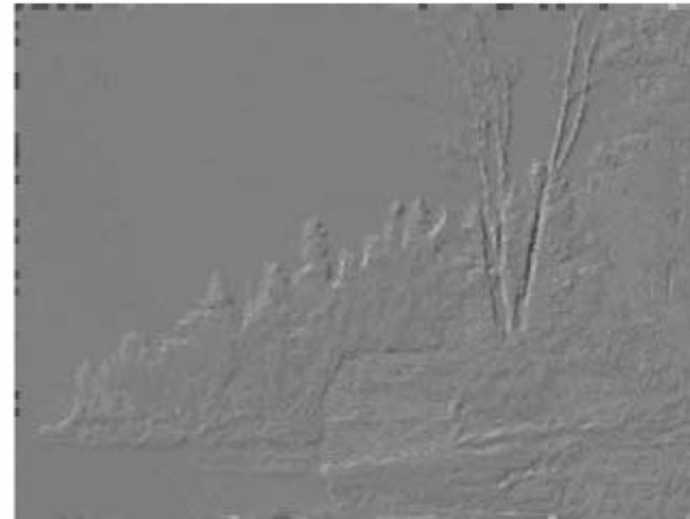
Unfiltered source ( $A$ )



Filtered source ( $A'$ )



Unfiltered target ( $B$ )



Filtered target ( $B'$ )

# Artistic Filters



A



A'



B



B'



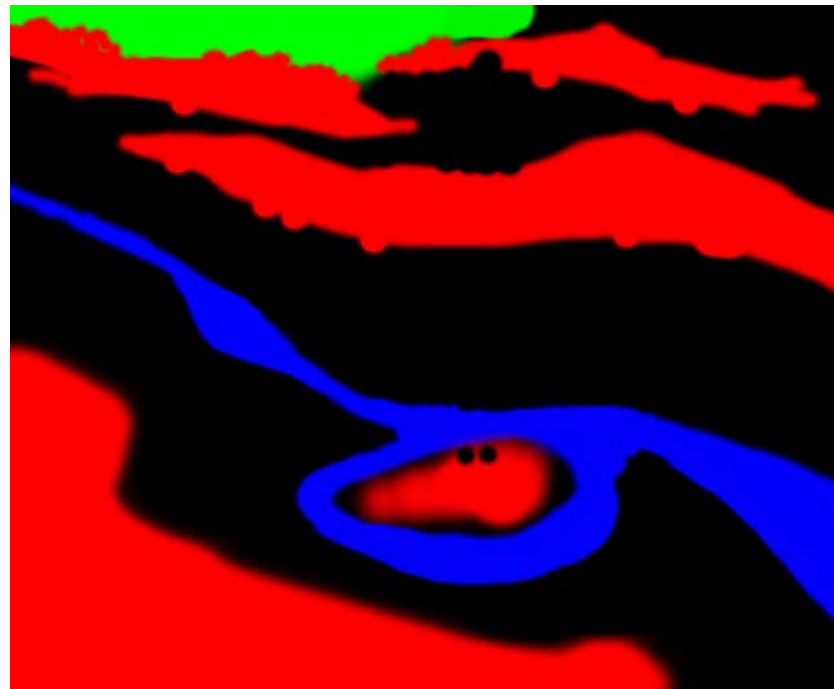
# Texture-by-numbers



A



A'

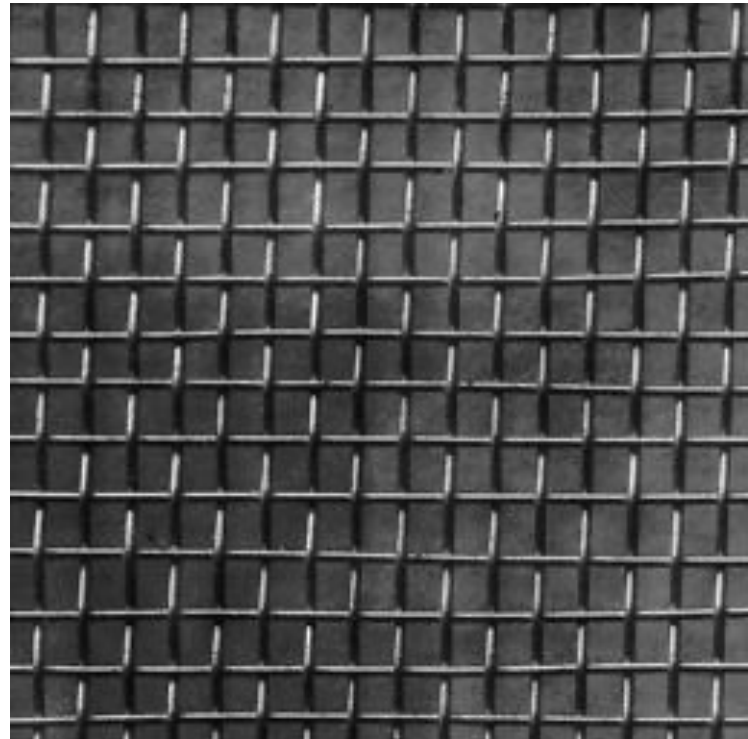


B

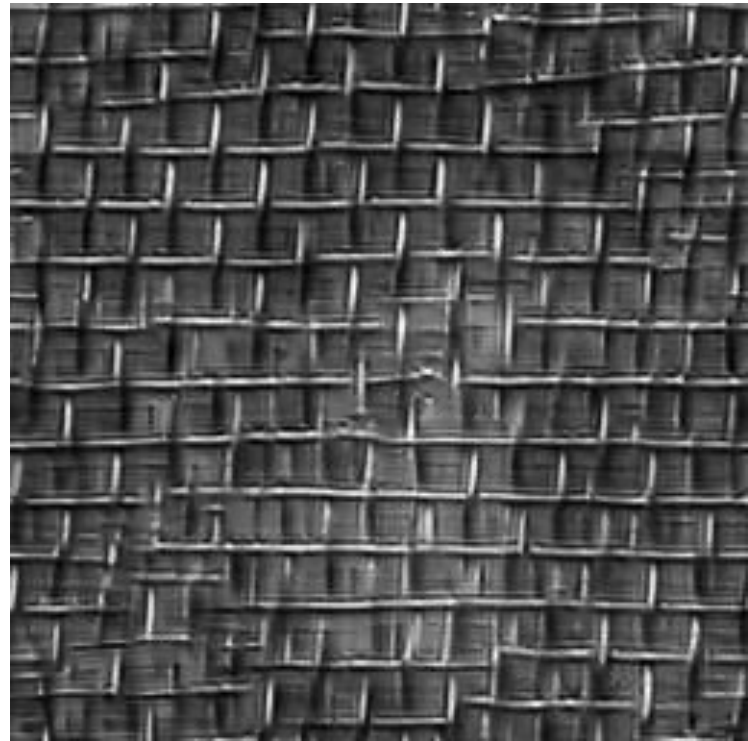


B'

