

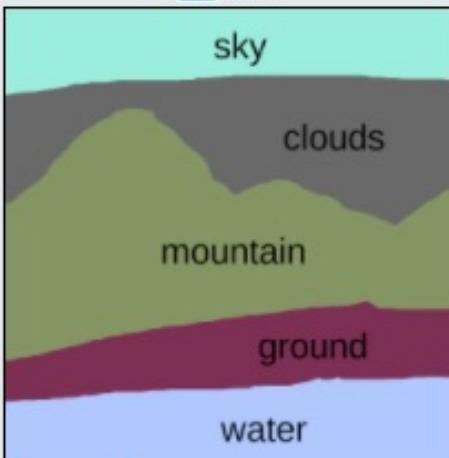
# Image-to-Image Translation and Conditional Generative Models (part II)

Jun-Yan Zhu

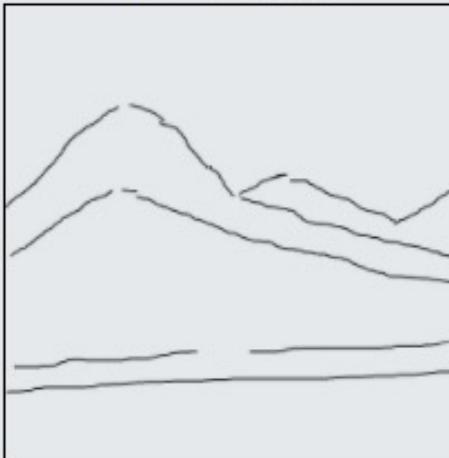
16-726, Spring 2025

Snow mountains  
near a frozen lake  
with pink clouds in  
the sky.

Text



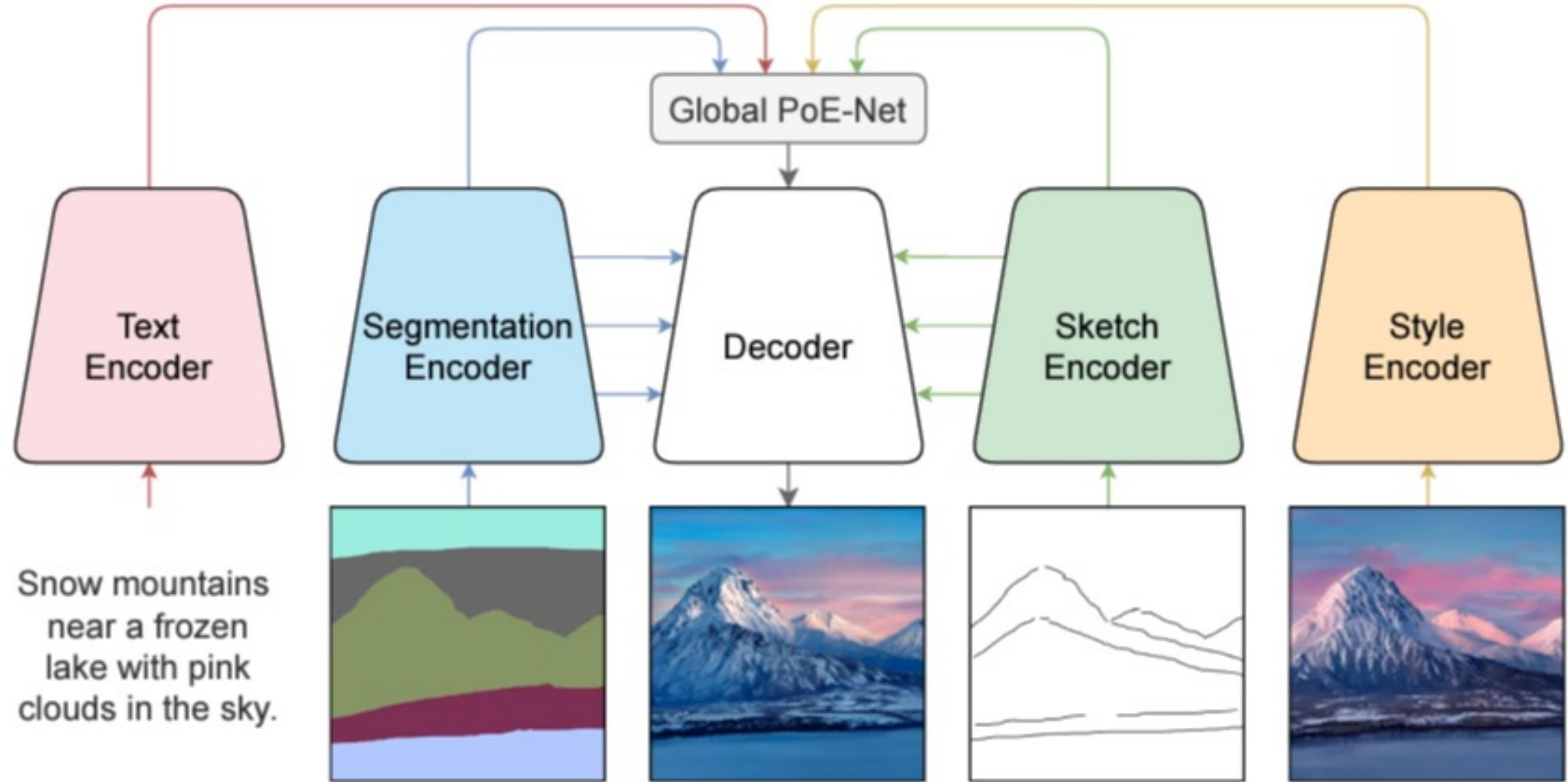
Segmentation



Sketch



Multimodal Conditional Image Synthesis with Product-of-Experts GANs [Huang et al., 2021]

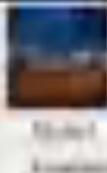


Multimodal Conditional Image Synthesis with Product-of-Experts GANs [Huang et al., 2021]



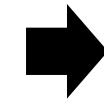
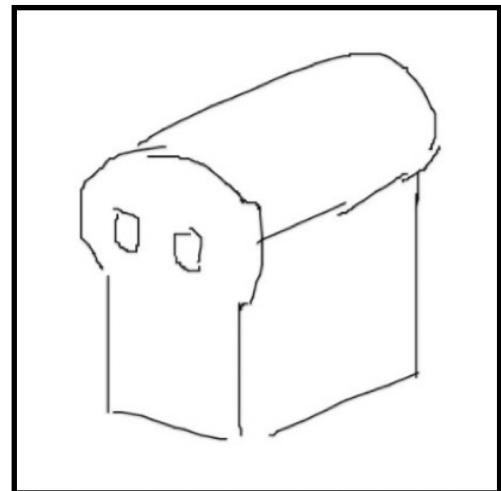
# GauGAN2

Paint Me a Picture



Generating...

# Supervised Learning Approach



Edges2cats

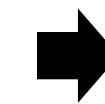
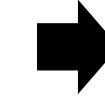


Image colorization



Street view images

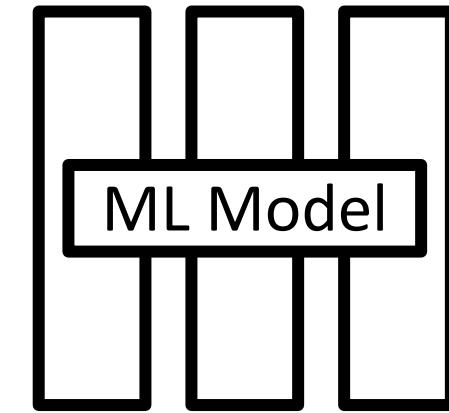


Natural outdoor images

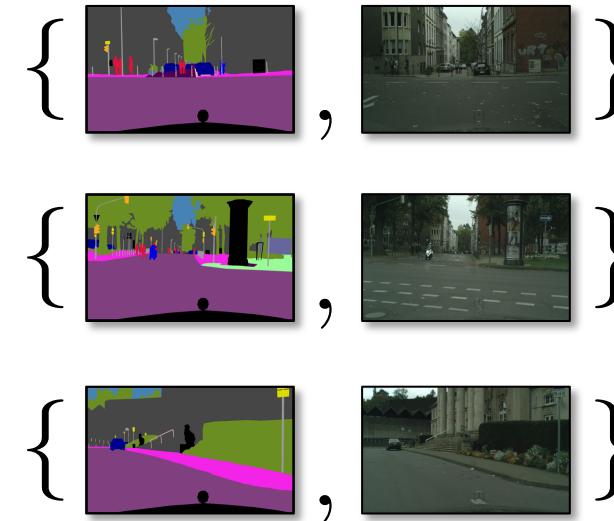
# Supervised Learning Approach



User Input



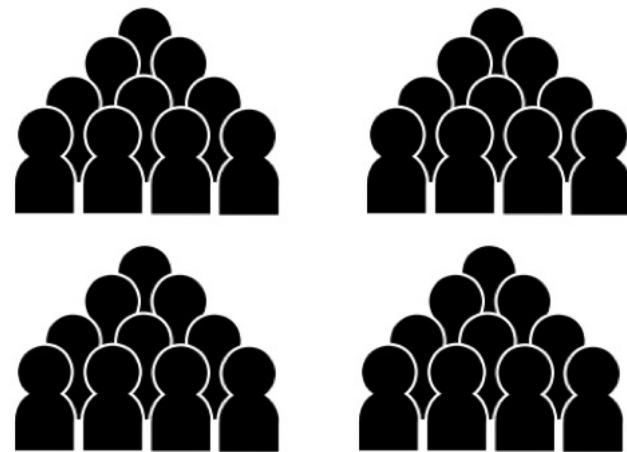
Learning algorithm



Labeled data



Visual Content



Expensive labor



Artistic authoring



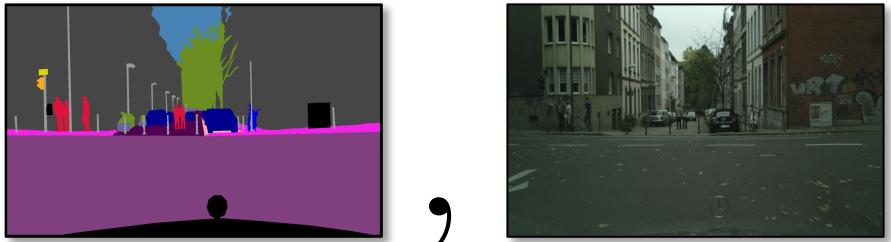
horse



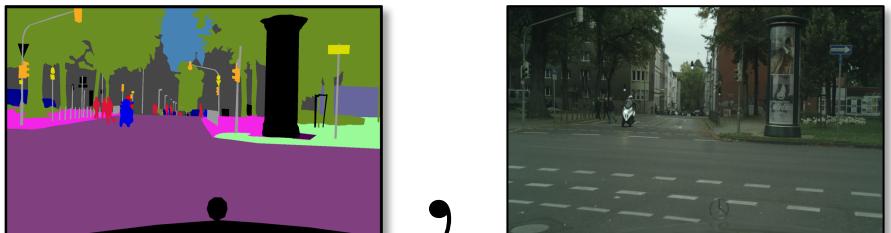
zebra

Infeasible

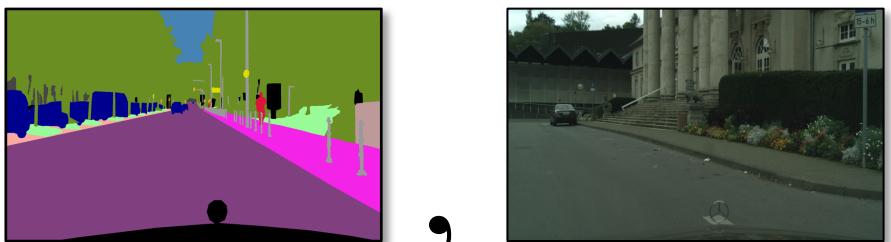
# Supervised

$$\left\{ \begin{array}{c} x_i \\ \text{ } \\ \text{ } \end{array} , \begin{array}{c} y_i \\ \text{ } \\ \text{ } \end{array} \right\}$$


The first row shows a semantic segmentation map of a street scene with colored regions for different objects, followed by a corresponding raw camera image of the same scene.

$$\left\{ \begin{array}{c} x_i \\ \text{ } \\ \text{ } \end{array} , \begin{array}{c} y_i \\ \text{ } \\ \text{ } \end{array} \right\}$$


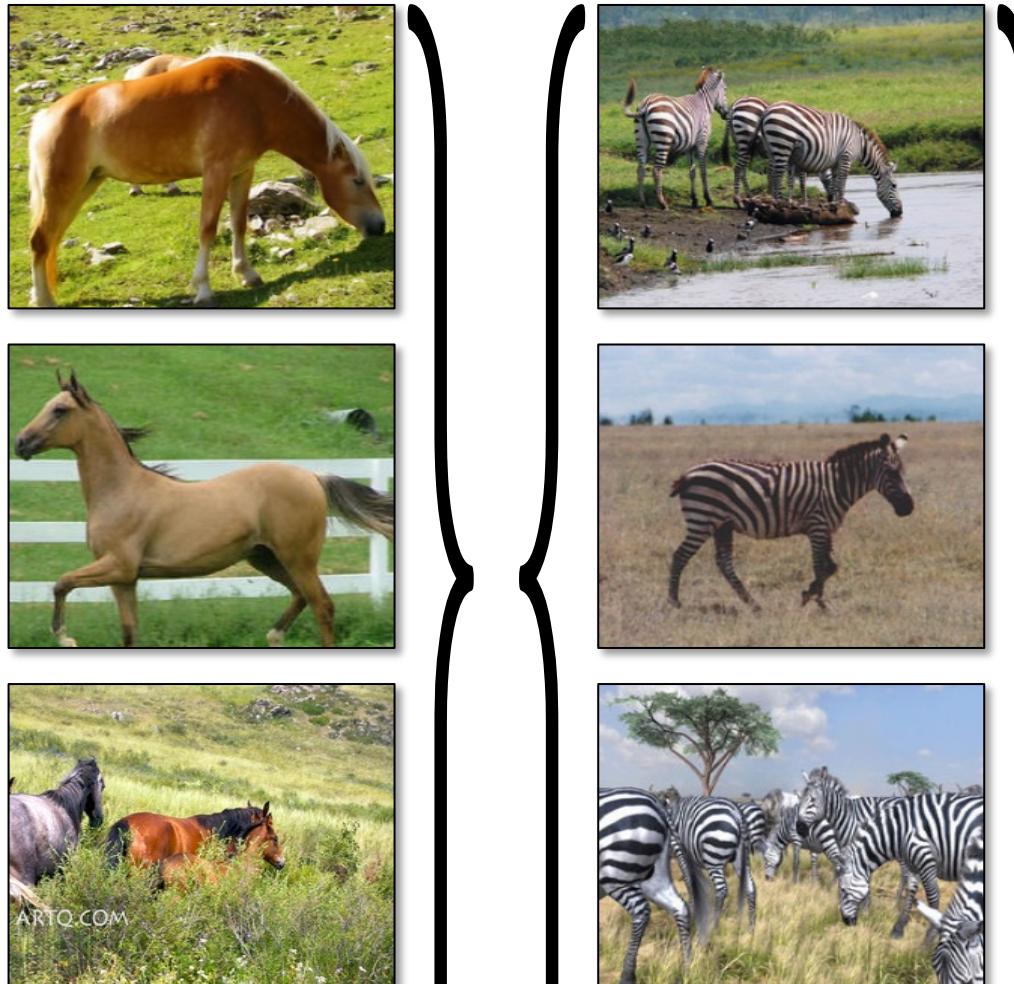
The second row shows a semantic segmentation map of a street scene with colored regions for different objects, followed by a corresponding raw camera image of the same scene.

$$\left\{ \begin{array}{c} x_i \\ \text{ } \\ \text{ } \end{array} , \begin{array}{c} y_i \\ \text{ } \\ \text{ } \end{array} \right\}$$


The third row shows a semantic segmentation map of a street scene with colored regions for different objects, followed by a corresponding raw camera image of the same scene.

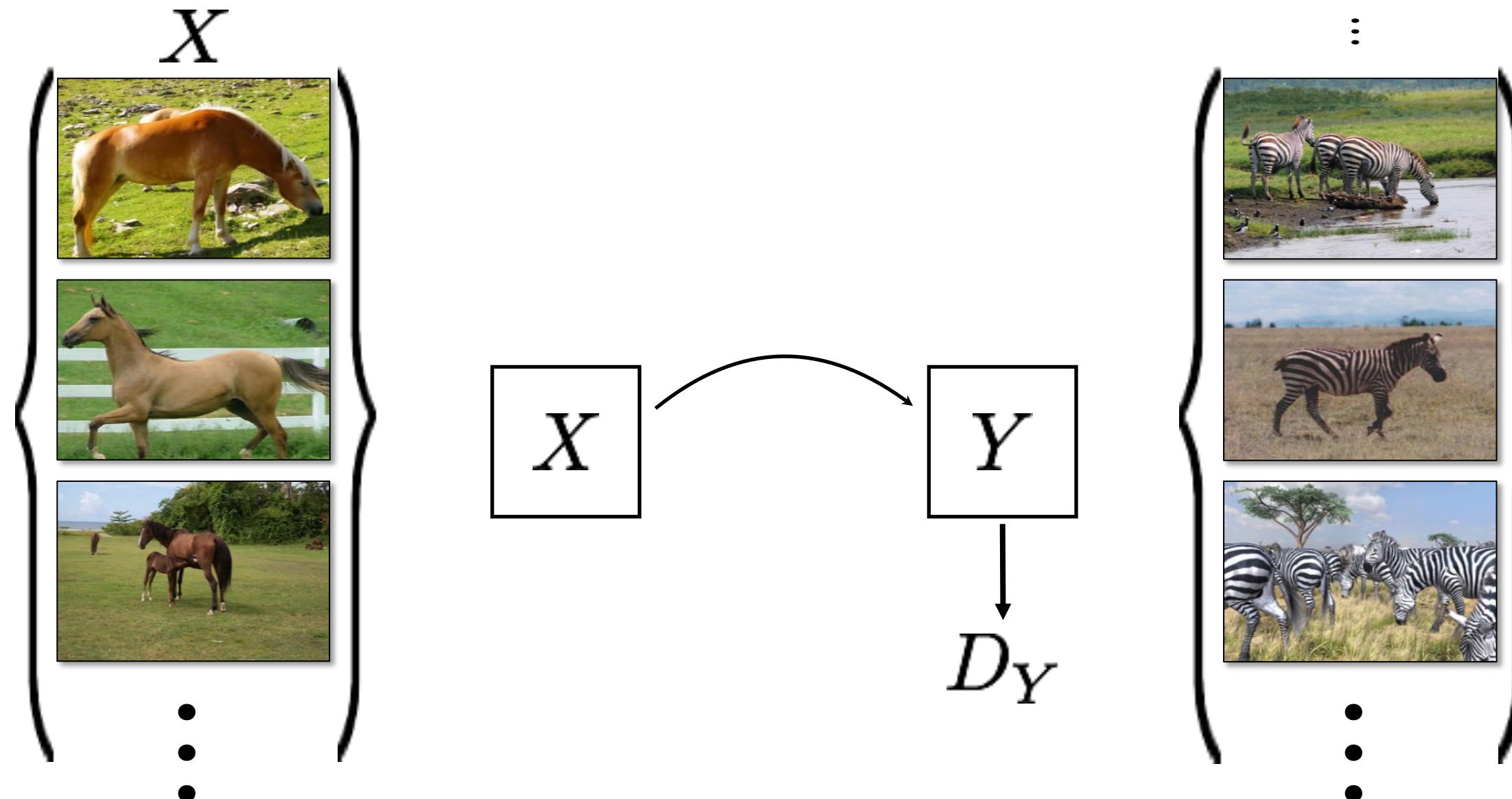
⋮

# Unsupervised

$$\left\{ \begin{array}{c} X \\ \text{ } \\ \text{ } \end{array} , \begin{array}{c} Y \\ \text{ } \\ \text{ } \end{array} \right\}$$


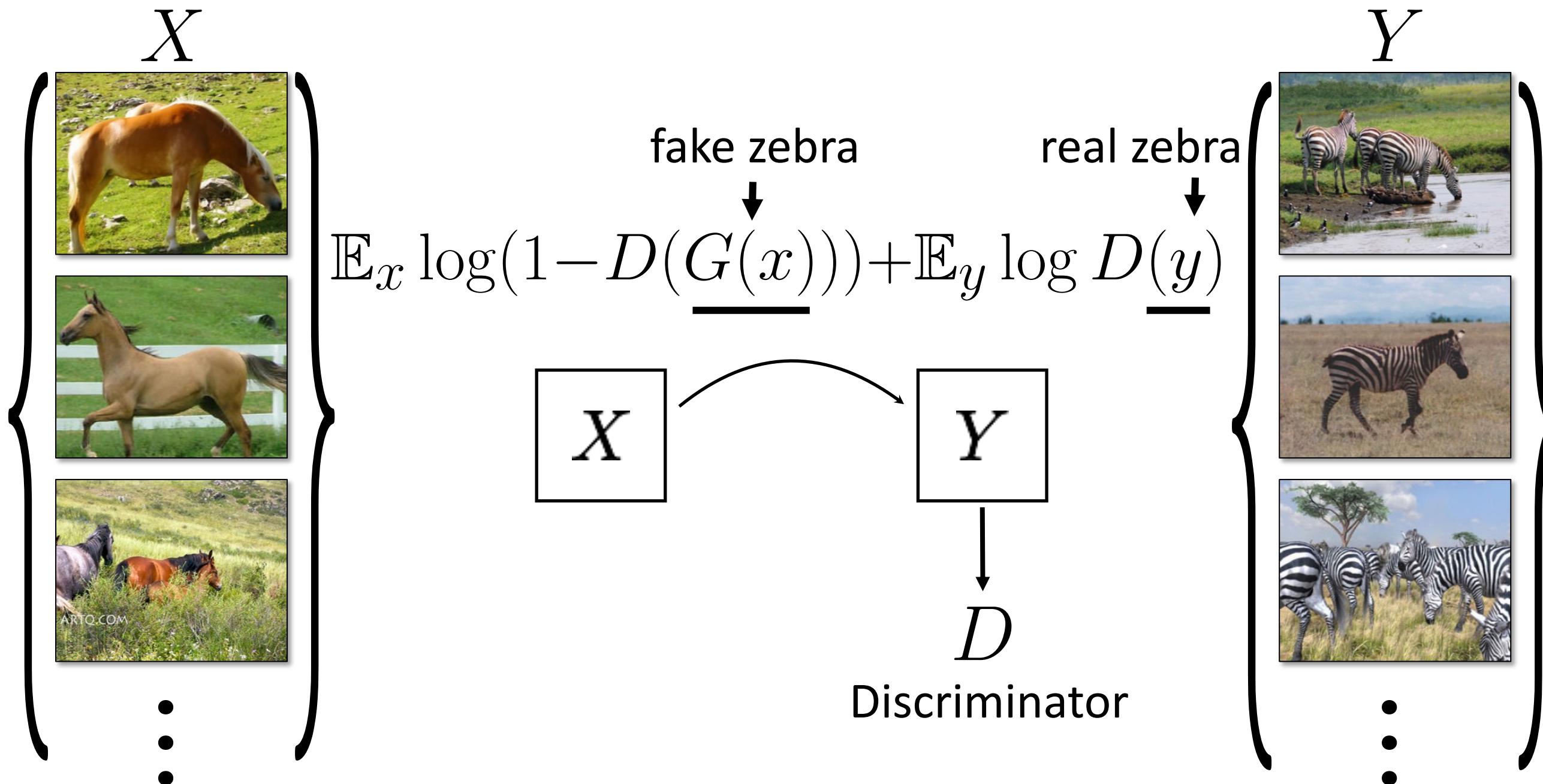
The diagram illustrates an unsupervised learning setup where two sets of images,  $X$  and  $Y$ , are shown side-by-side. Set  $X$  contains images of horses in various poses and environments. Set  $Y$  contains images of zebras in various environments. Vertical ellipses between the sets indicate that there are many more images in each set than shown here.

# Unsupervised Learning of $p(y | x)$



[Zhu\*, Park\*, Isola, and Efros, 2017]

# Unsupervised Learning of $p(y | x)$

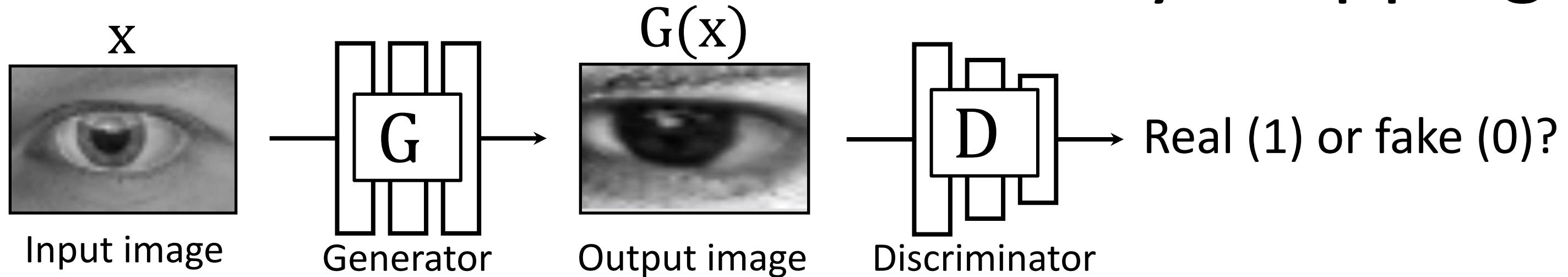


# Unsupervised Learning of $p(y | x)$



- artifacts
- ignore inputs

# Additional Constraint: Identity Mapping

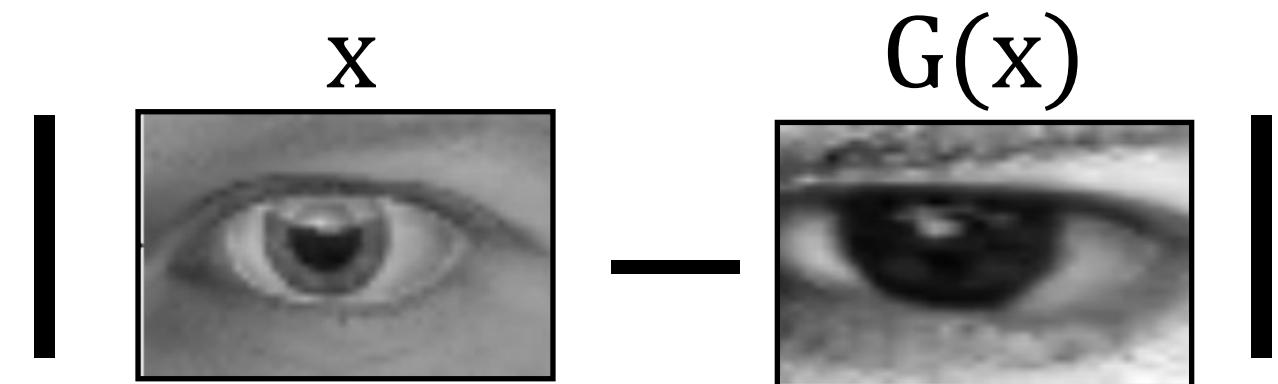


## Adversarial loss

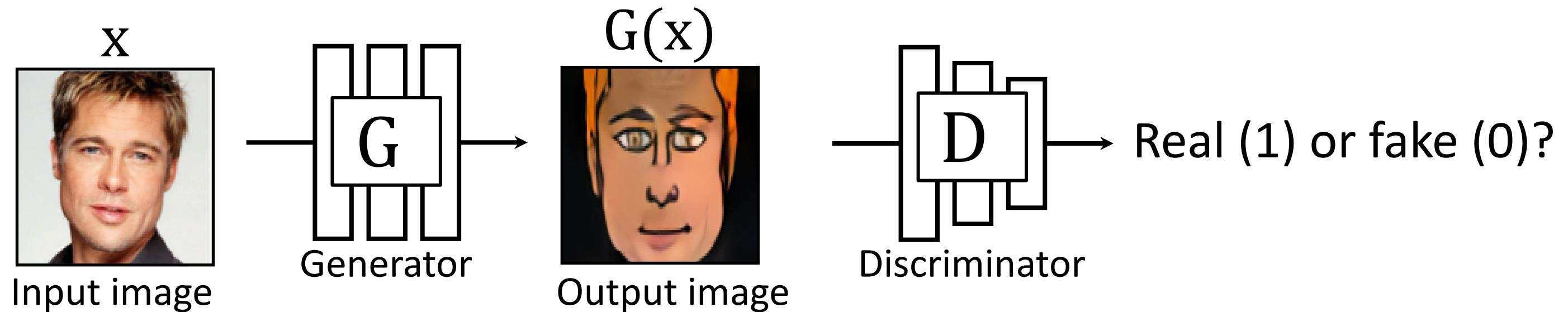
$$\mathbb{E}_x \log(1 - D_Y(G(x))) + \mathbb{E}_y \log D_Y(y)$$

## Self-Regularization loss

$$\mathbb{E}_x \|G(x) - x\|_1$$



# Additional Constraint: Feature Loss



# Adversarial loss

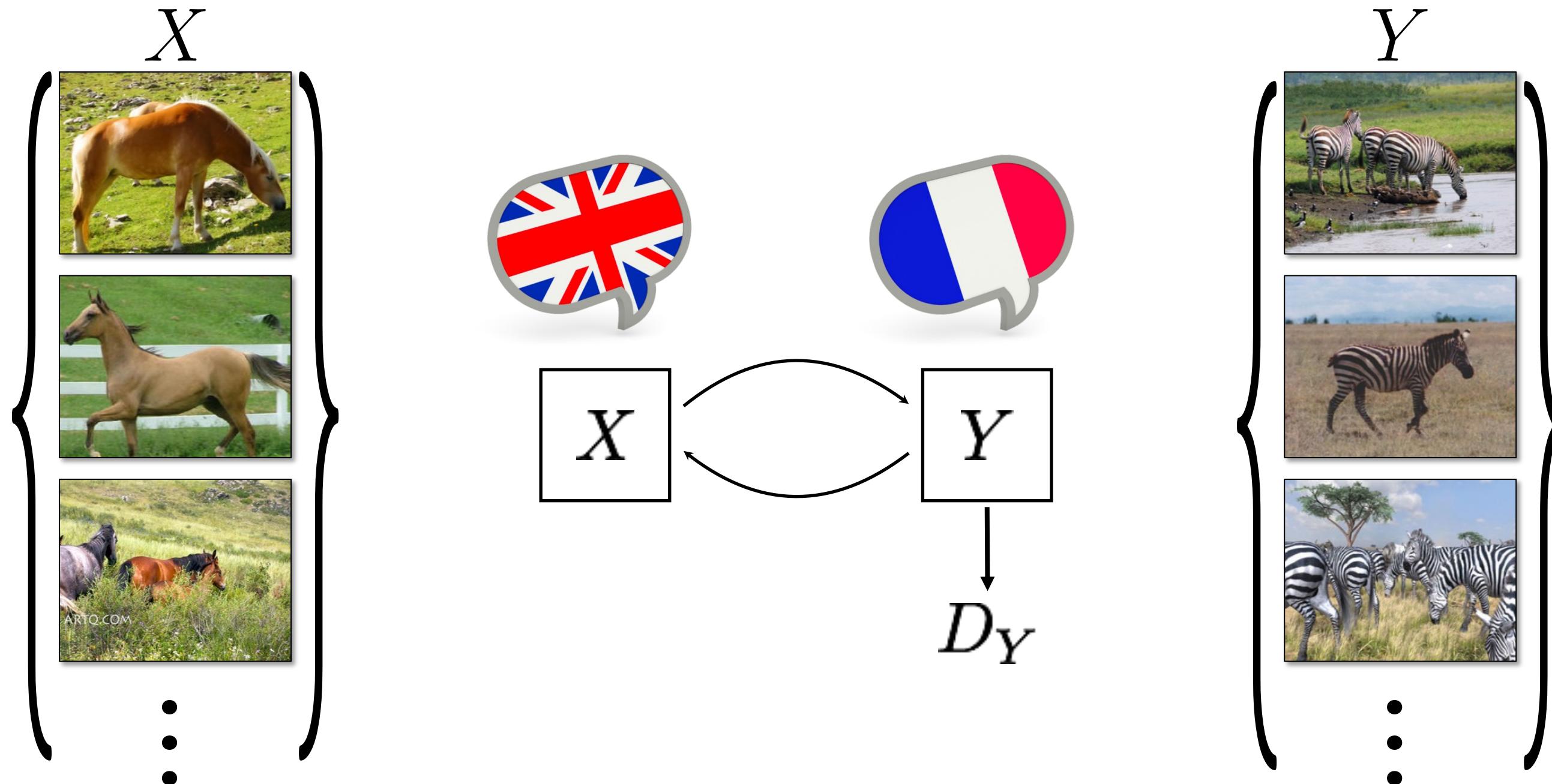
$$\mathbb{E}_x \log(1 - D_Y(G(x))) + \mathbb{E}_y \log D_Y(y)$$