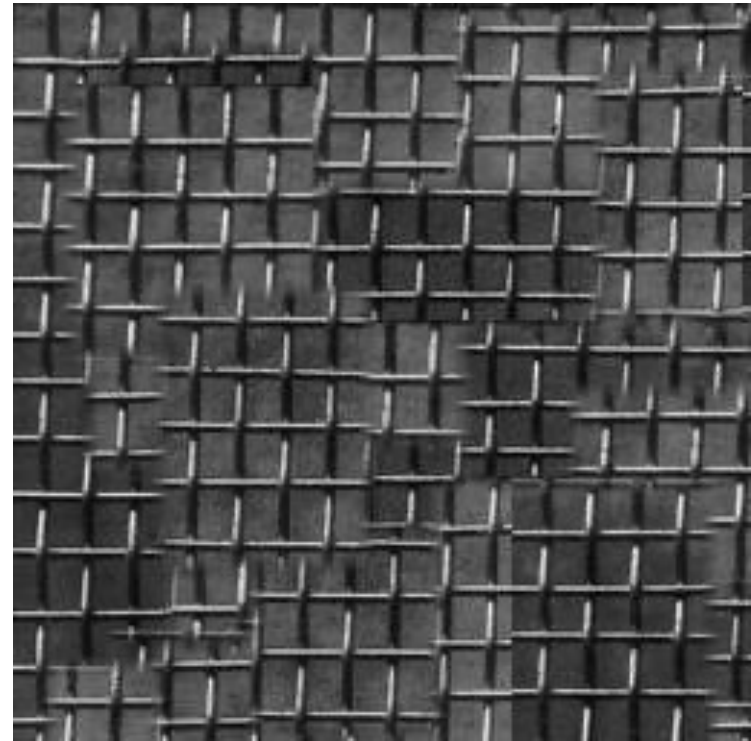
# Parametric Texture Synthesis



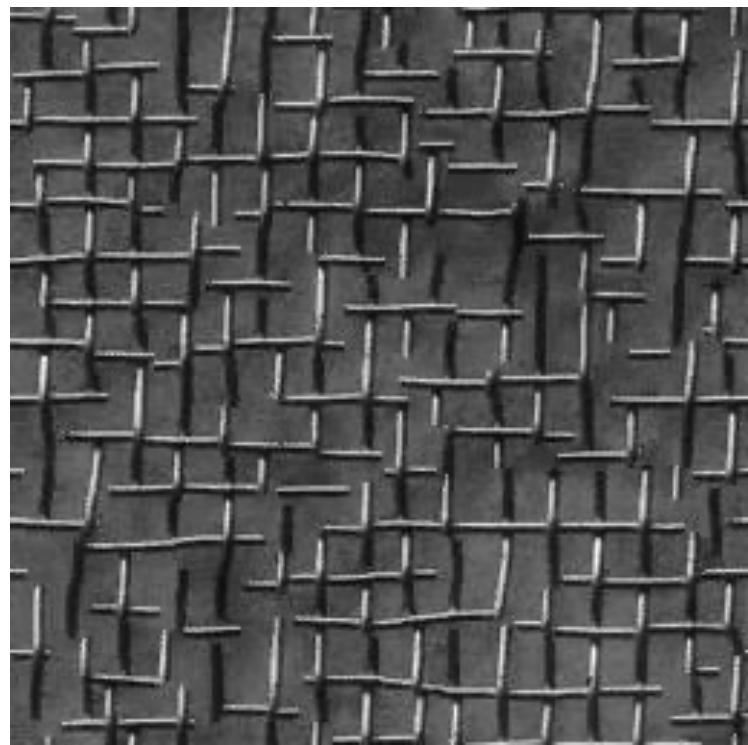
**input image**



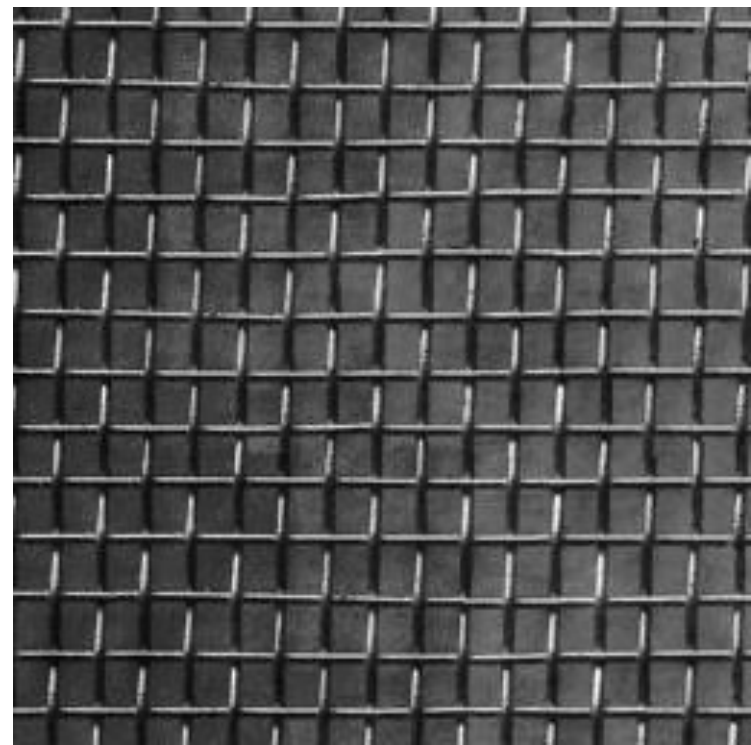
**Portilla & Simoncelli**



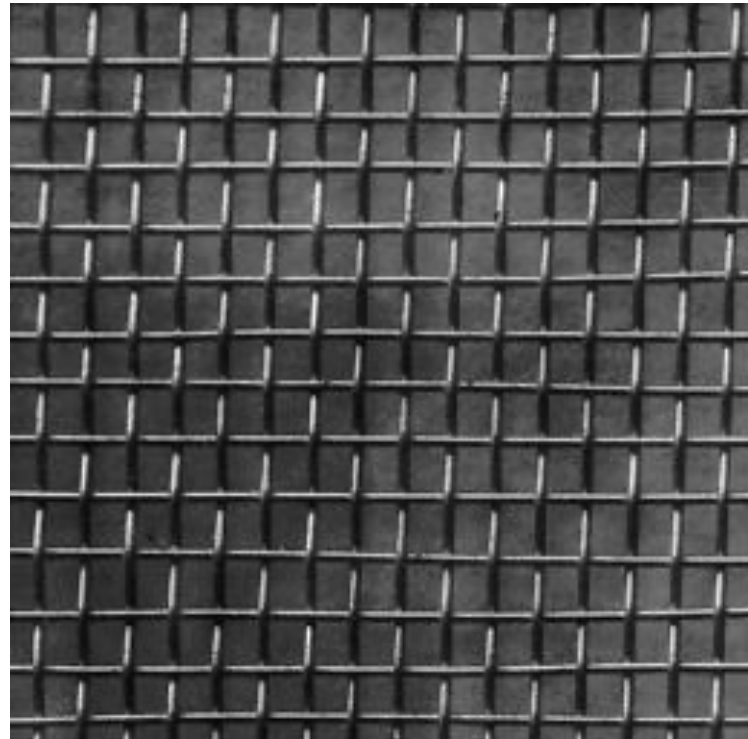
**Xu, Guo & Shum**



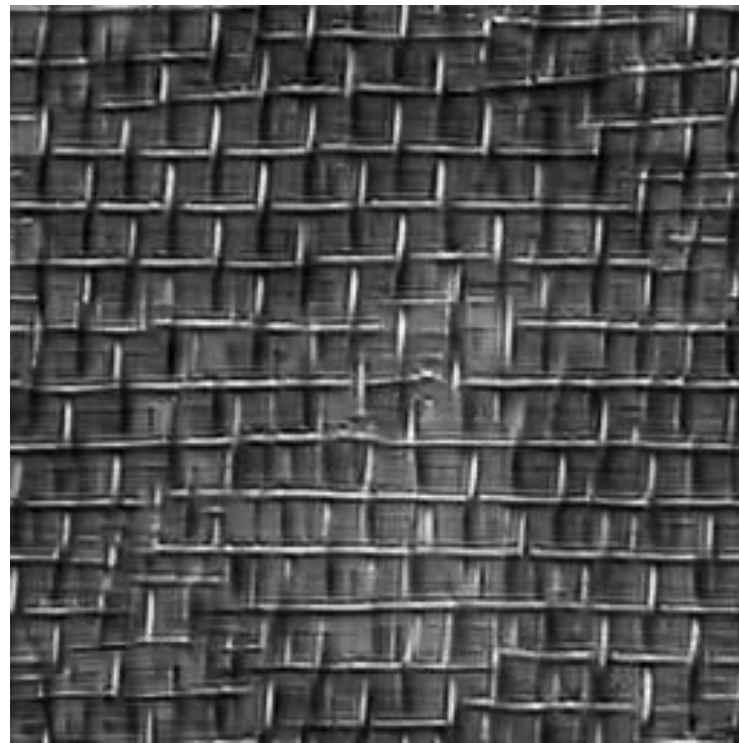
**Wei & Levoy**



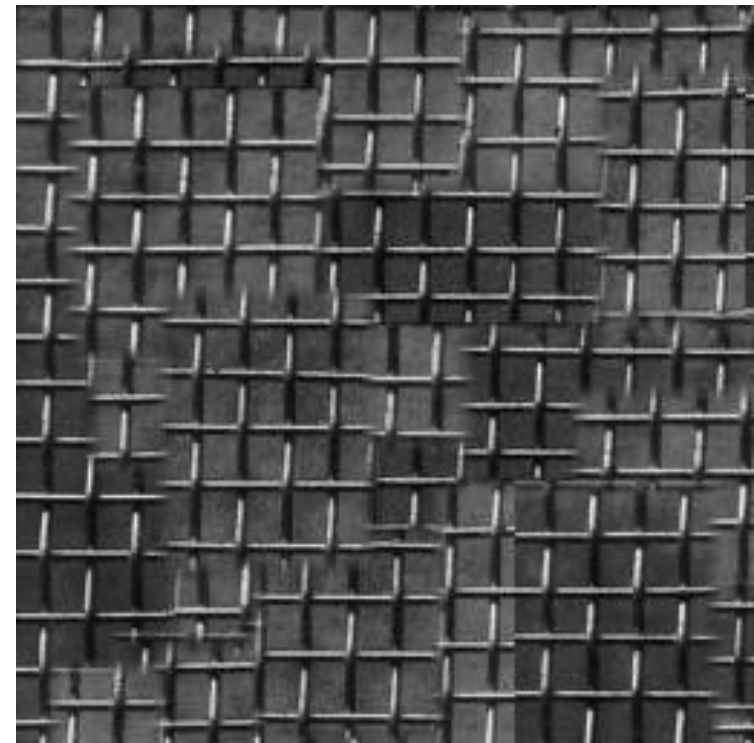
**Efros and Freeman**



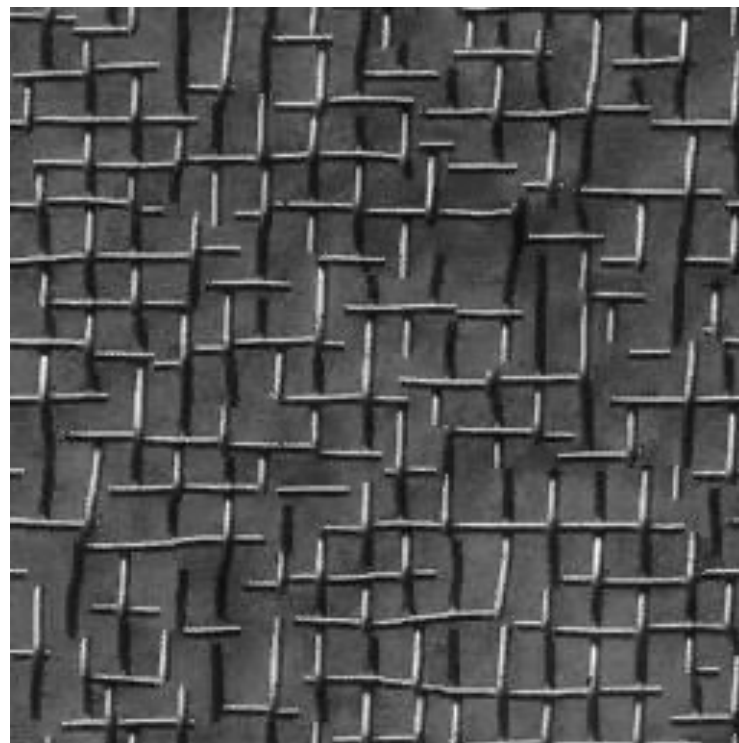