# Feature loss

$$\mathbb{E}_x \left| \left| F(G(x)) - F(x) \right| \right|$$

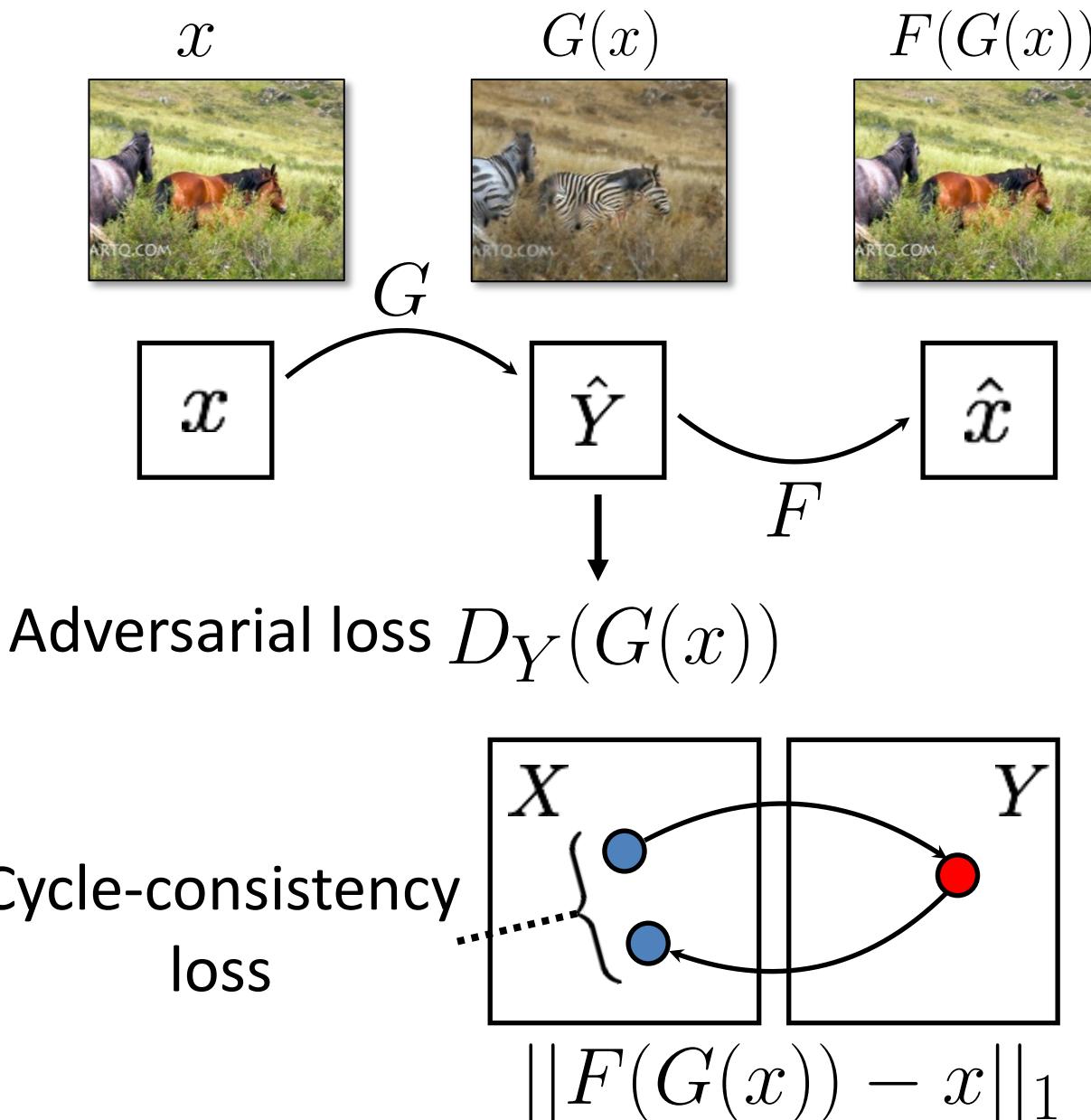
Requires F to work across two domains

# Additional Constraint: Cycle-Consistency



CycleGAN [Zhu\*, Park\* et al., ICCV 2017]

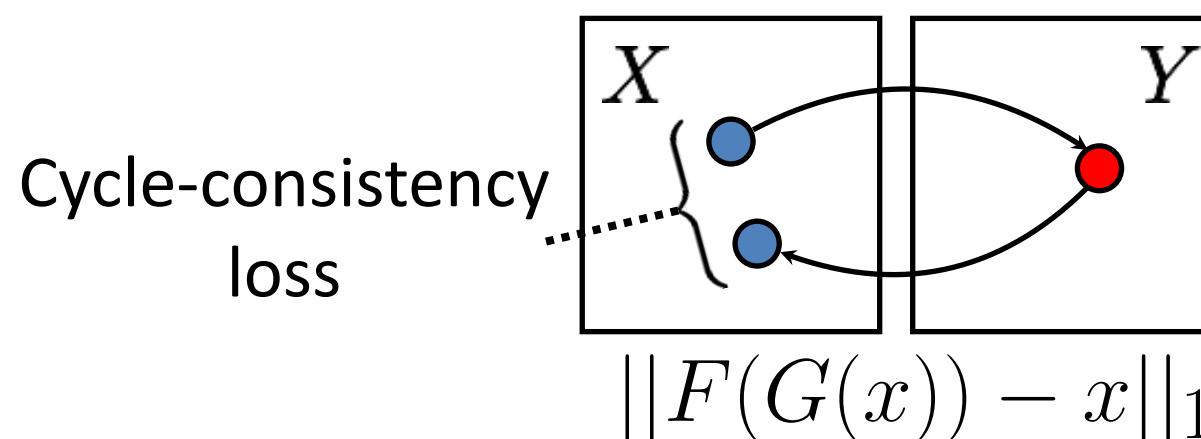
# Cycle-Consistent Adversarial Networks



**Adversarial loss**

$$\mathbb{E}_x \log(1 - D_Y(G(x))) + \mathbb{E}_y \log D_Y(y)$$

Adversarial loss  $D_Y(G(x))$

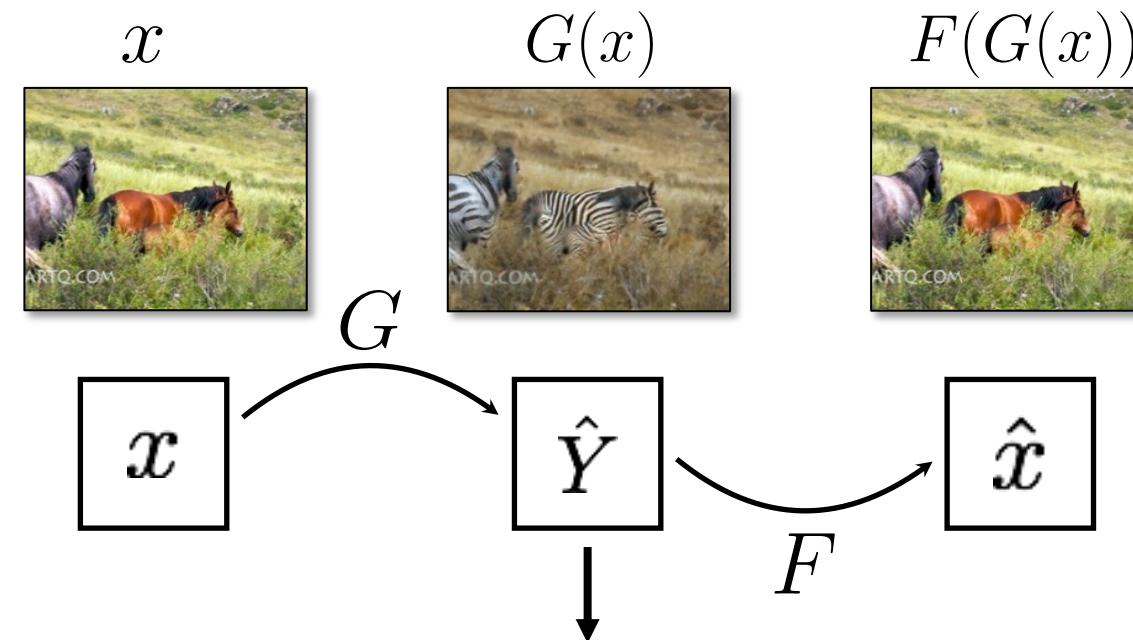


**Cycle-consistency loss**

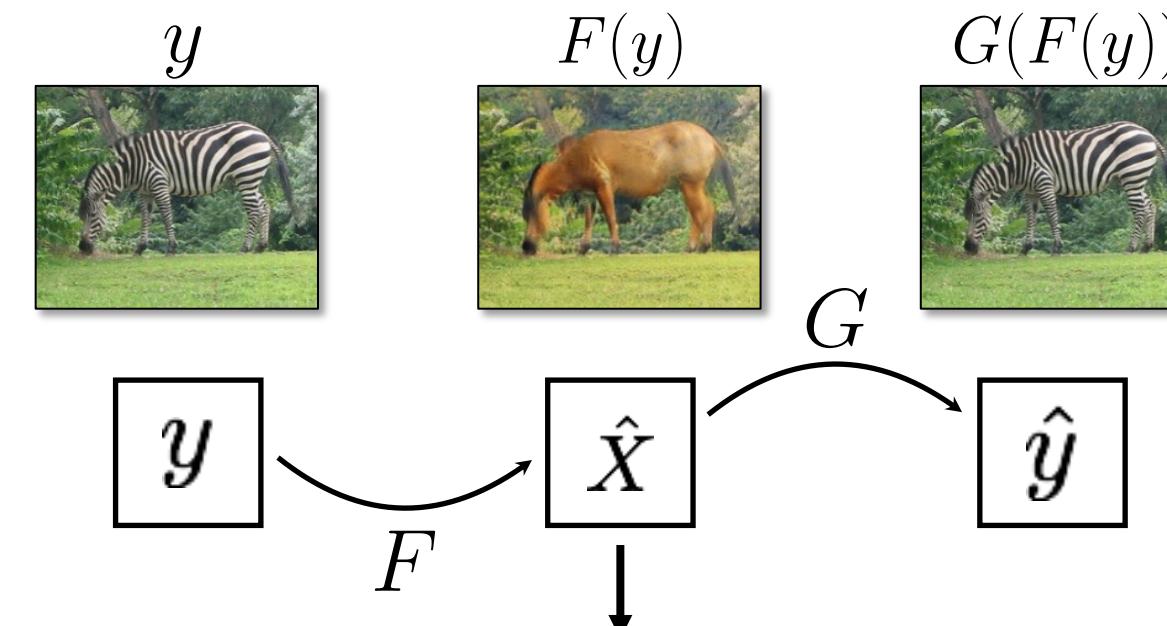
$$\mathbb{E}_x \|F(G(x)) - x\|_1$$

CycleGAN [Zhu\*, Park\* et al., ICCV 2017]

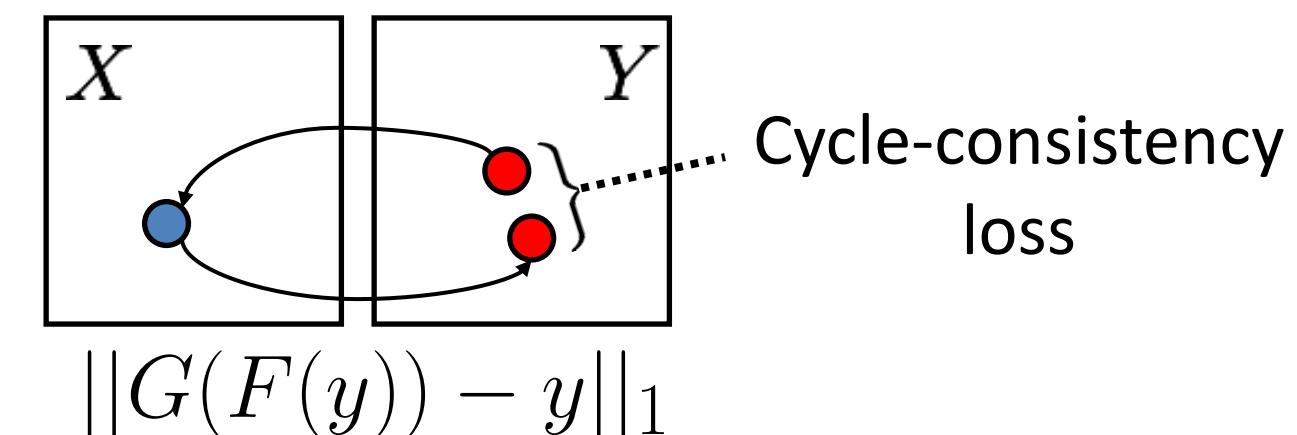
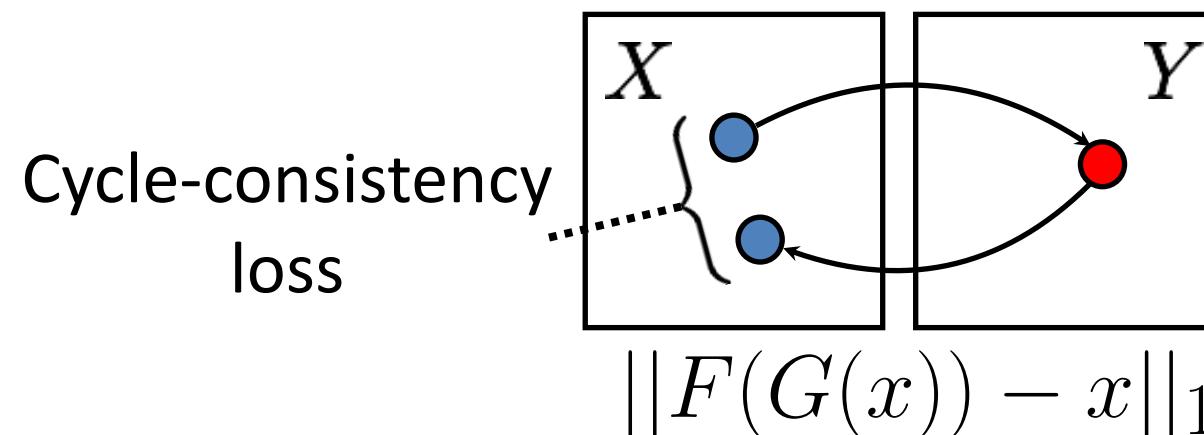
# Cycle-Consistent Adversarial Networks



Adversarial loss  $D_Y(G(x))$



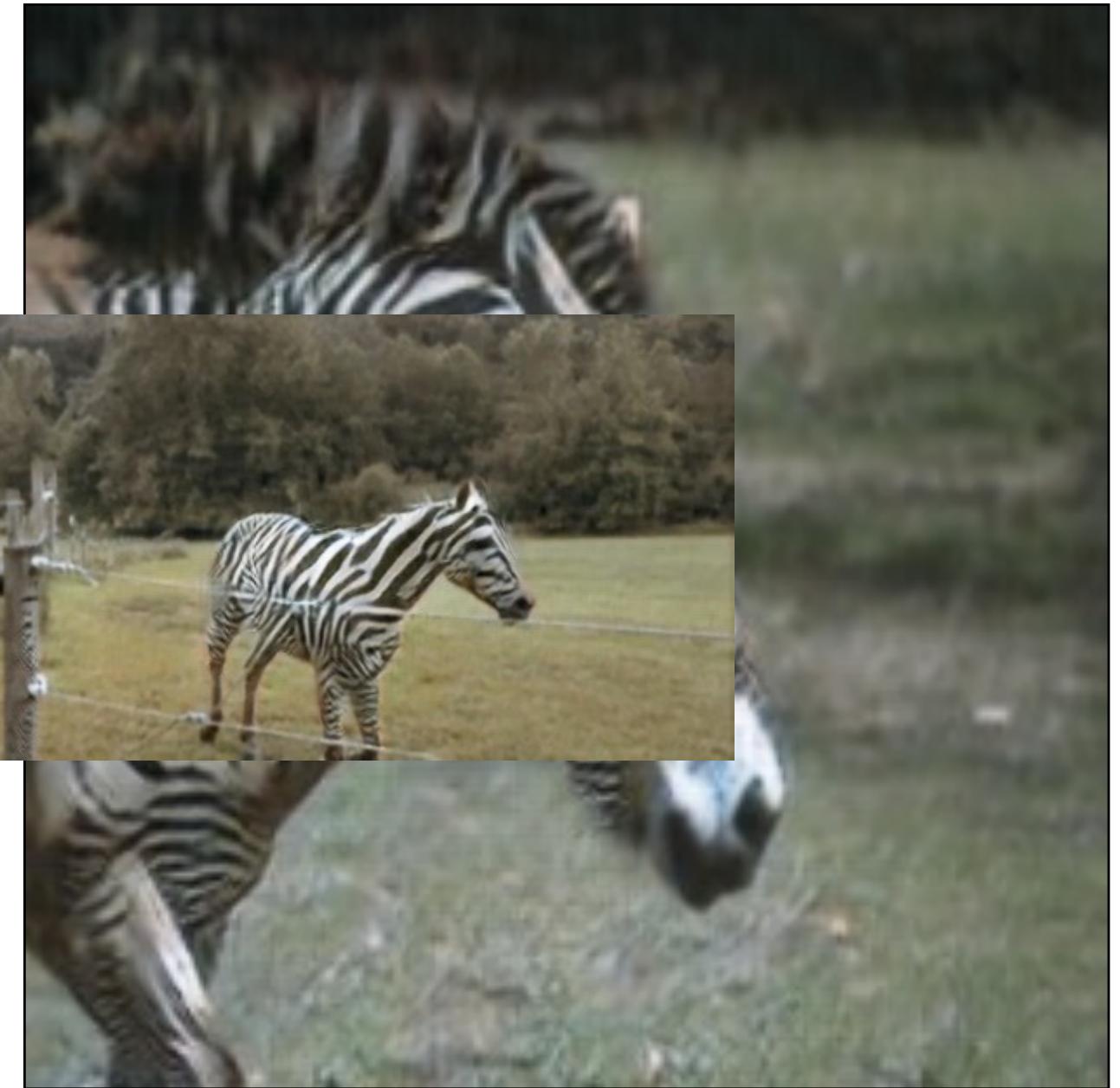
$D_X(F(y))$  Adversarial loss



CycleGAN [Zhu\*, Park\* et al., ICCV 2017]

# Results

# Horse → Zebra



# Orange → Apple



# Monet's paintings → photographic style



# Monet's paintings → photographic style



# Collection Style Transfer



Photograph ©Alexei Efros



Monet



Van Gogh



Cezanne



Ukiyo-e

# Improving the Realism of CG Rendering



CG Game: Grand Theft Auto



Street view images in German cities

Data from [Richter et al., 2016], [Cordts et al, 2016]

# Improving the Realism of CG Rendering



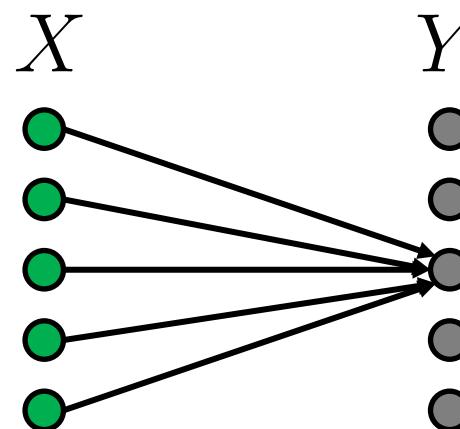
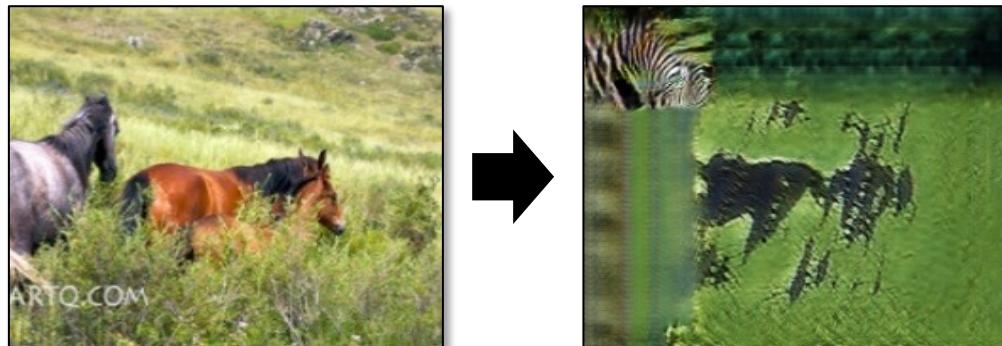
Output image with `cgimage` street view style

# Why CycleGAN works

# Why CycleGAN works

## Adversarial loss

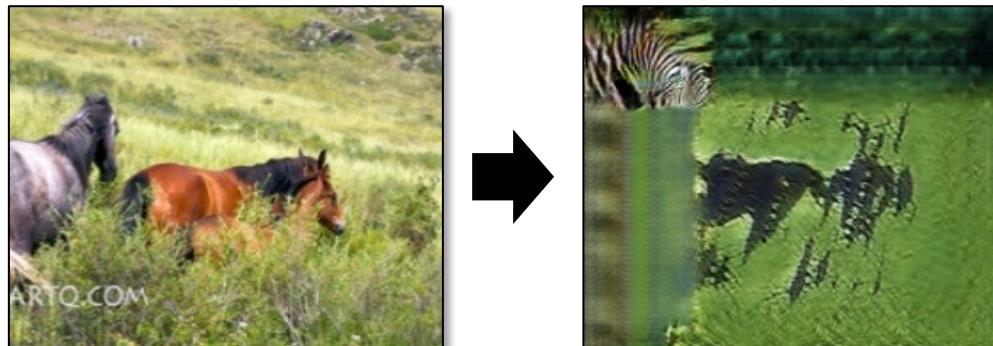
$$\mathbb{E}_x \log(1 - D_Y(G(x))) + \mathbb{E}_y \log D_Y(y)$$



# Why CycleGAN works

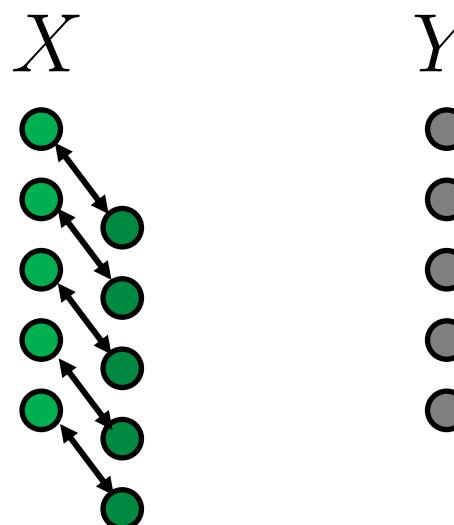
## Adversarial loss

$$\mathbb{E}_x \log(1 - D_Y(G(x))) + \mathbb{E}_y \log D_Y(y)$$



## Cycle-consistency loss

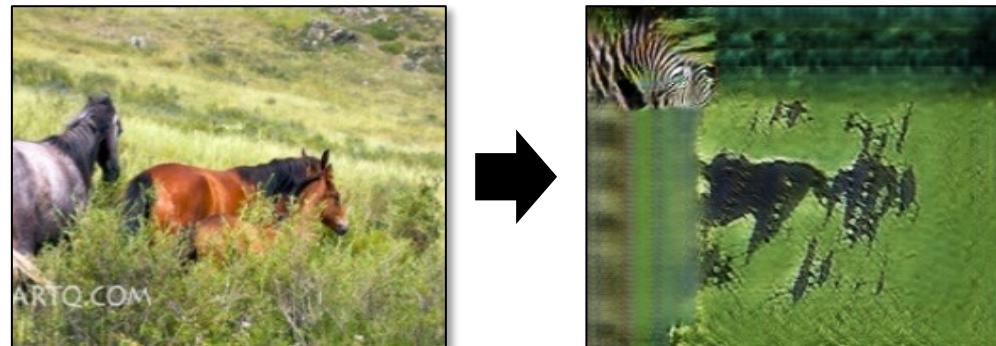
$$\mathbb{E}_x \|F(G(x)) - x\|_1$$



# Why CycleGAN works

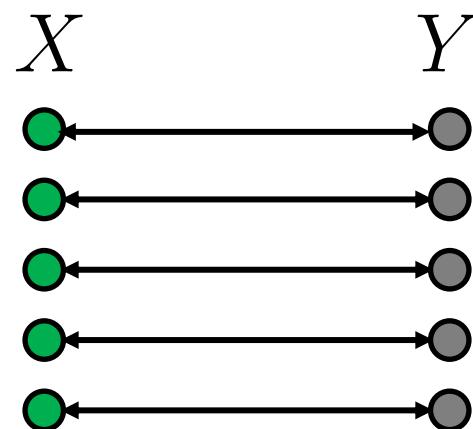
## Adversarial loss

$$\mathbb{E}_x \log(1 - D_Y(G(x))) + \mathbb{E}_y \log D_Y(y)$$



## Cycle-consistency loss

$$\mathbb{E}_x \|F(G(x)) - x\|_1$$



## Full objective



# Why CycleGAN works

## Adversarial loss

$$\mathbb{E}_x \log(1 - D_Y(G(x))) + \mathbb{E}_y \log D_Y(y)$$

$x$



## Cycle-consistency loss

$$\mathbb{E}_x \|F(G(x)) - x\|_1$$

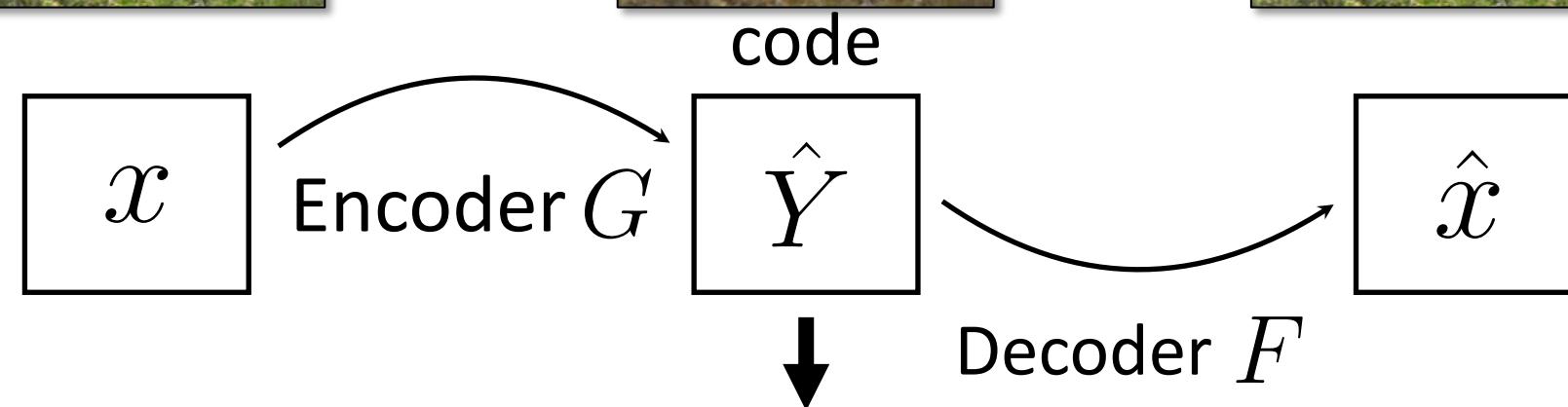
$G(x)$



$F(G(x))$



## Auto-encoder w/ domain prior



Constraint:  $\text{len}(\mathcal{G}(x)) \leq \text{latent}(Y)$

# Why CycleGAN works

## Adversarial loss

$$\mathbb{E}_x \log(1 - D_Y(G(x))) + \mathbb{E}_y \log D_Y(y)$$

Under-constrained problem



A strong regularizer

**Assumption:** simple invertible function

**Probabilistic Interpretation :** Upper bound of conditional entropy  $H(y|x)$

[Li et al. 2017]

# Why CycleGAN works

## Adversarial loss

$$\mathbb{E}_x \log(1 - D_Y(G(x))) + \mathbb{E}_y \log D_Y(y)$$

## Cycle-consistency loss

$$\mathbb{E}_x \|F(G(x)) - x\|_1$$

flip the image



$$P \circ G$$



$$F \circ P^{-1}$$



## Invertible Perturbation

flip the image again

**Adversarial loss:** images are horizontally symmetric

**Cycle-consistency loss :**  $\|F \circ P^{-1}(P \circ G(x)) - x\|$

# Style and Content Disentanglement

# Style and Content Separation

**A**

Classification

<b>A</b>	<b>B</b>	<b>C</b>	<b>D</b>	<b>E</b>
<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>
A	B	C	D	E
<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>
<b>A</b>	<b>B</b>	<b>C</b>	<b>D</b>	<b>E</b>
B	C	<b>A</b>	E	D

Domain Adaptation

**B**

Extrapolation

<b>A</b>	<b>B</b>	<b>C</b>	<b>D</b>	<b>E</b>
<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>
A	B	C	D	E
<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>
<b>A</b>	<b>B</b>	<b>C</b>	<b>D</b>	<b>E</b>
?	?	C	D	E

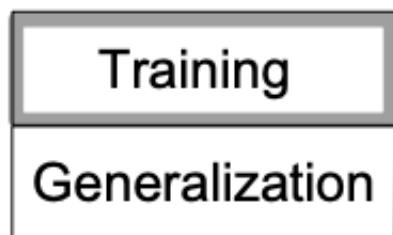
Paired Image-to-Image Translation

**C**

Translation

<b>A</b>	<b>B</b>	<b>C</b>	<b>D</b>	<b>E</b>	?	?	?
<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>			
A	B	C	D	E			
<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>			
<b>A</b>	<b>B</b>	<b>C</b>	<b>D</b>	<b>E</b>	?	?	?
?				?	F	G	H