**input image**



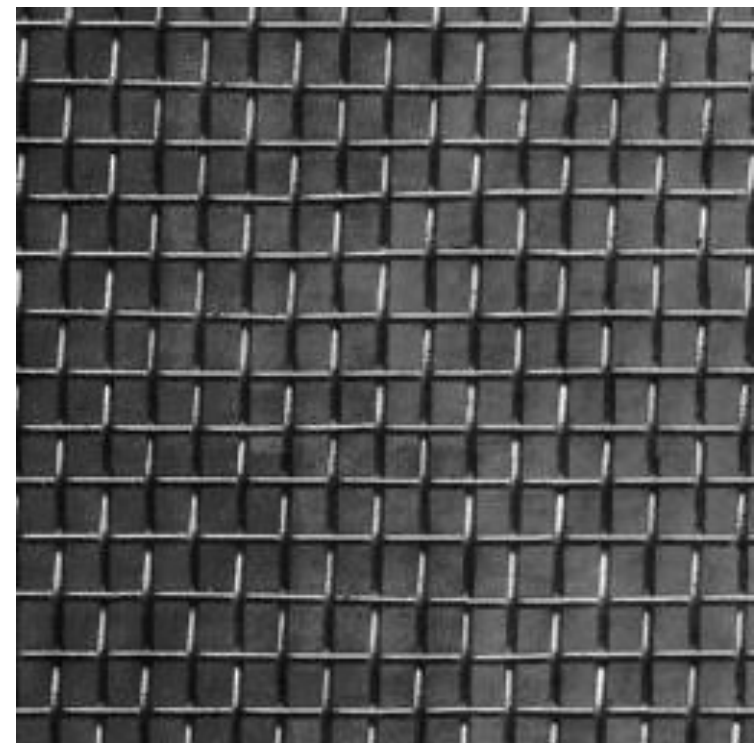
**Portilla & Simoncelli**



**Xu, Guo & Shum**

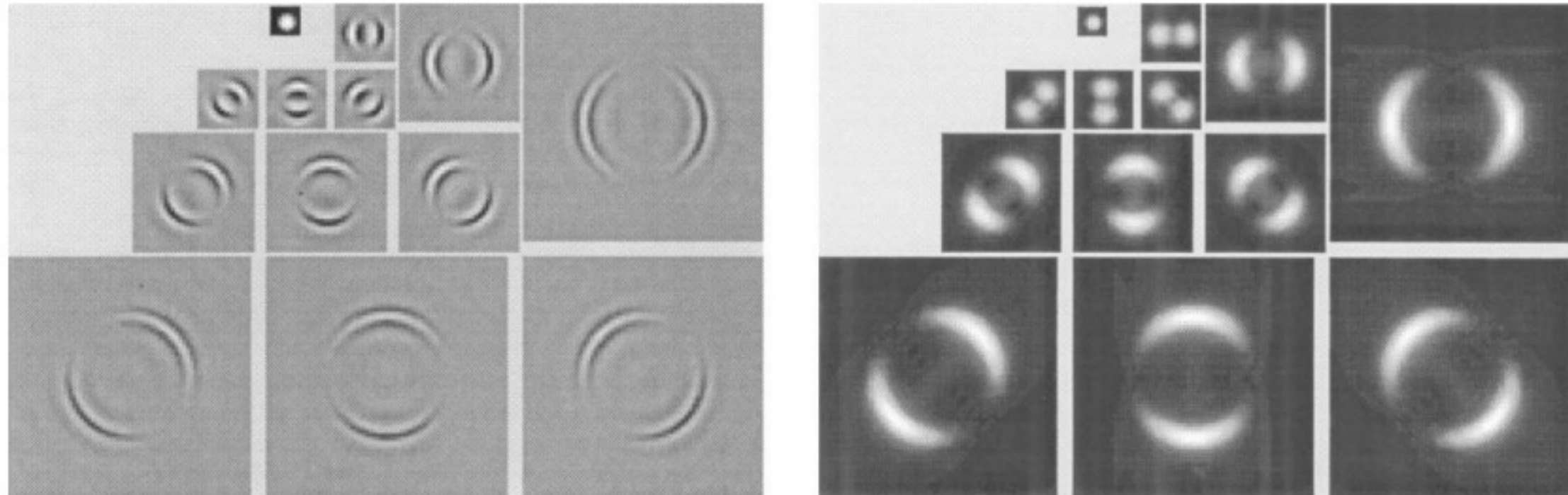


**Wei & Levoy**



**Efros and Freeman**

# Parametric Texture Synthesis



Histogram and cross-channel correlation using wavelet basis

Statistics  $\longrightarrow \mathcal{E}(\phi_j(y)) \approx \mathcal{E}(\phi_j(\hat{y}))$

Wavelet features

A Parametric Texture Model Based on Joint Statistics of Complex Wavelet Coefficients