Unpaired Image-to-Image Translation



Separating Style and Content  
[Tenenbaum and Freeman 1996]

$$y_k^{sc} = \sum_{i=1}^I \sum_{j=1}^J w_{ijk} a_i^s b_j^c.$$

# Style and Content

## Adversarial loss

$$\mathbb{E}_x \log(1 - D_Y(G(x))) + \mathbb{E}_y \log D_Y(y)$$



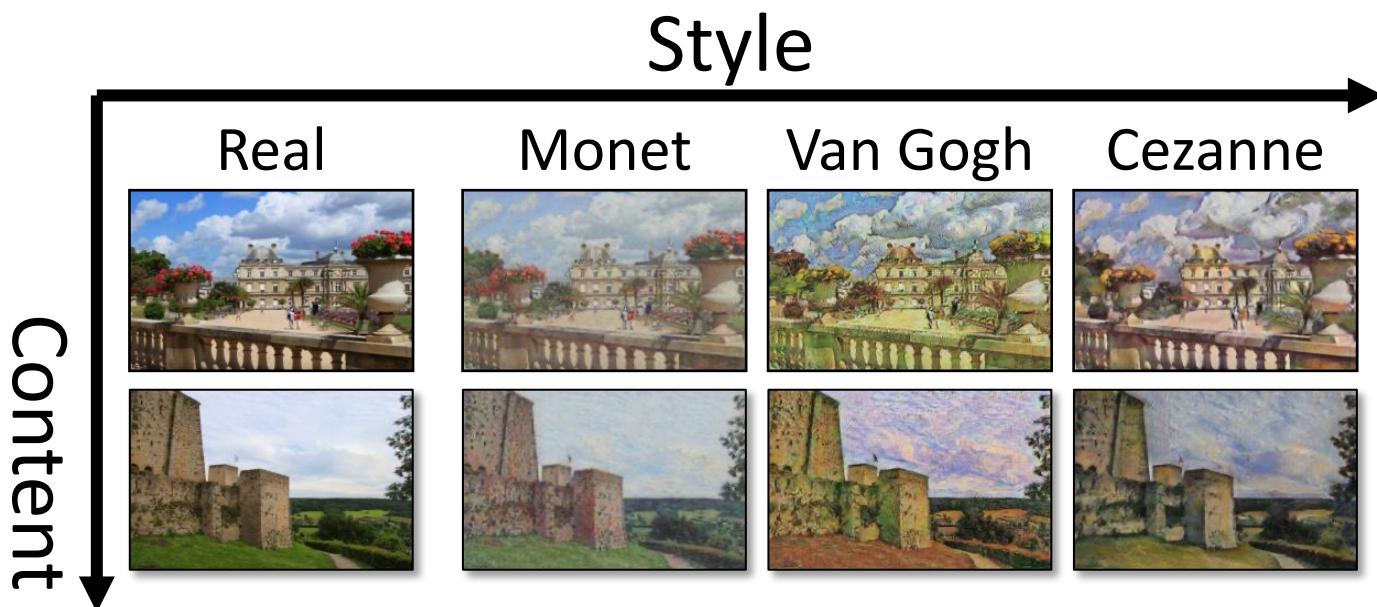
$p(x) \rightarrow p(y)$  change style

## Cycle-consistency loss

$$\mathbb{E}_x \|F(G(x)) - x\|_1$$

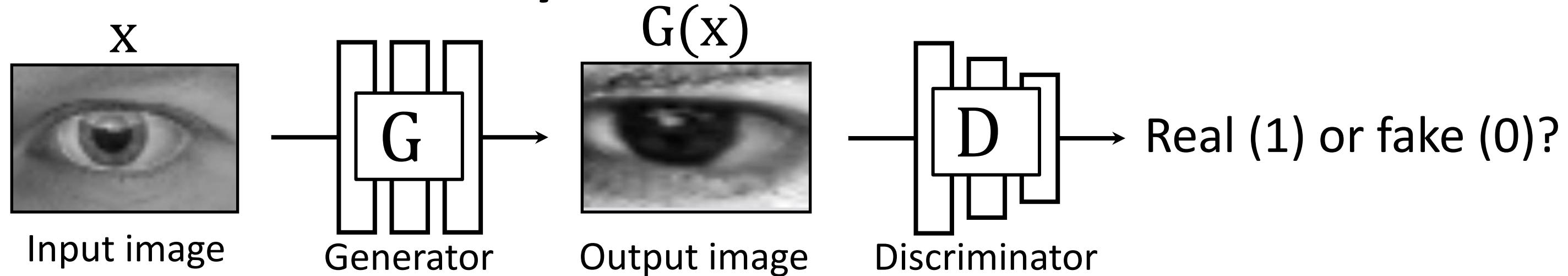


Bidirectional: preserve content



Separating Style and Content  
[Tenenbaum and Freeman 1996]

# Style and Content

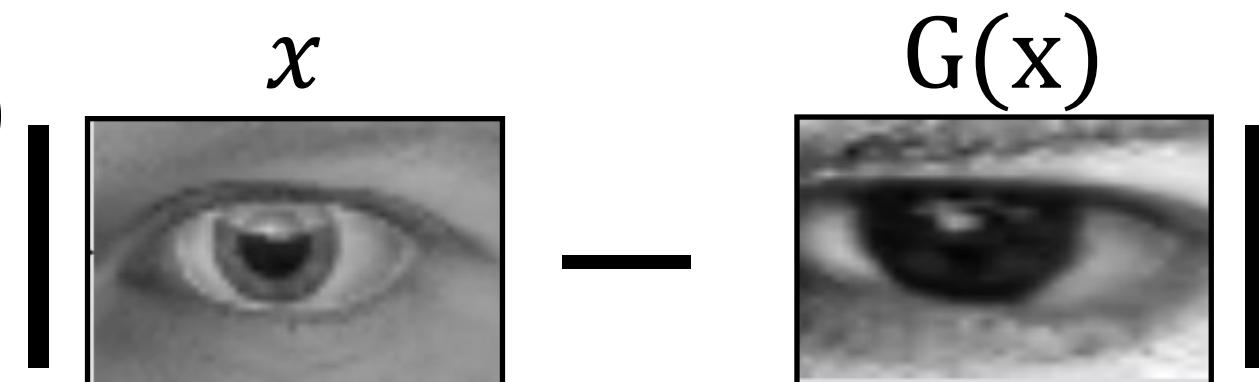


**Adversarial loss (change style)**

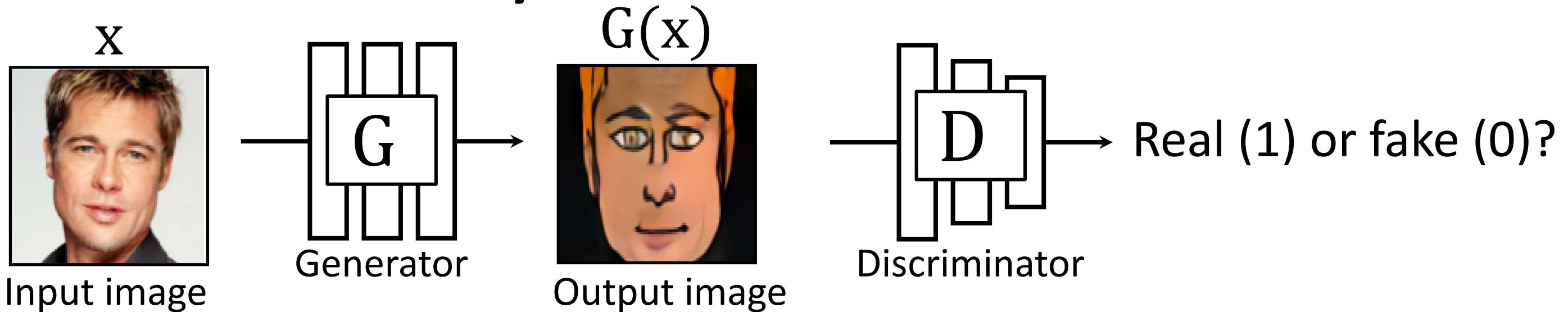
$$\mathbb{E}_x \log(1 - D_Y(G(x))) + \mathbb{E}_y \log D_Y(y)$$

**L1 loss (preserve content in pixel space)**

$$\mathbb{E}_x \|G(x) - x\|_1$$



# Style and Content



**Adversarial loss (change style)**

$$\mathbb{E}_x \log(1 - D_Y(G(x))) + \mathbb{E}_y \log D_Y(y)$$

**Feature loss (Preserve content in feature space)**

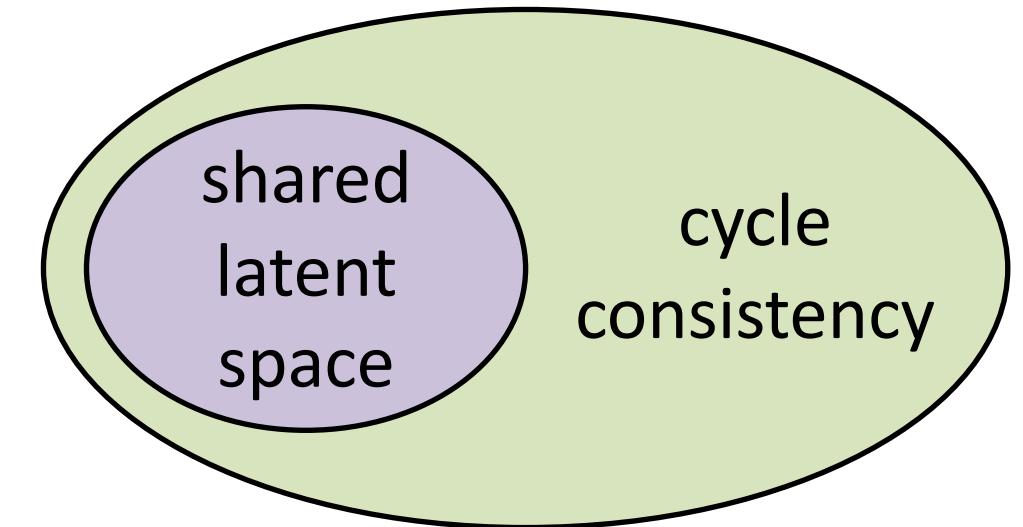
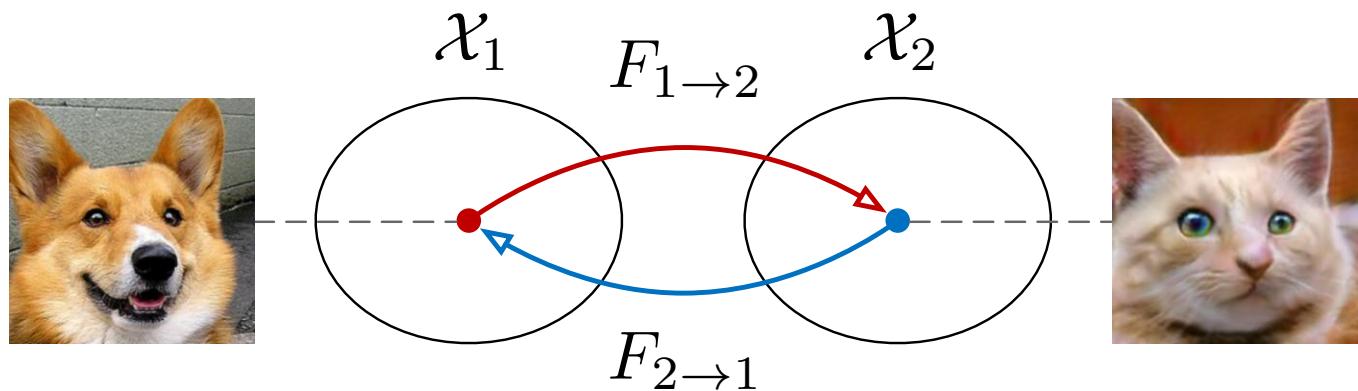
$$\mathbb{E}_x \|F(G(x)) - F(x)\|$$

$$|F(\text{Input}) - F(\text{Output})|$$

DTN [Taigman et al., 2017]

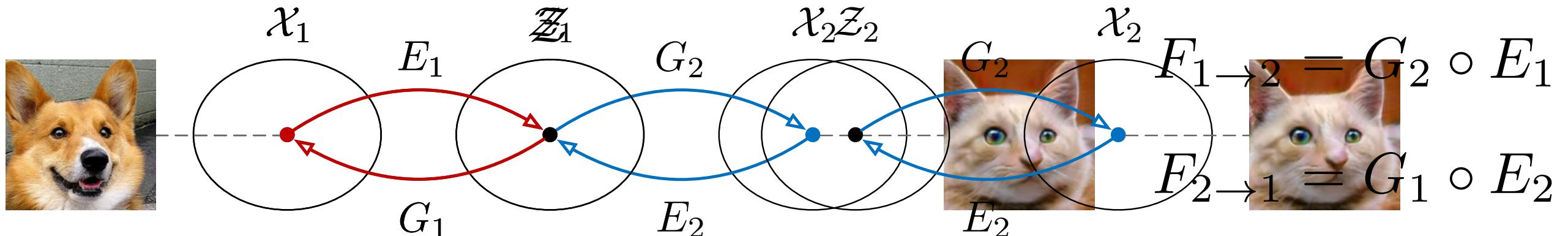
# CycleGAN and UNIT

- CycleGAN (**cycle consistency**)



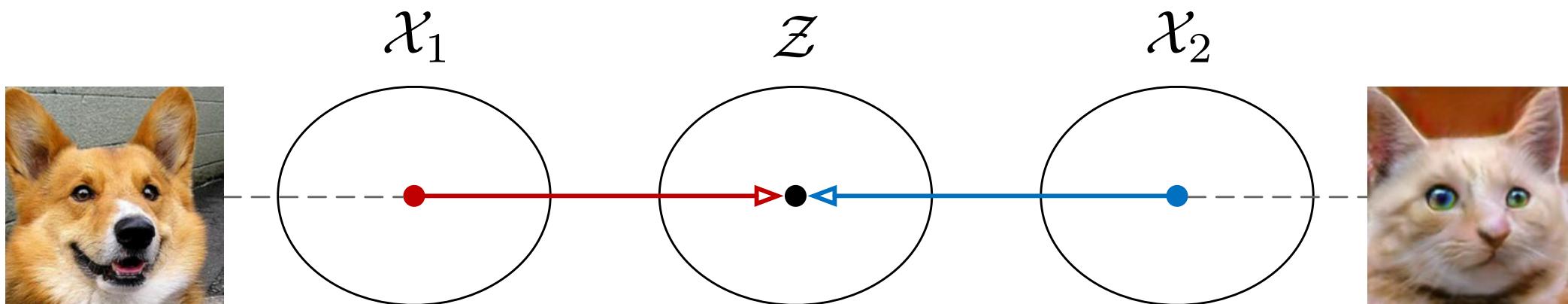
- UNIT (**shared latent space**) [Liu et al. 2017]

shared latent space  $\Rightarrow$  cycle consistency



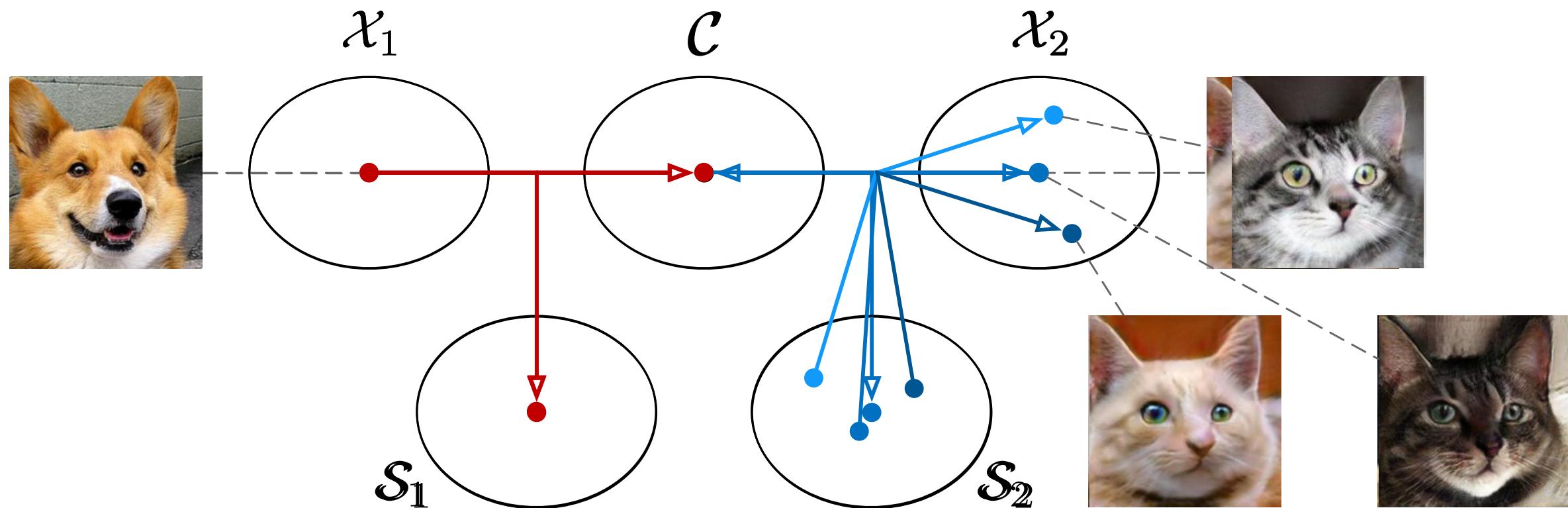
# Disentangling the Latent Space

- UNIT
  - A single **shared, domain-invariant** latent space  $\mathcal{Z}$

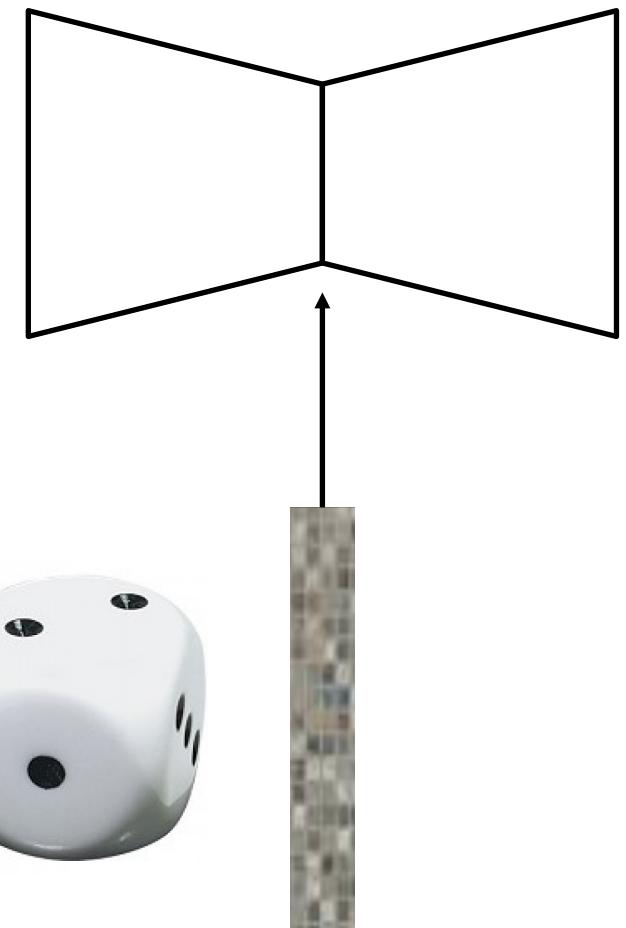
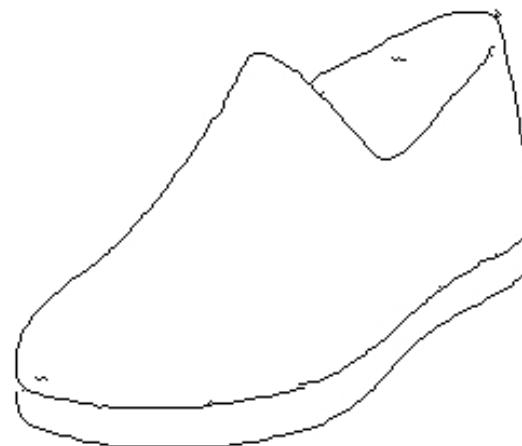


# Disentangling the Latent Space

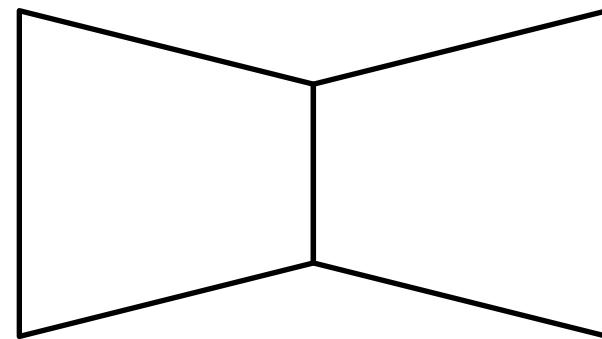
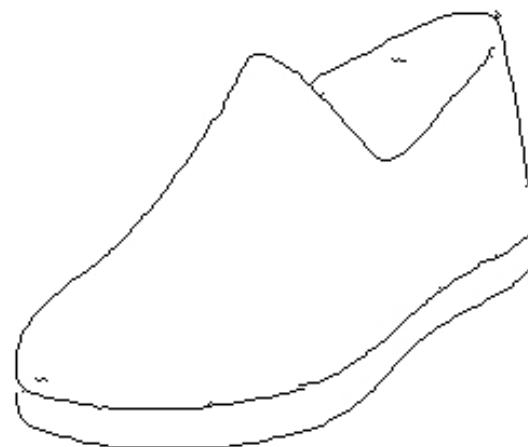
- Multimodal UNIT (MUNIT)
  - A **content** space  $\mathcal{C}$  that is **shared, domain-invariant**
  - Two **style** spaces  $\mathcal{S}_1, \mathcal{S}_2$  that are **unshared, domain-specific**



# Unimodality



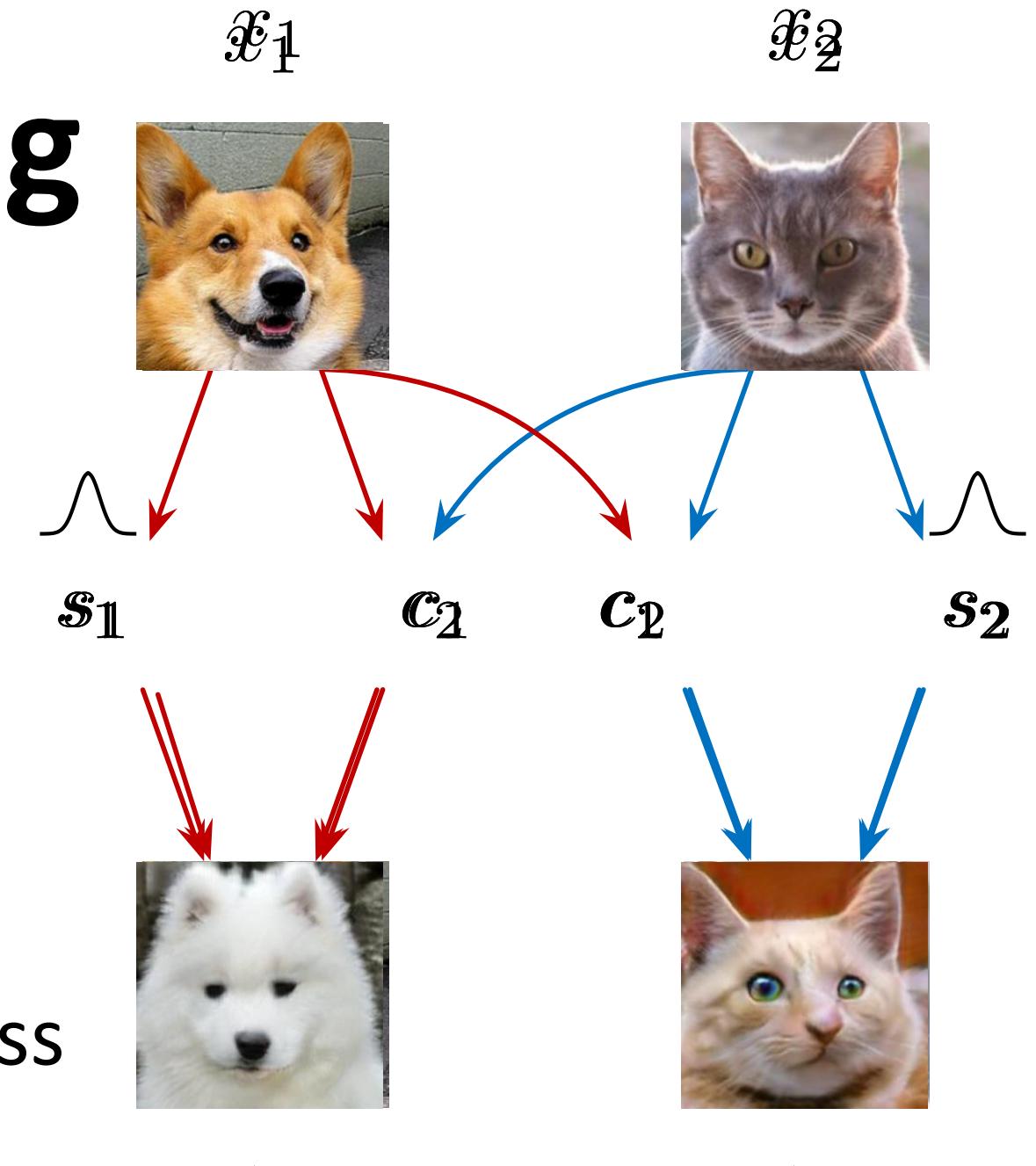
# Towards Multimodality



...

# Training

- Notations:
  - $x$ : images
  - $c$ : content
  - $s$ : style
- Loss:
  - Bidirectional reconstruction loss
    - Image reconstruction loss
    - Latent reconstruction loss
  - GAN loss

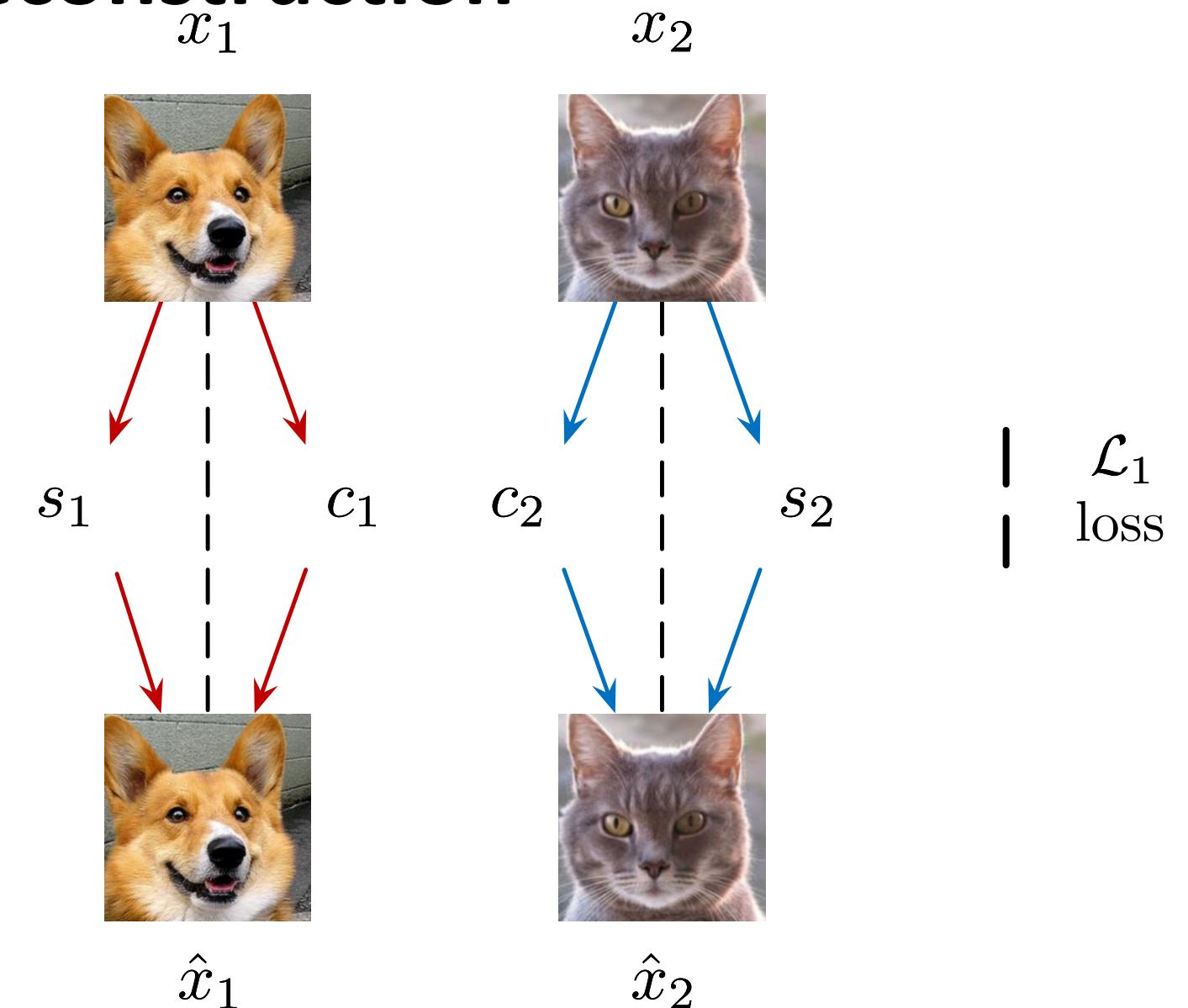


With cross-domain reconstruction

# Bidirectional Reconstruction Loss: Image Reconstruction

Notations:

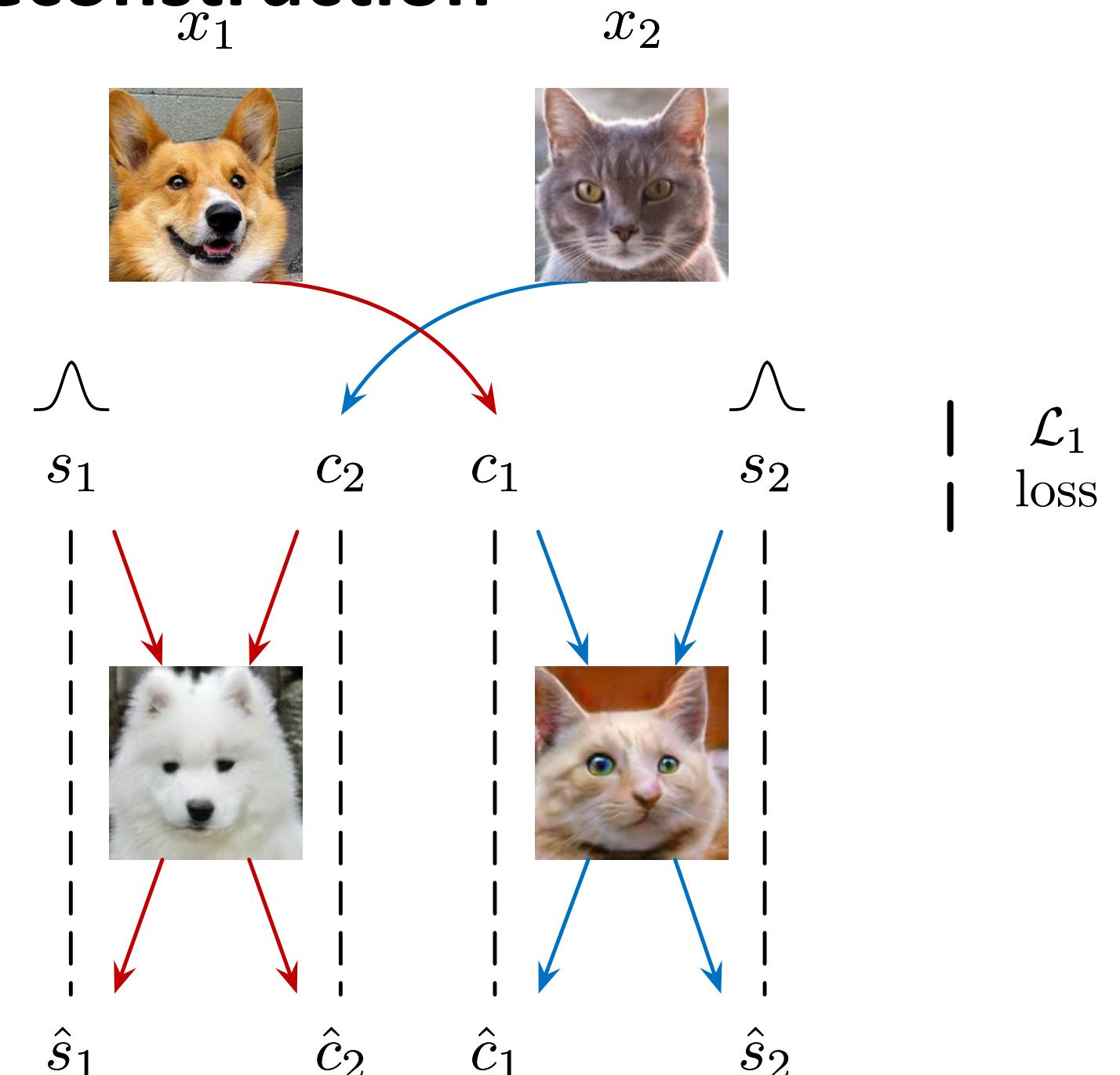
- $x$ : images
- $c$ : content
- $s$ : style