Portilla and Simoncelli, IJCV 1999

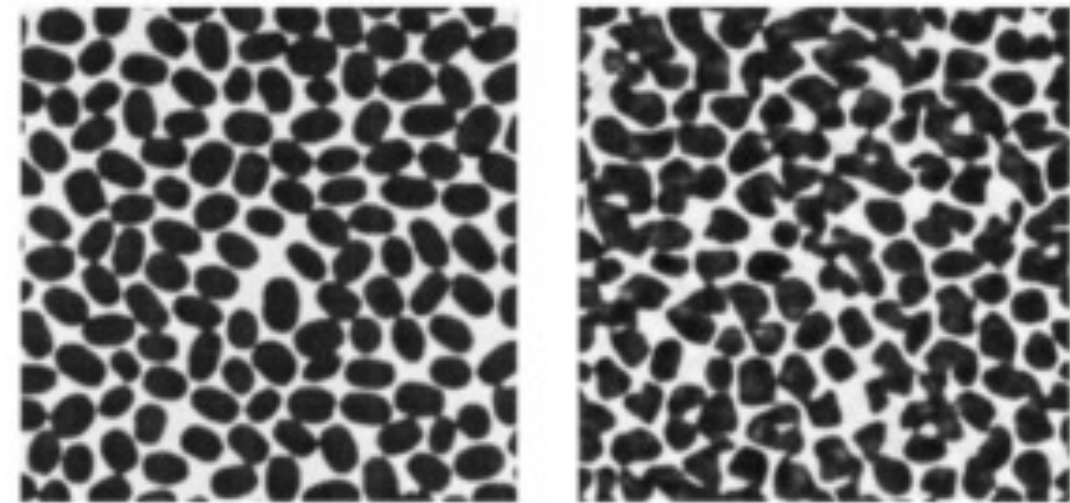
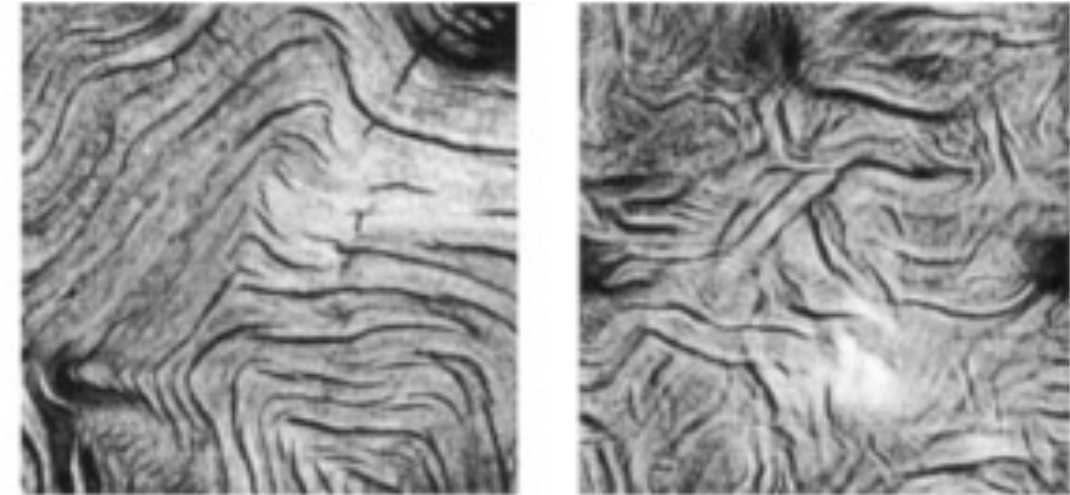
# Parametric Texture Synthesis

## Objective function

Given input texture  $y$ , feature descriptor  $\phi$ ,  
and statistics summary function  $\mathcal{E}$

We aim to optimize the output image  $\hat{y}$

$$\hat{y}^* = \arg \min_{\hat{y}} \|\mathcal{E}(\phi_j(\hat{y})) - \mathcal{E}(\phi_j(y))\|$$



Original  $y$

Output  $\hat{y}$

# Deep Learning Version

Gram matrix:

- Cross Correlation of CNN features
- Invariant to the feature locations

$$V = [v_1, v_2, \dots, v_n]$$

$$G_{ij} = \langle v_i, v_j \rangle \quad G = V^T V$$

$$Gram^{(j)}(x) = \frac{1}{C_j H_j W_j} \sum_{h=1}^{H_j} \sum_{w=1}^{W_j} \phi_j(x)_{h,w,c} \phi_j(x)_{h,w,c'}$$

h, w: pixel locations index

c: channel index

H, W: height and width of feature map

C: the number of total channels

# Style Reconstruction (Style Loss)

$$\left| \text{Gram} \left( \begin{array}{c} \hat{y} \\ \text{optimized output} \end{array} \right) - \text{Gram} \left( \begin{array}{c} y \\ \text{style image} \end{array} \right) \right|$$

Gram = Gram Matrix of a deep network's features (e.g., ImageNet classifier)

## Style Loss

$$\arg \min_{\hat{y}} \sum_j^M \lambda_j \left\| \text{Gram}^{(j)}(\hat{y}) - \text{Gram}^{(j)}(y) \right\|^2$$

weight                      (j)-th layer



Portilla & Simoncelli



original



pool4



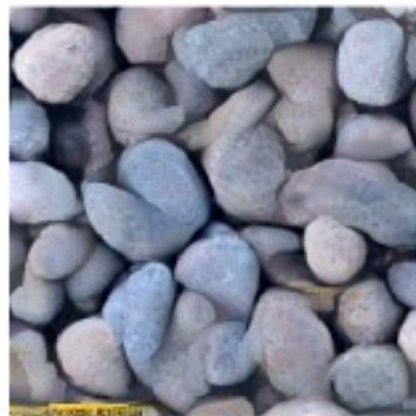
pool3



A ~1k parameters



~10k parameters



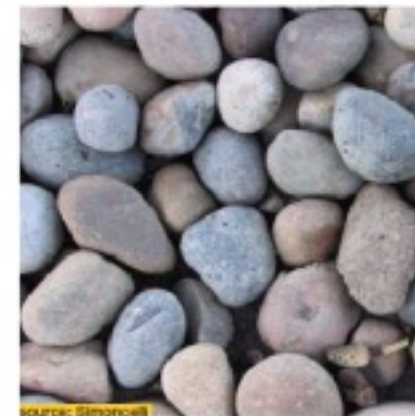
~177k parameters



~852k parameters

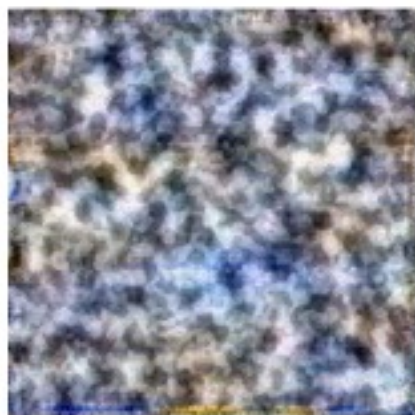


original



Number of parameters

B conv1



conv2



conv3



conv4



conv5

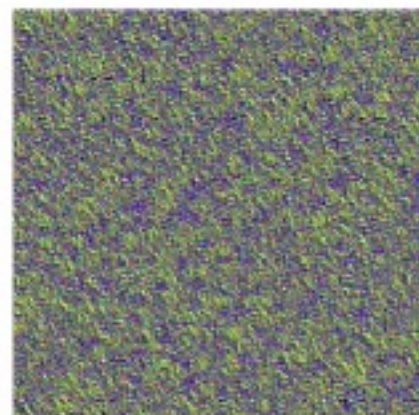


Different layers

C conv1\_1



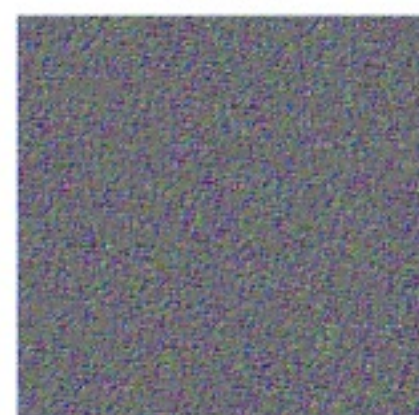
pool1



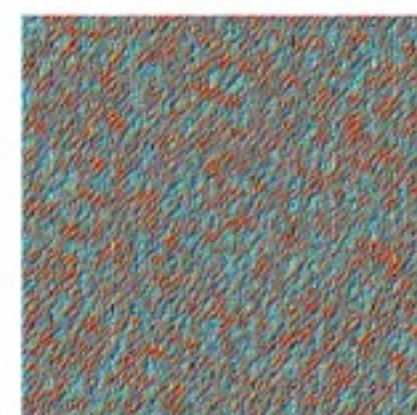
pool2



pool3



pool4



The same network architecture with random weights

# Neural Style Transfer



content image

+



style image

=



output result

# Content Reconstruction (Perceptual Loss)

$$\left| F\left(\overset{\hat{y}}{\text{optimized output}}\right) - F\left(\overset{x}{\text{content image}}\right) \right|$$

F is a deep network (e.g., ImageNet classifier)

## Content Loss

$$\arg \min_{\hat{y}} \sum_i^N \overset{\text{weight}}{\lambda_i} \left\| \overset{(i)\text{-th layer}}{F^{(i)}}(\hat{y}) - F^{(i)}(x) \right\|_1$$

# Content Reconstruction (Perceptual Loss)



Conv1\_2

Conv2\_2

Conv3\_2

Conv4\_2

Conv5\_2

# Neural Style Transfer

$$|\text{Gram}(\hat{y}) - \text{Gram}(y)|$$

optimized output                      style image

$$+ |\text{F}(\hat{y}) - \text{F}(x)|$$

optimized output                      content image

$$\arg \min_{\hat{y}} \mathcal{L}_{\text{style}}(\hat{y}, y) + \lambda \mathcal{L}_{\text{content}}(\hat{y}, x)$$



# Different Initializations





# Fast Neural Style Transfer

- Optimization-based method

$$\arg \min_{\hat{y}} \mathcal{L}_{\text{style}}(\hat{y}, y) + \lambda \mathcal{L}_{\text{content}}(\hat{y}, x)$$