# Bidirectional Reconstruction Loss: Image Reconstruction

Notations:

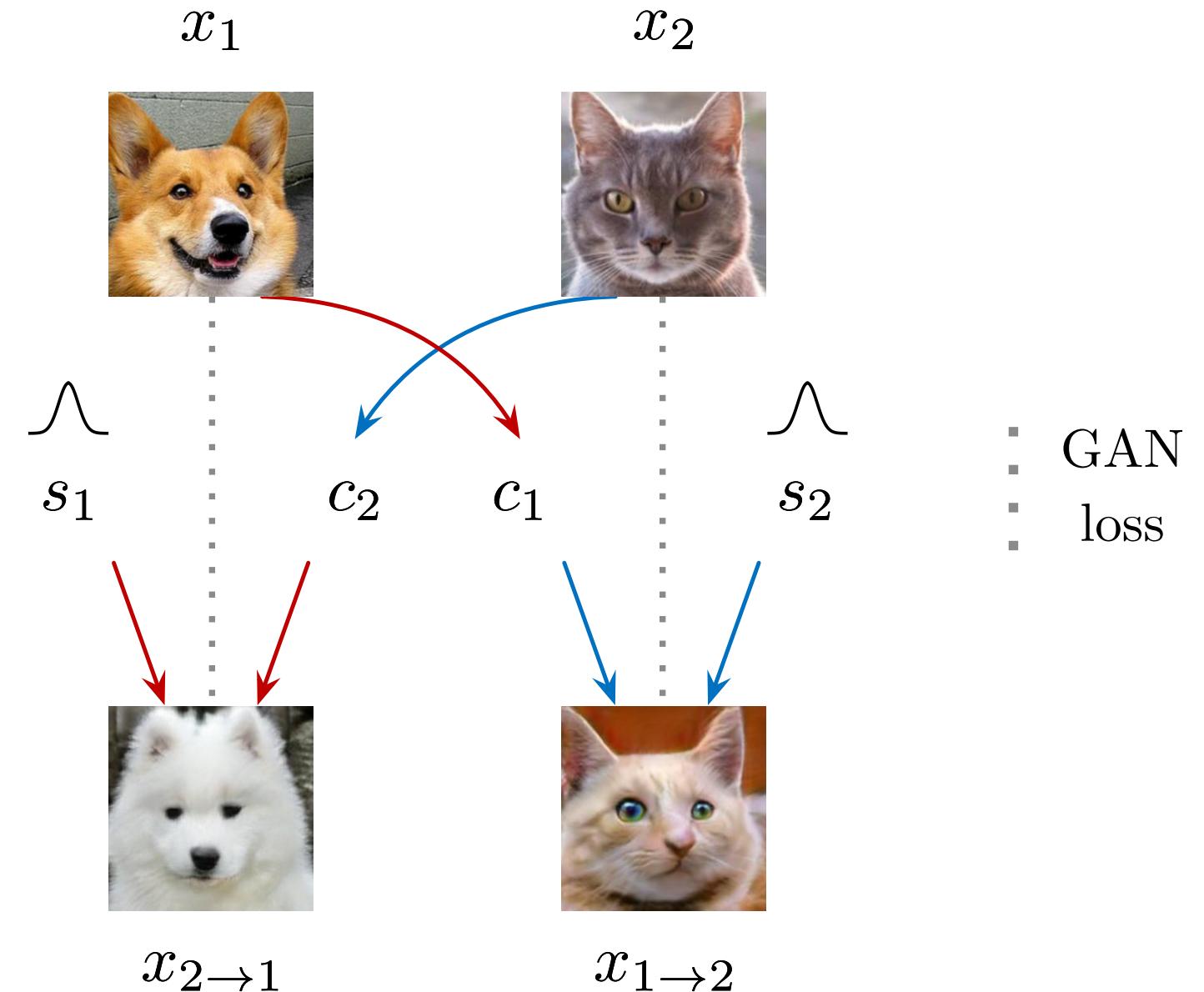
- $x$ : images
- $c$ : content
- $s$ : style



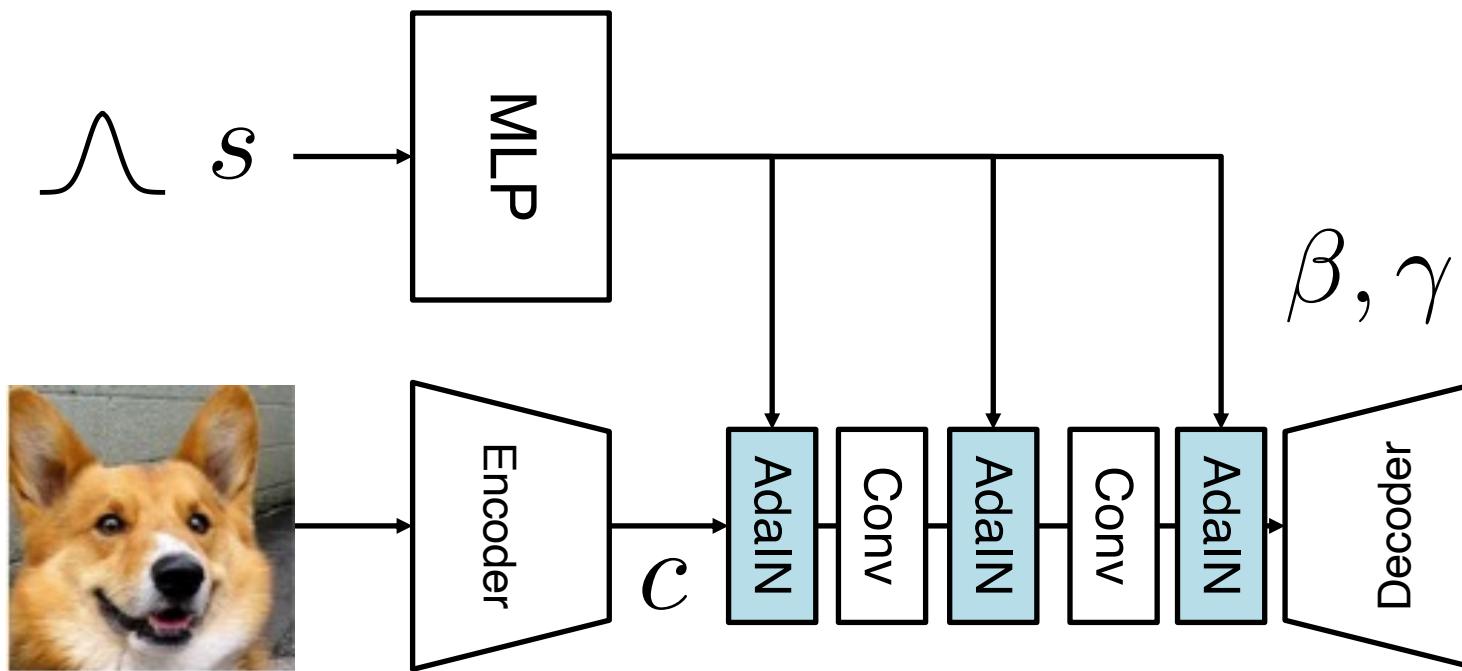
# GAN Loss

Notations:

- $x$ : images
- $c$ : content
- $s$ : style



# AdaIN in a Generative Network

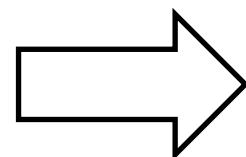


$$\text{AdaIN}(c, s) = \gamma \left( \frac{c - \mu(c)}{\sigma(c)} \right) + \beta$$

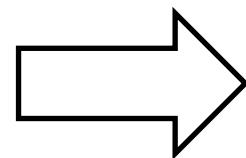
AdaIN in a generative network

# Sketches <-> Photo

Input

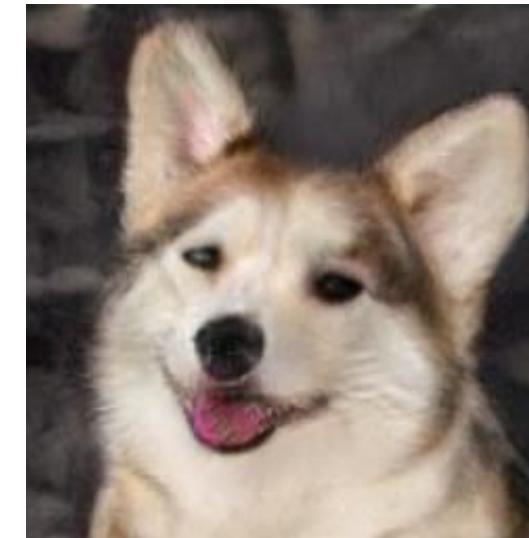
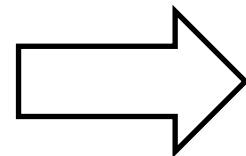


Outputs

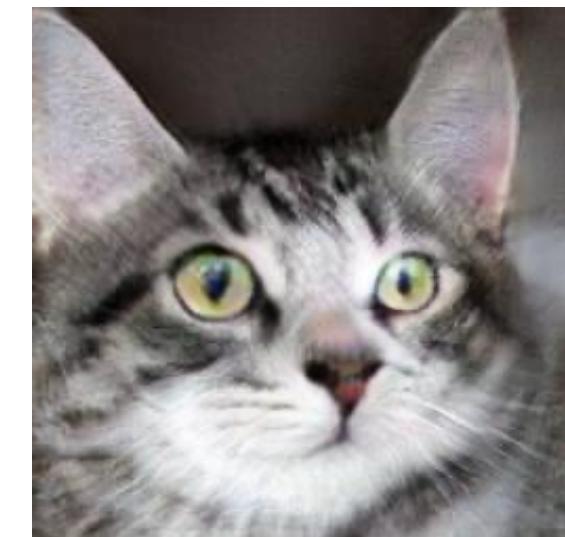
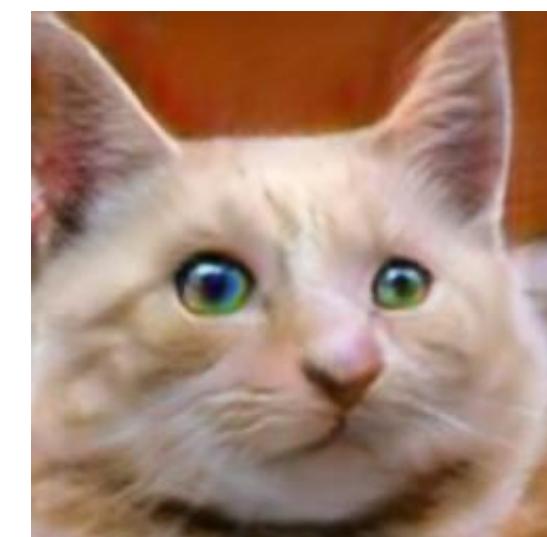
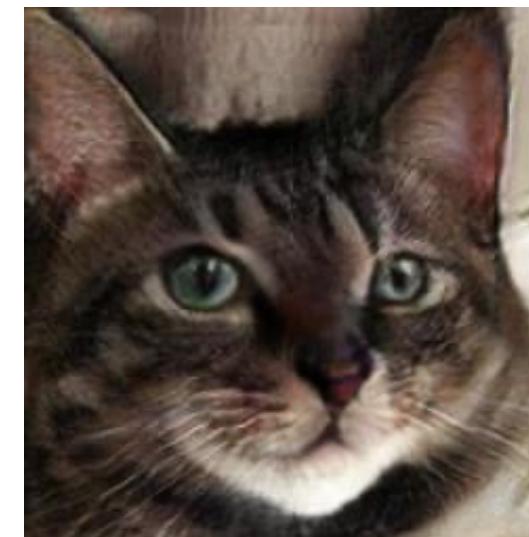
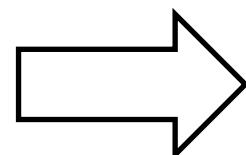
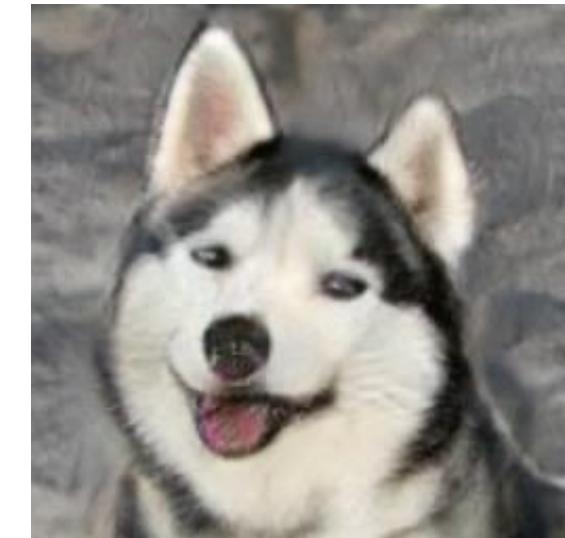