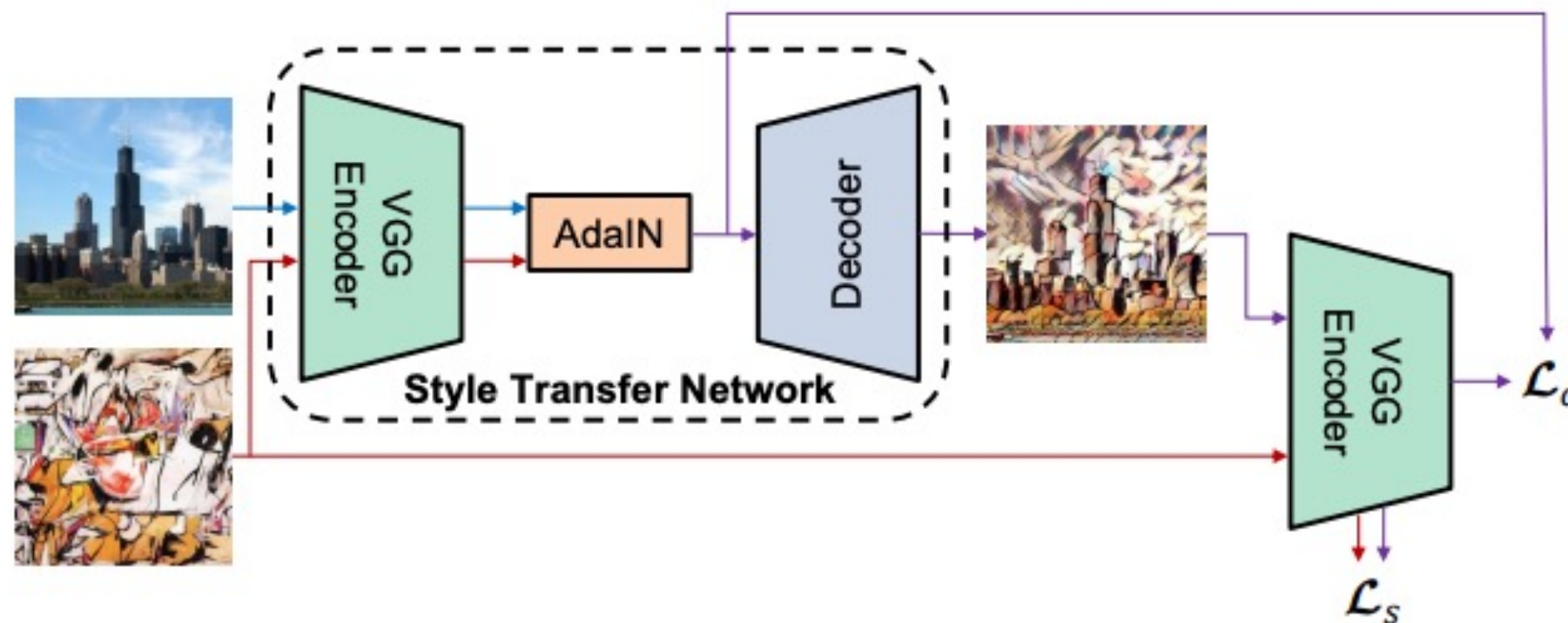
- Feedforward network

$$\arg \min_G \mathbb{E}_x \mathcal{L}_{\text{style}}(G(x), y) + \lambda \mathcal{L}_{\text{content}}(G(x), x)$$

# Arbitrary Style Transfer with AdaIN

- Feedforward network with any style

$$\arg \min_G \mathbb{E}_{x,y} \mathcal{L}_{\text{style}}(G(x,y), y) + \lambda \mathcal{L}_{\text{content}}(G(x,y), x)$$



# Arbitrary Style Transfer with AdaIN



Neural Style Transfer  
vs.  
Image-to-Image Translation

Input



Style Image I



Style image II



Entire collection



CycleGAN

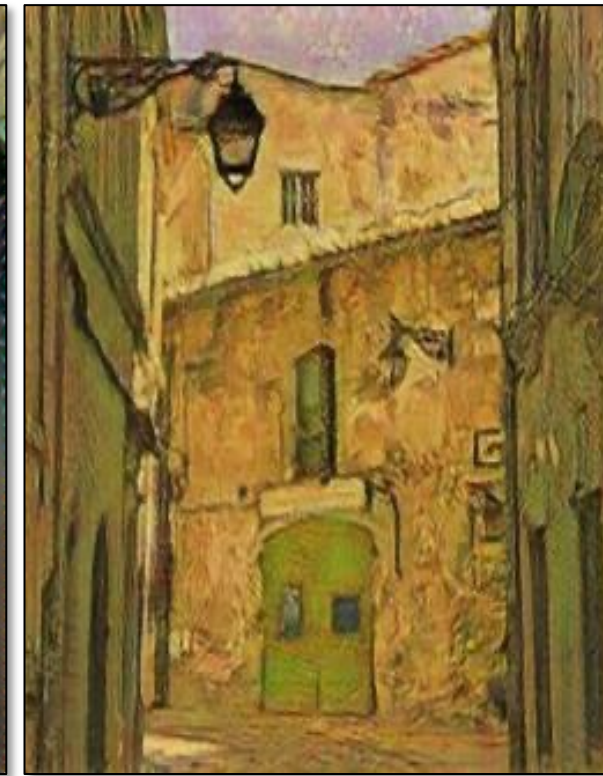


Photo → Van Gogh

Input



Style image I



Style image II



Entire collection



CycleGAN



horse → zebra

# Photo Style Transfer

# Deep Photo Style Transfer



(a) Reference style image

(b) Input image

(c) Neural Style (distortions)

(d) Our result

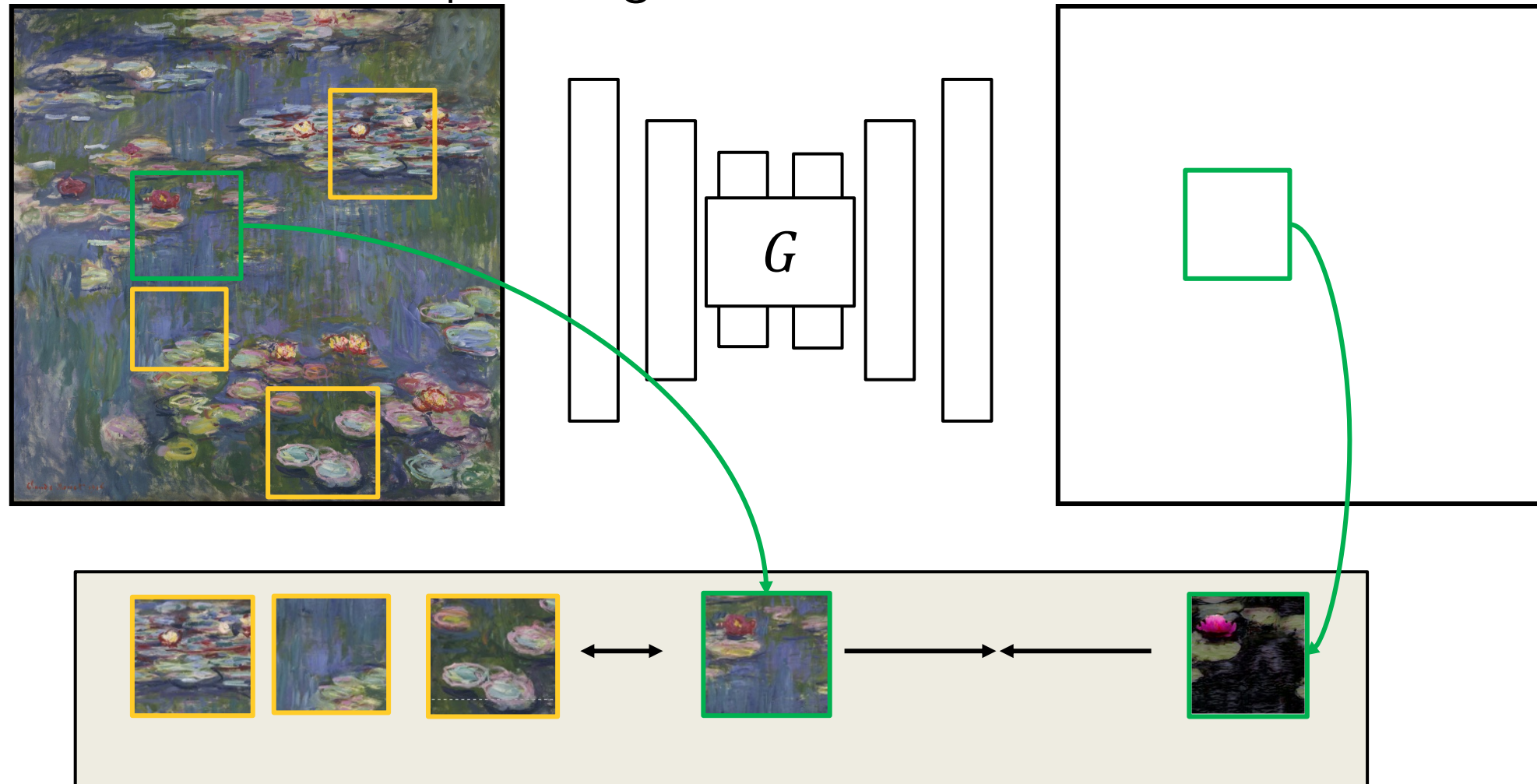
Local color transfer? (hard to transfer texture)

# Single Image Translation



# Single Image Translation

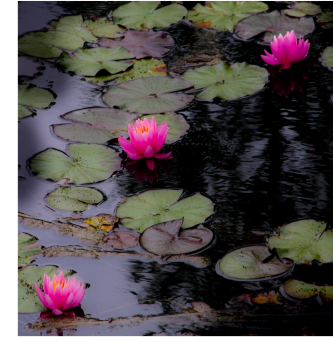
Claude Monet's painting



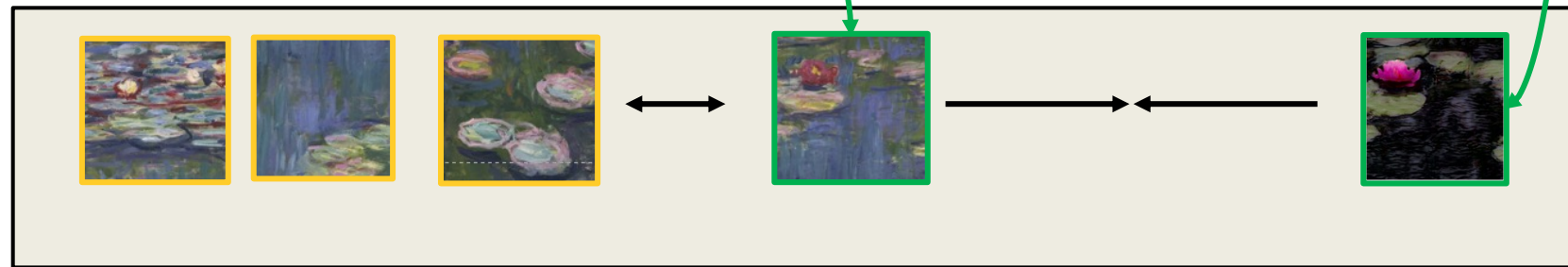
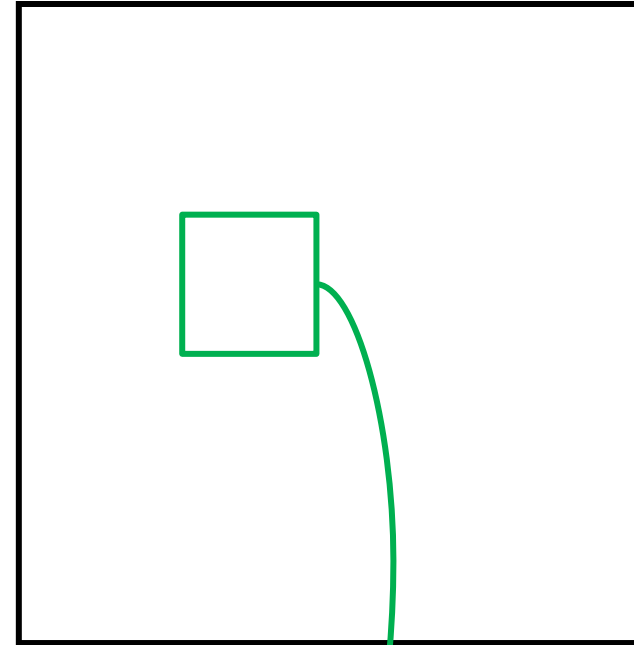
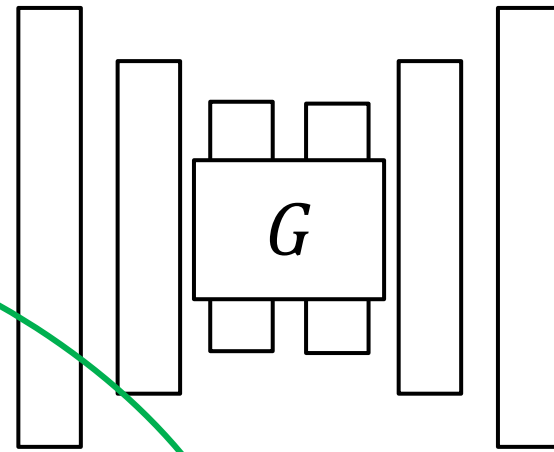
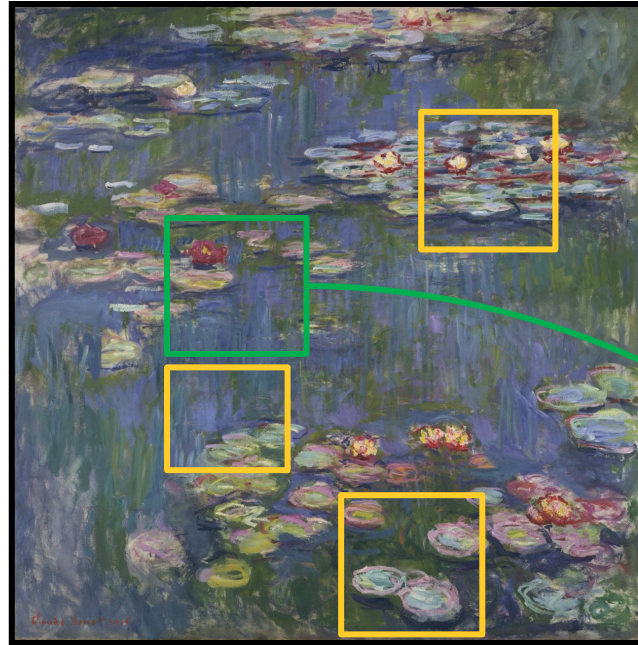
Internal contrastive loss is well-suited for single image translation.  
Also see InGAN (Shocher et al., ICCV'19), SinGAN (Shaham et al., ICCV'19)