# Cats ↔ Dogs

Input



Outputs



# Synthetic ↔ Real

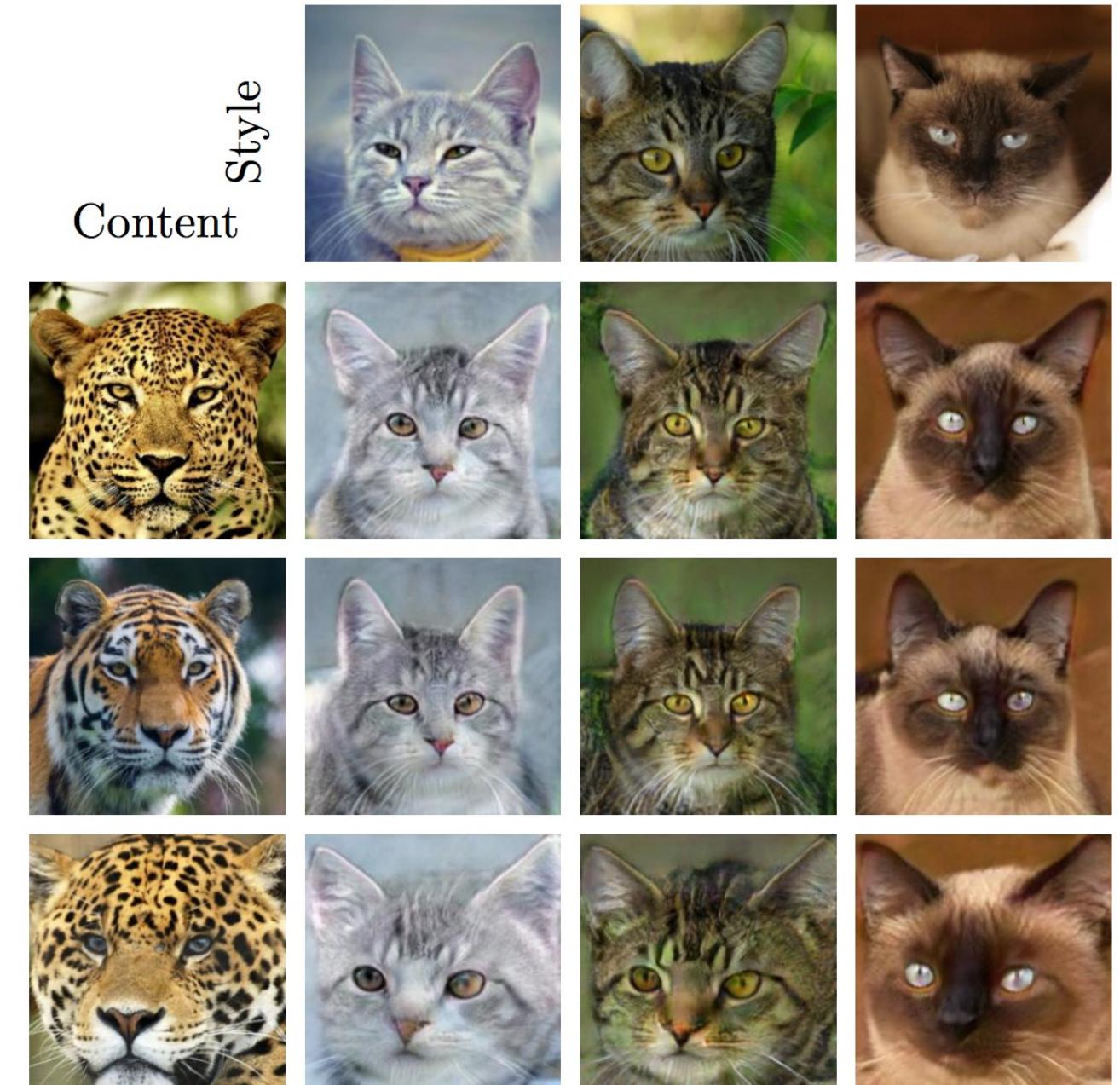
Input



Outputs



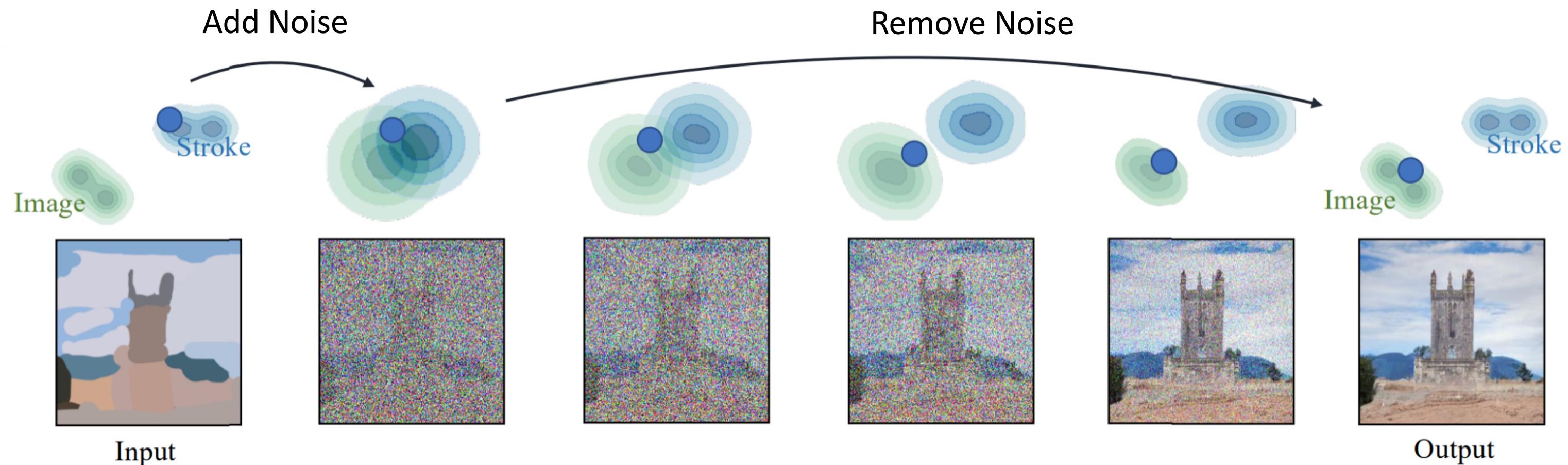
# Example-guided Translation



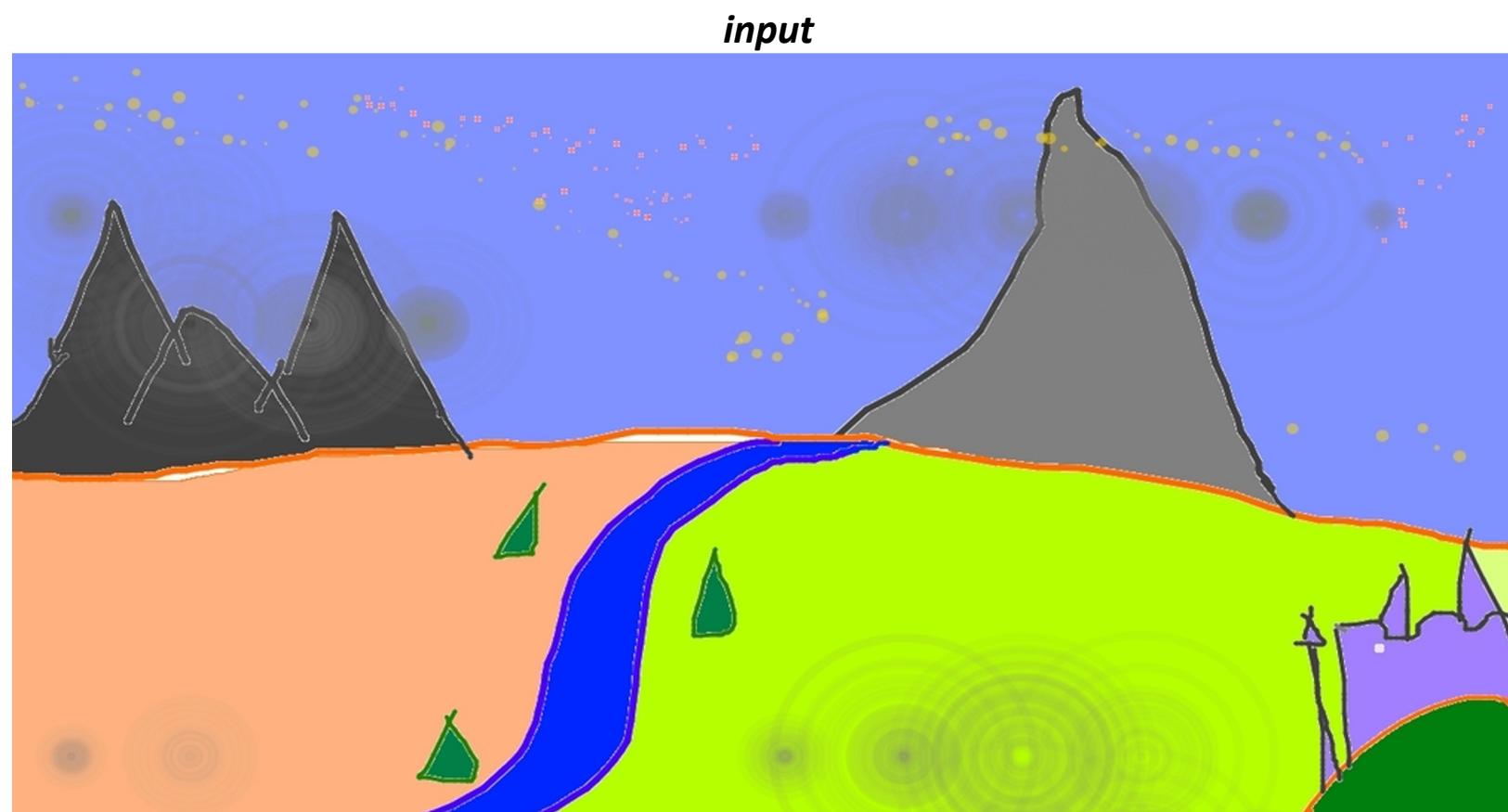
# Image-to-Image Translation with Diffusion Models

# Guided Image Synthesis

SDEdit (<https://arxiv.org/abs/2108.01073>) recipe: diffuse → denoise

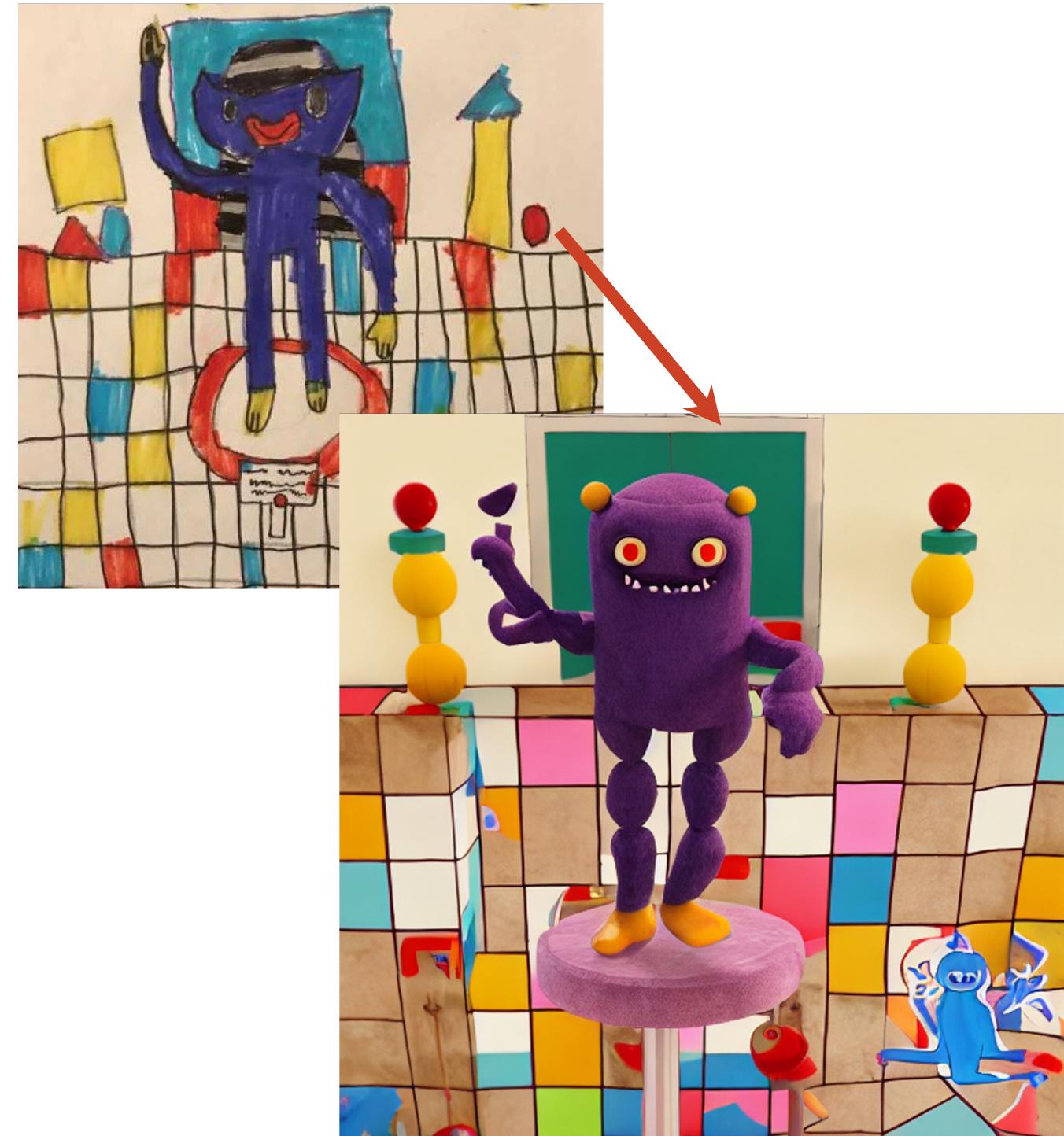


# Guided Image Synthesis

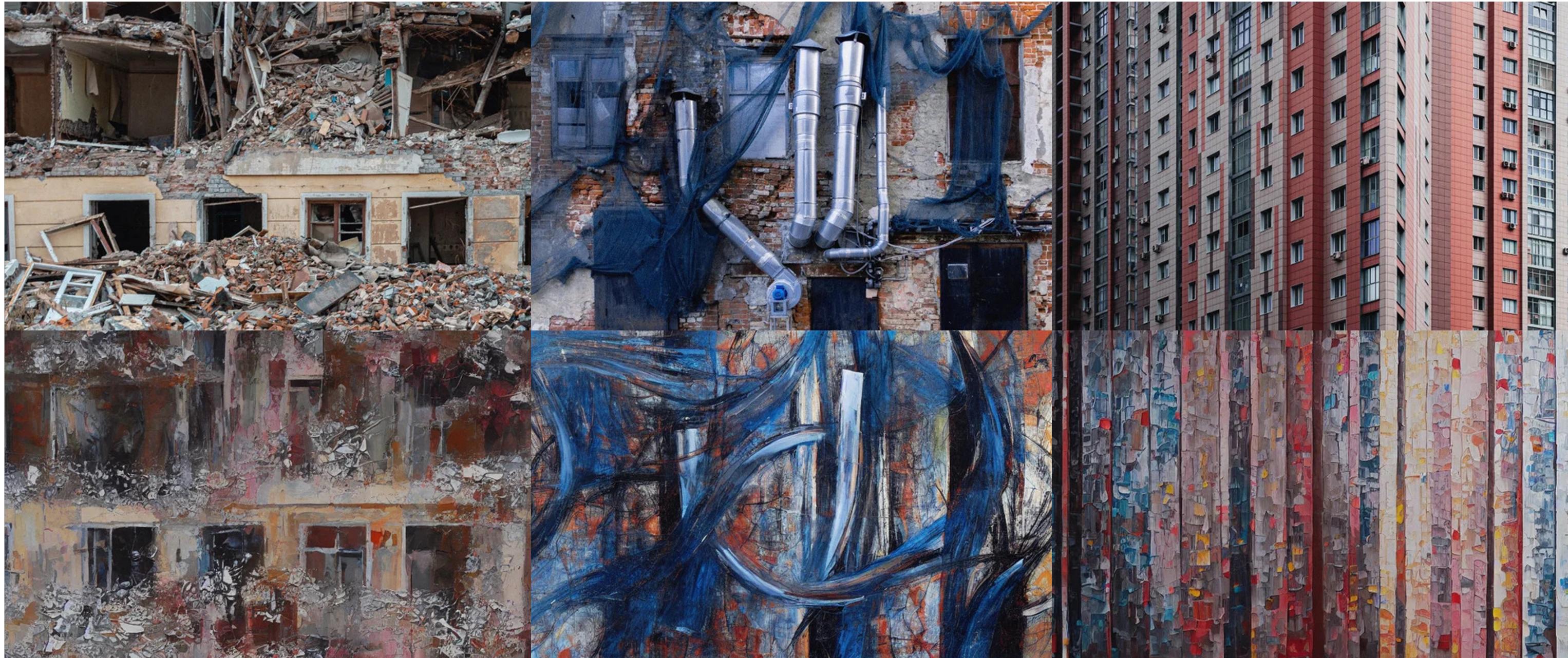




# “Upgrade” your child’s artwork



# abstract art from photos



original post by [u/Pereulkov](#)

[https://www.reddit.com/r/StableDiffusion/comments/xhyad/i\\_made\\_abstract\\_art\\_from\\_my\\_photos/](https://www.reddit.com/r/StableDiffusion/comments/xhyad/i_made_abstract_art_from_my_photos/)

# Thank You!



16-726, Spring 2025

<https://learning-image-synthesis.github.io/>