# Single Image Translation

Reference photo



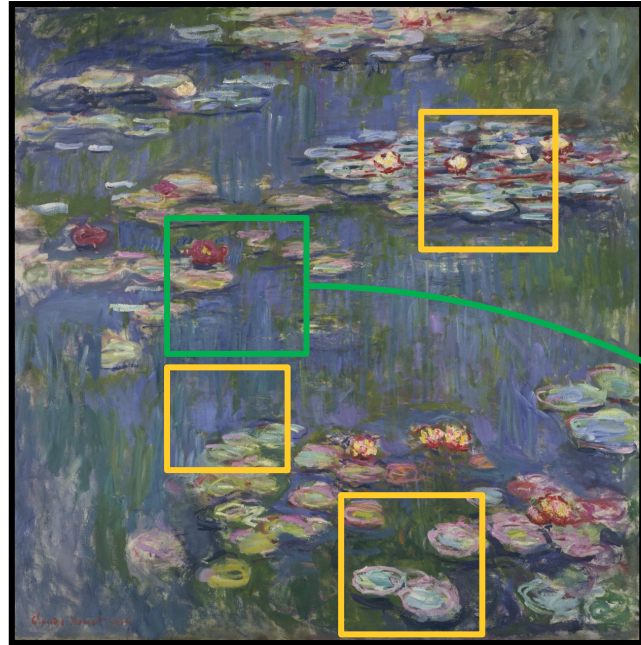
Claude Monet's painting



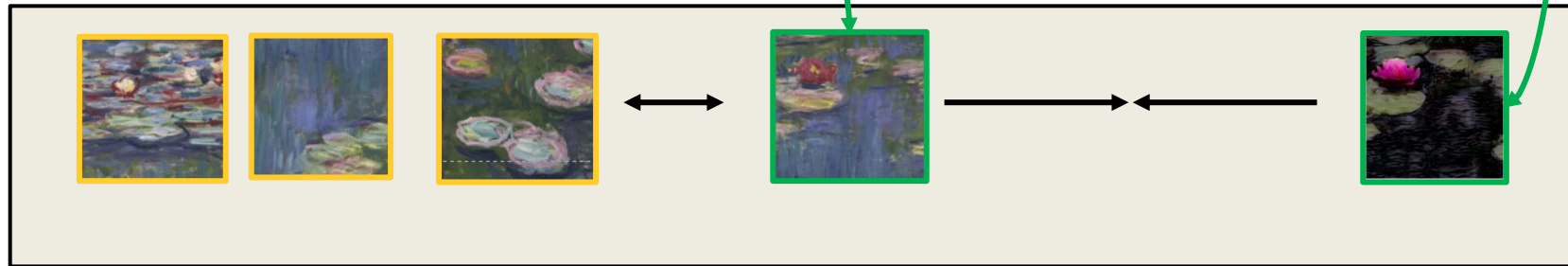
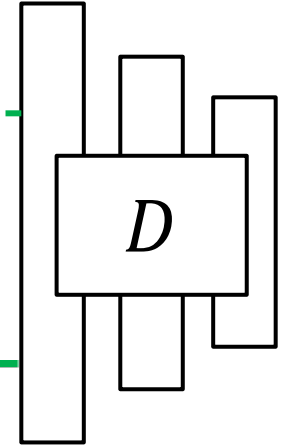
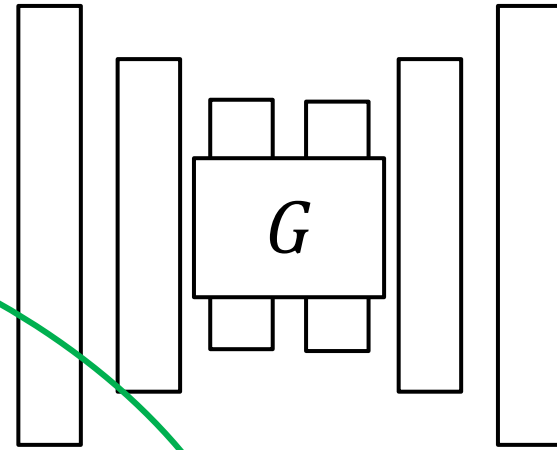
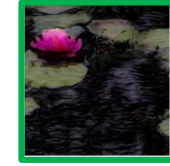
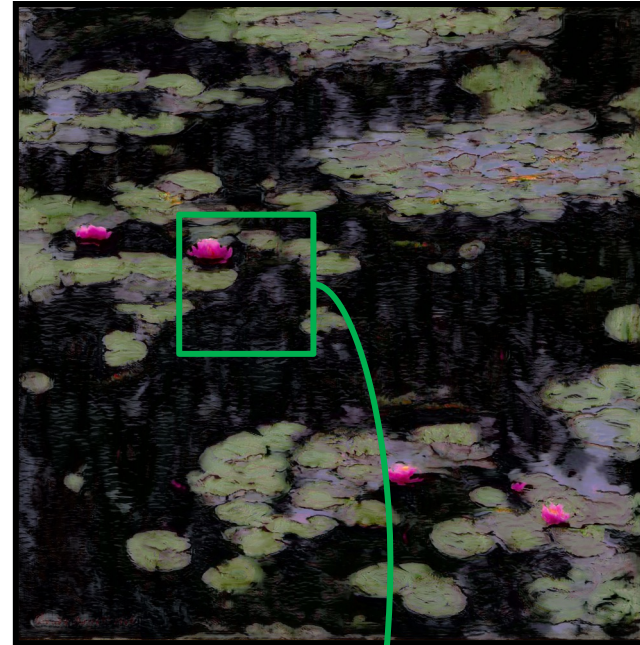
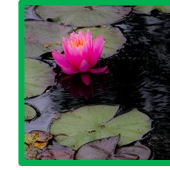
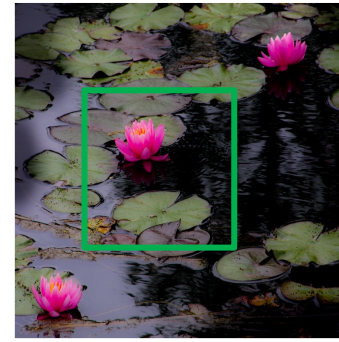
Internal contrastive loss is well-suited for single image translation.  
Also see InGAN (Shocher et al., ICCV'19), SinGAN (Shaham et al., ICCV'19)

# Single Image Translation

Claude Monet's painting



Reference photo



Internal contrastive loss is well-suited for single image translation.  
Also see InGAN (Shocher et al., ICCV'19), SinGAN (Shaham et al., ICCV'19)



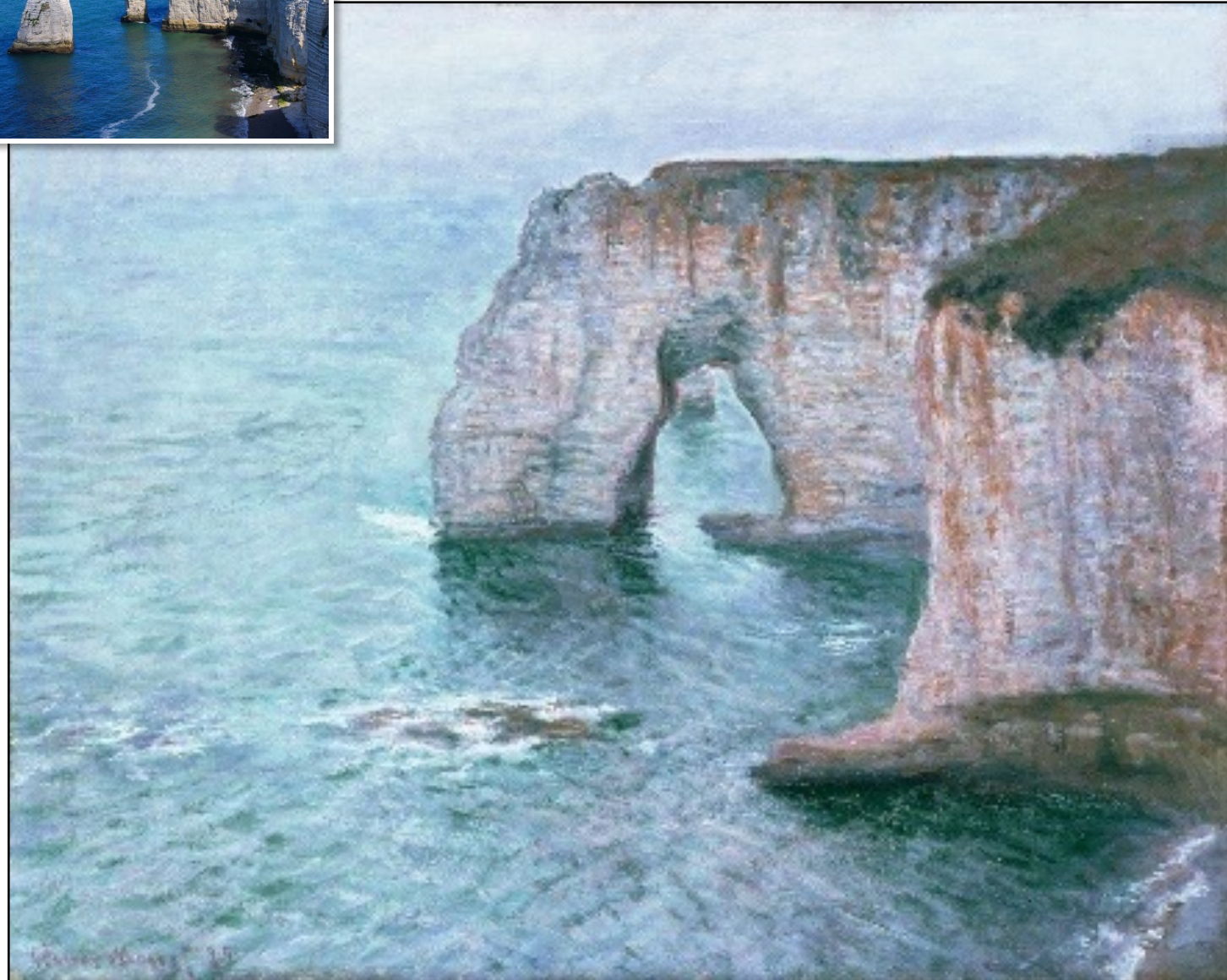
Painting

Reference



Painting

Reference



Painting



Gatys et al. CVPR'16

Reference



Painting



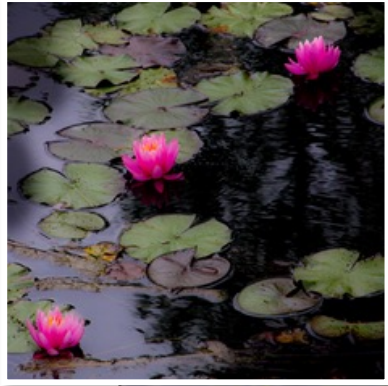
Single Image translation (CUT)



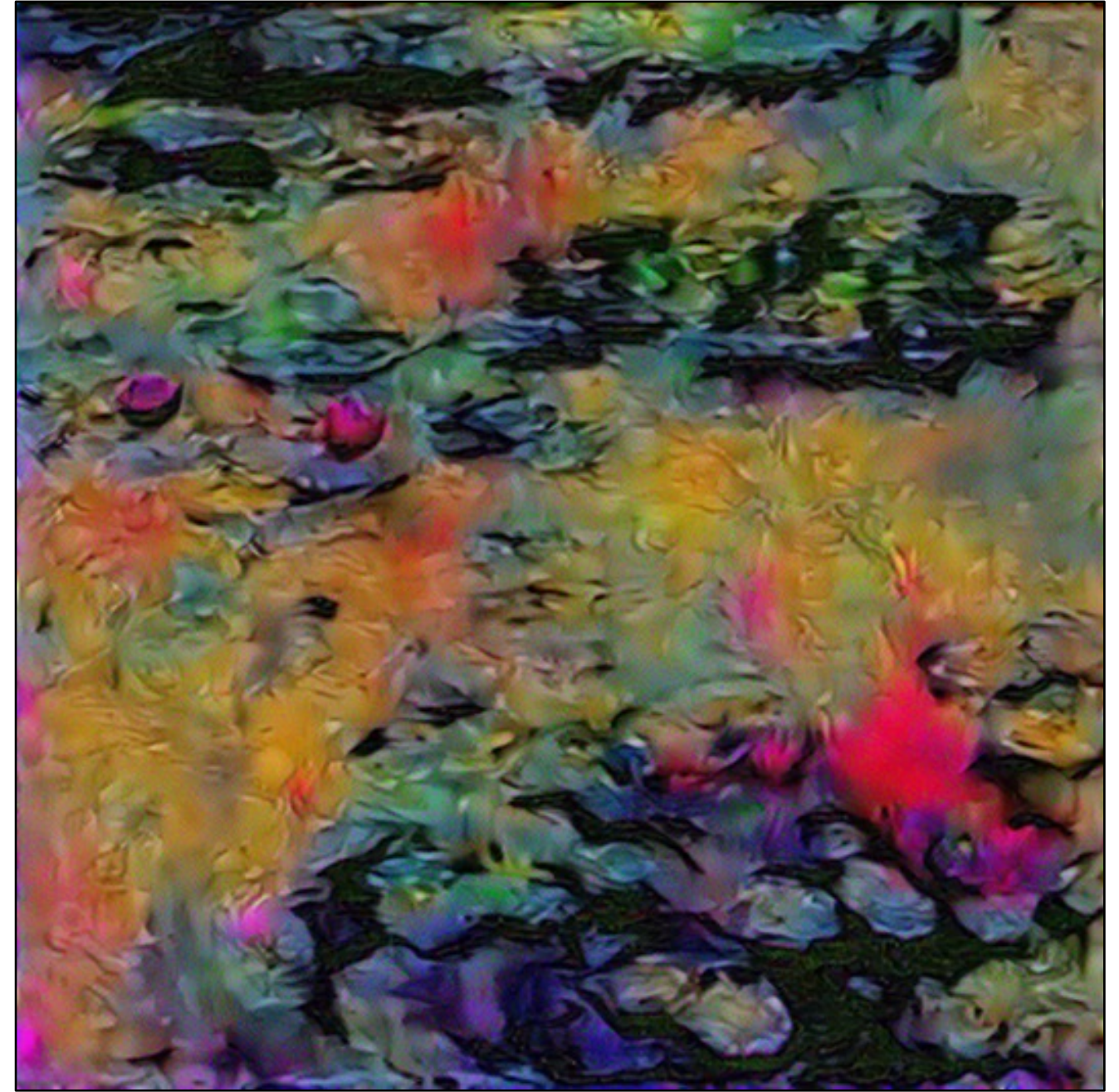
Painting



Reference

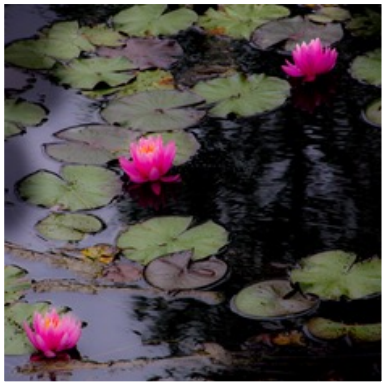


Painting

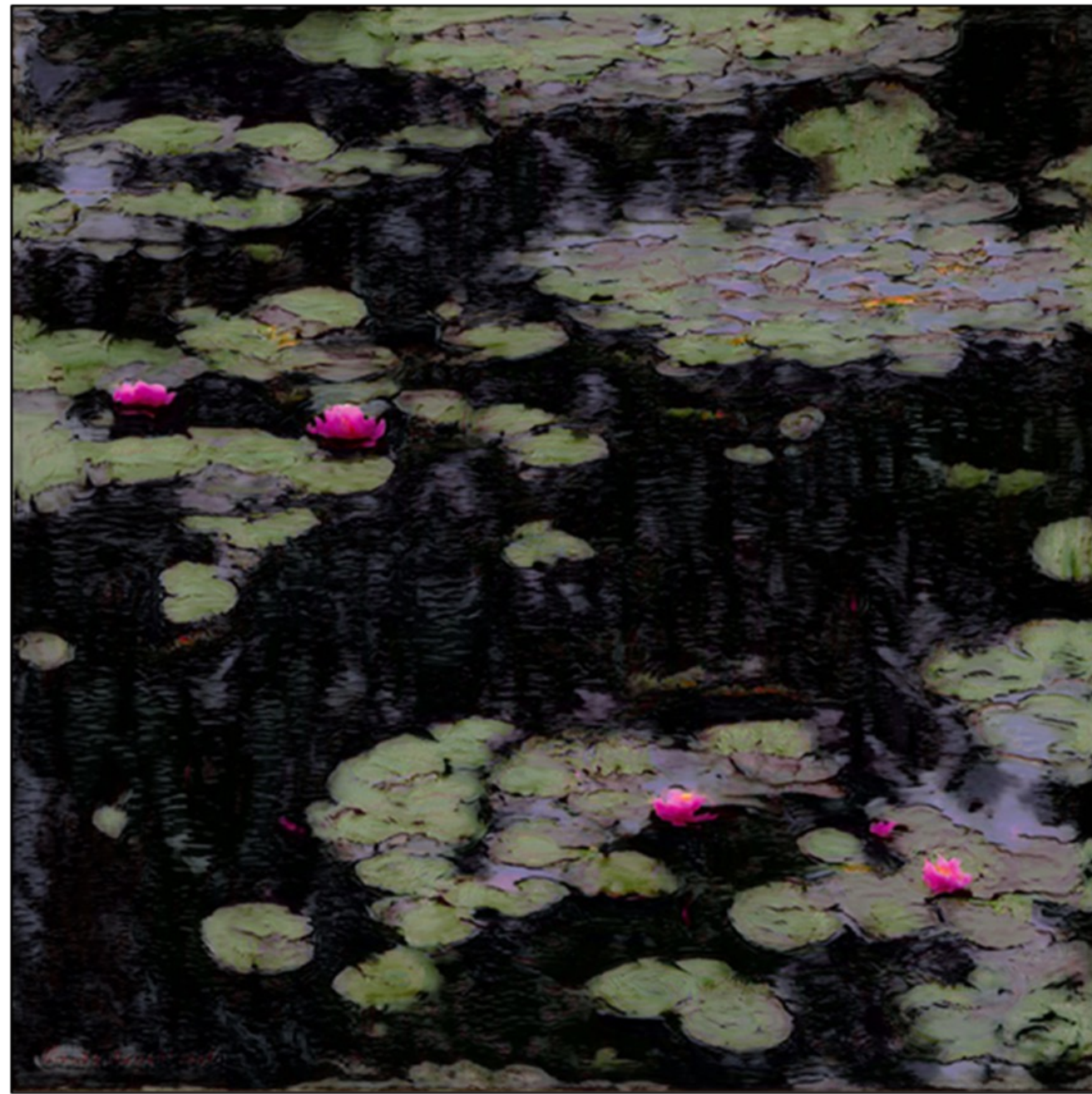


Gatys et al. CVPR'16

Reference



Painting



Single Image translation (CUT)

# Style Transfer vs. Image-to-Image Translation

- Data (how to define Style)
  - A single image? A collection of images
- Applications
  - Photo -> Painting (Neural Style Transfer, Image-to-Image Translation)
  - Photo -> Photo (Image-to-Image Translation, Photo Style Transfer (Color) )
  - Painting -> Photo (Image-to-Image Translation, Deep Image Analogy)
- Algorithms:
  - Patch-based method (or dense correspondence)
  - Optimization-based method
  - Feed-forward network
- Loss functions
  - Style Loss: GAN loss, Gram matrix loss
  - Content Loss: Perceptual Loss, Cycle-consistency loss, Contrastive Loss (InfoNCE)